

## 10+10W STEREO AMPLIFIER FOR CAR RADIO

The TDA2004 is a class B dual audio power amplifier in MULTIWATT® package specifically designed for car radio applications; stereo amplifiers are easily designed using this device that provides a high current capability (up to 3.5A) and that can drive very low impedance loads (down to 1.6Ω).

Its main features are:

**Low distortion.**

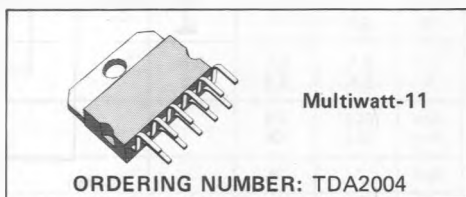
**Low noise.**

**High reliability** of the chip and of the package with additional safety during operation thanks to protections against:

- output AC short circuit to ground;
- very inductive loads

- overrating chip temperature;
- load dump voltage surge;
- fortuitous open ground;

**Space and cost saving:** very low number of external components, very simple mounting system with no electrical isolation between the package and the heatsink.



### ABSOLUTE MAXIMUM RATINGS

$V_s$	Operating supply voltage	18	V
$V_s$	DC supply voltage	28	V
$V_s$	Peak supply voltage (for 50ms)	40	V
$I_o$ (*)	Output peak current (non repetitive $t = 0.1\text{ms}$ )	4.5	A
$I_o$ (*)	Output peak current (repetitive $f \geq 10\text{Hz}$ )	3.5	A
$P_{tot}$	Power dissipation at $T_{case} = 60^\circ\text{C}$	30	W
$T_j, T_{stg}$	Storage and junction temperature	-40 to 150	$^\circ\text{C}$

(\*) The max. output current is internally limited.

### CONNECTION DIAGRAM

(Top view)

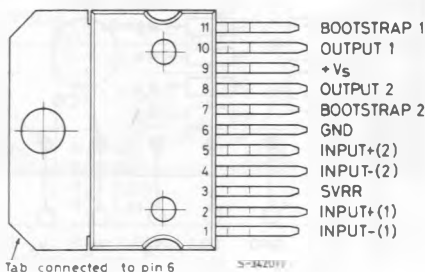


Fig. 1 - Test and application circuit

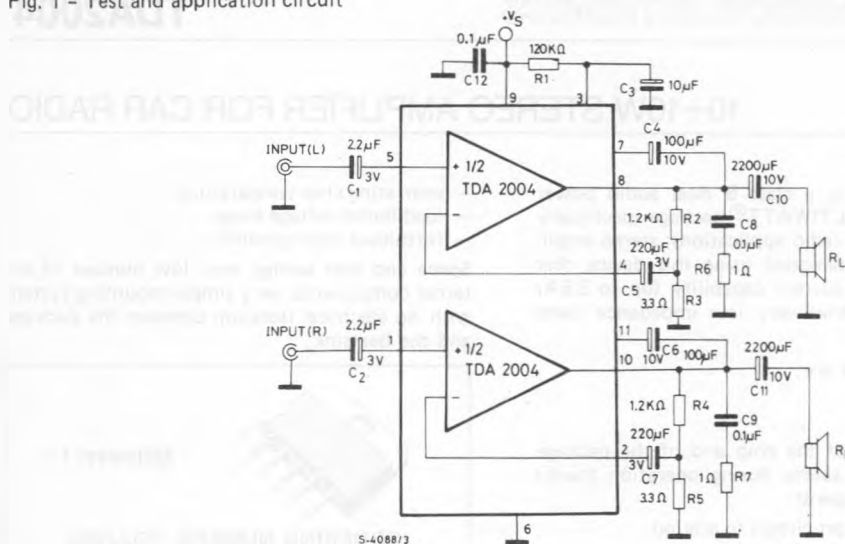
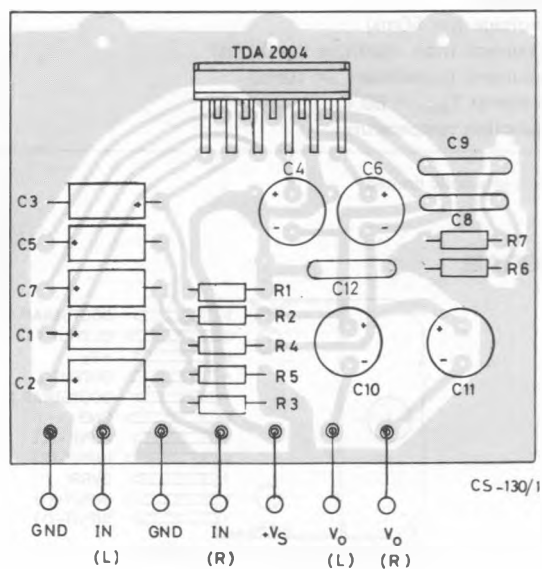


Fig. 2 - PC board and components layout (scale 1:1)



## THERMAL DATA

$R_{th \text{ j-case}}$	Thermal resistance junction-case	max	3	$^{\circ}\text{C/W}$
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**ELECTRICAL CHARACTERISTICS** (Refer to the test circuit,  $T_{amb} = 25^{\circ}\text{C}$ ,  $G_v = 50 \text{ dB}$ ,  $R_{th \text{ (heatsink)}} = 4^{\circ}\text{C/W}$ , unless otherwise specified)

Parameter	Test conditions	Min.	Typ.	Max.	Unit
$V_s$	Supply voltage	8		18	V
$V_o$	Quiescent output voltage	$V_s = 14.4\text{V}$ $V_s = 13.2\text{V}$	6.6 6.0	7.2 6.6	V V
$I_d$	Total quiescent drain current	$V_s = 14.4\text{V}$ $V_s = 13.2\text{V}$	65 62	120 120	mA mA
$I_{SB}$	Stand-by current	Pin 3 grounded	5		mA
$P_o$	Output power (each channel)	$f = 1 \text{ KHz}$ $d = 10\%$ $V_s = 14.4\text{V}$  $R_L = 4\Omega$ $R_L = 3.2\Omega$ $R_L = 2\Omega$ $R_L = 1.6\Omega$  $V_s = 13.2\text{V}$  $R_L = 3.2\Omega$ $R_L = 1.6\Omega$  $V_s = 16\text{V}$  $R_L = 2\Omega$	6 7 9 10  6 9  12	6.5 8 10(*) 11  6.5 10	          W W W W  W W W
$d$	Distortion (each channel)	$f = 1 \text{ KHz}$ $V_s = 14.4\text{V}$ $R_L = 4\Omega$ $P_o = 50 \text{ mW to } 4\text{W}$ $V_s = 14.4\text{V}$ $R_L = 2\Omega$ $P_o = 50 \text{ mW to } 6\text{W}$ $V_s = 13.2\text{V}$ $R_L = 3.2\Omega$ $P_o = 50 \text{ mW to } 3\text{W}$ $V_s = 13.2\text{V}$ $R_L = 1.6\Omega$ $P_o = 50 \text{ mW to } 6\text{W}$	       0.2 0.3 0.2 0.3	       1 1 1 1	       % % % %
CT	Cross talk	$V_s = 14.4\text{V}$ $V_o = 4 \text{ V}_{rms}$ $R_L = 4\Omega$ $f = 1 \text{ KHz}$ $R_g = 5 \text{ K}\Omega$ $f = 10 \text{ KHz}$	50 40	60 45	 dB dB
$V_i$	Input saturation voltage		300		mV
$R_i$	Input resistance (non inverting input)	$f = 1 \text{ KHz}$	70	200	$\text{K}\Omega$
$f_L$	Low frequency roll off (-3 dB)	$R_L = 4\Omega$ $R_L = 2\Omega$ $R_L = 3.2\Omega$ $R_L = 1.6\Omega$		35 50 40 55	Hz Hz Hz Hz
$f_H$	High frequency roll off (-3 dB)	$R_L = 1.6\Omega \text{ to } 4\Omega$	15		KHz
$G_v$	Voltage gain (open loop)	$f = 1 \text{ KHz}$		90	dB

## ELECTRICAL CHARACTERISTICS (continued)

Parameters		Test conditions	Min.	Typ.	Max.	Unit
$G_V$	Voltage gain (closed loop)	$f = 1 \text{ KHz}$	48	50	51	dB
	Closed loop gain matching			0.5		dB
$e_N$	Total input noise voltage	$R_g = 10 \text{ K}\Omega$ (*)		1.5	5	$\mu\text{V}$
SVR	Supply voltage rejection	$f_{\text{ripple}} = 100 \text{ Hz}$ $R_g = 10 \text{ K}\Omega$ $C_3 = 10 \mu\text{F}$ $V_{\text{ripple}} = 0.5 \text{ V}_{\text{rms}}$	35	45		dB
$\eta$	Efficiency	$V_S = 14.4 \text{ V}$ $f = 1 \text{ KHz}$				
		$R_L = 4 \Omega$ $P_O = 6.5 \text{ W}$		70		%
		$R_L = 2 \Omega$ $P_O = 10 \text{ W}$		60		%
		$V_S = 13.2 \text{ V}$ $f = 1 \text{ KHz}$				
		$R_L = 3.2 \Omega$ $P_O = 6.5 \text{ W}$		70		%
		$R_L = 1.6 \Omega$ $P_O = 10 \text{ W}$		60		%
$T_J$	Thermal shut down junction temperature			145		$^{\circ}\text{C}$

(\*) 9.3W without bootstrap.

(°) Bandwidth filter: 22 Hz to 22 KHz.

Fig. 3 - Quiescent output voltage vs. supply voltage

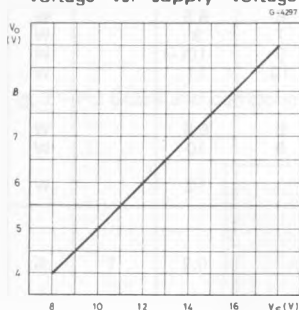


Fig. 4 - Quiescent drain current vs. supply voltage

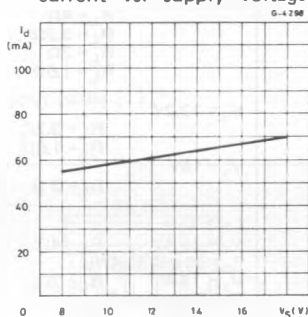


Fig. 5 - Distortion vs. output power

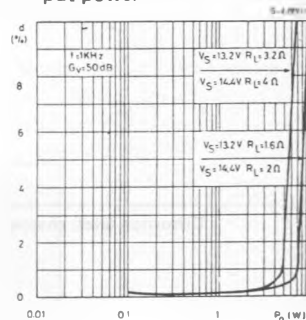


Fig. 6 - Output power vs. supply voltage

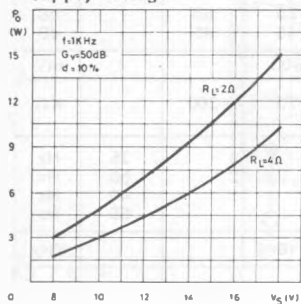


Fig. 7 - Output power vs. supply voltage

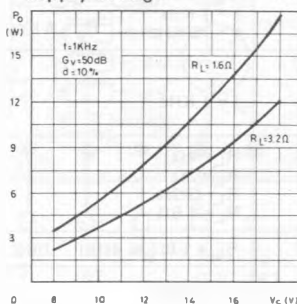


Fig. 8 - Distortion vs. frequency

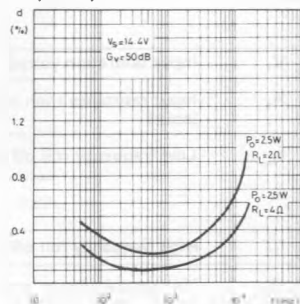


Fig. 9 - Distortion vs. frequency

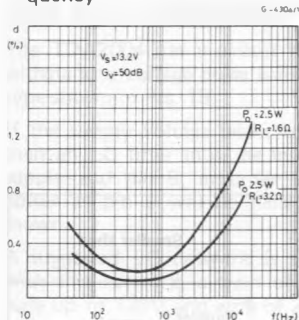
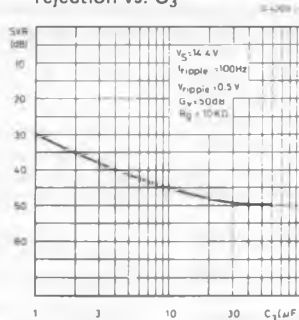
Fig. 10 - Supply voltage rejection vs.  $C_3$ 

Fig. 11 - Supply voltage rejection vs. frequency

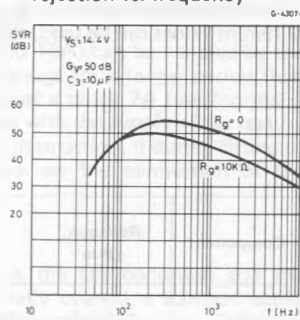
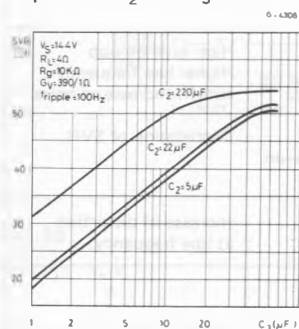
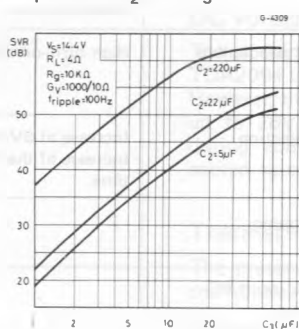
Fig. 12 - Supply voltage rejection vs. values of capacitors  $C_2$  and  $C_3$ Fig. 13 - Supply voltage rejection vs. values of capacitors  $C_2$  and  $C_3$ 

Fig. 14 - Gain vs. input sensitivity

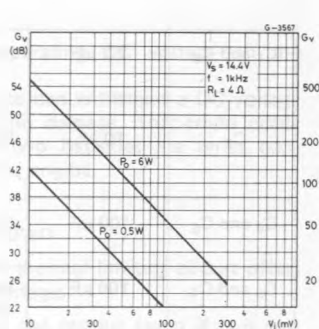


Fig. 15 - Maximum allowable power dissipation vs. ambient temperature

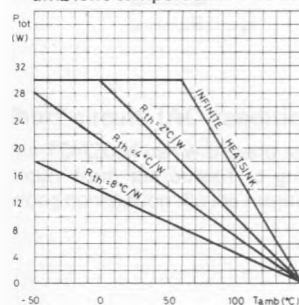


Fig. 16 - Total power dissipation and efficiency vs. output power

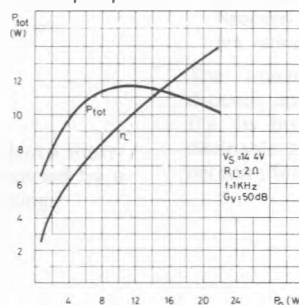
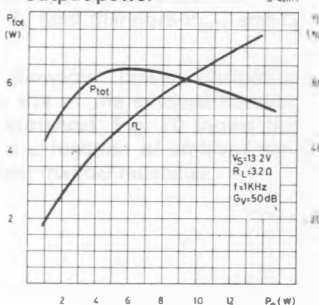


Fig. 17 - Total power dissipation and efficiency vs. output power



## APPLICATION SUGGESTION

The recommended values of the components are those shown on application circuit of fig. 1. Different values can be used; the following table can help the designer.

Component	Recomm. value	Purpose	Larger than	Smaller than
$R_1$	120 K $\Omega$	Optimisation of the output signal symmetry	Smaller $P_{O\ max}$	Smaller $P_{O\ max}$
$R_2$ and $R_4$	1 K $\Omega$	Close loop gain setting (*)	Increase of gain	Decrease of gain
$R_3$ and $R_5$	3.3 $\Omega$		Decrease of gain	Increase of gain
$R_6$ and $R_7$	1 $\Omega$	Frequency stability	Danger of oscillation at high frequency with inductive load	
$C_1$ and $C_2$	2.2 $\mu$ F	Input DC decoupling	High turn-on delay	High turn-on pop Higher low frequency cutoff. Increase of noise.
$C_3$	10 $\mu$ F	Ripple rejection	Increase of SVR. Increase of the switch-on time.	Degradation of SVR.
$C_4$ and $C_6$	100 $\mu$ F	Bootstrapping		Increase of distortion at low frequency.
$C_5$ and $C_7$	100 $\mu$ F	Feedback Input DC decoupling.		
$C_8$ and $C_9$	0.1 $\mu$ F	Frequency stability.		Danger of oscillation.
$C_{10}$ and $C_{11}$	1000 $\mu$ F to 2200 $\mu$ F	Output DC decoupling.		Higher low-frequency cut-off.

(\*) The closed-loop gain must be higher than 26dB

## BUILT-IN PROTECTION SYSTEMS

### Load dump voltage surge

The TDA2004 has a circuit which enables it to withstand a voltage pulse train, on pin 9, of the type shown in Fig. 19.

If the supply voltage peaks to more than 40V, then an LC filter must be inserted between the supply and pin 9, in order to assure that the pulses at pin 9 will be held within the limits shown.

A suggested LC network is shown in Fig. 18. With this network, a train of pulse with amplitude up to 120V and with of 2ms can be applied to point A. This type of protection is ON when the supply voltage (pulse or DC) exceeds 18V. For this reason the maximum operating supply voltage is 18V.

Fig. 18

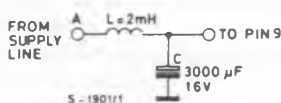
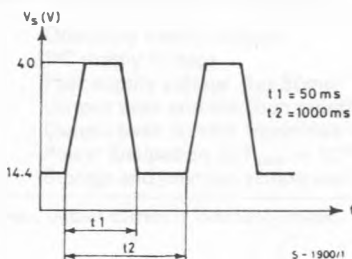


Fig. 19



### Short circuit (AC conditions)

The TDA2004 can withstand an accidental short-circuit from the output to ground caused by a wrong connection during normal working.

### Polarity inversion

High current (up to 10A) can be handled by the device with no damage for a longer period than the blow-out time of a quick 2A fuse (normally connected in series with the supply). This feature is added to avoid destruction, if during fitting to the car, a mistake on the connection of the supply is made.

### Open ground

When the radio is the ON condition and the ground is accidentally opened, a standard audio amplifier will be damaged. On the TDA2004 protection diodes are included to avoid any damage.

### Inductive load

A protection diode is provided to allow use of the TDA2004 with inductive loads.

### DC voltage

The maximum operating DC voltage on the TDA2004 is 18V.

However the device can withstand a DC voltage up to 28V with no damage. This could occur during winter if two batteries are series connected to crank the engine.

### Thermal shut-down

The presence of a thermal limiting circuit offers the following advantages:

- 1) an overload on the output (even if it is permanent), or an excessive ambient temperature can be easily withstood.
- 2) the heatsink can have a smaller factor of safety compared with that of a conventional circuit. There is no device damage in the case of excessive junction temperature: all that happens is the  $P_O$  (and therefore  $P_{Tot}$ ) and  $I_d$  are reduced.

The maximum allowable power dissipation depends upon the size of the external heatsink (i.e. its thermal resistance); Fig. 20 shown this dissipable power as a function of ambient temperature for different thermal resistance.