

TOSHIBA BIPOLAR LINEAR INTEGRATED CIRCUIT SILICON MONOLITHIC

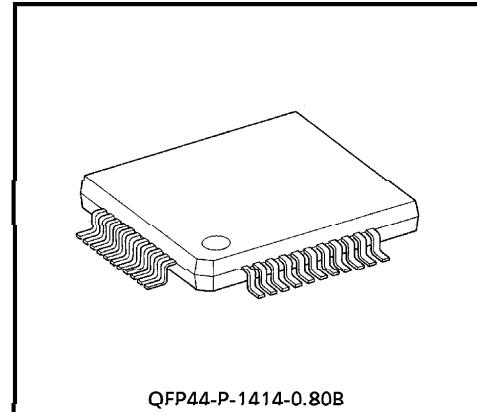
# TA8479F

## 3 PHASE FULL WAVE BRUSHLESS DC MOTOR DRIVER IC FOR VIDEO CAMERA

TA8479F is a capstan / cylinder motor 1-chip driver IC for video camera. Enclosing the capstan and cylinder sections in one package saves space and makes patterning the set board easier.

### FEATURES

- Capstan / Cylinder Motor Driver in 1 Chip
- 3 Phase Full Wave Drive~Voltage Control / Voltage Drive Mode
- Package : QFP44
- Built-in Thermal Shutdown Circuit
  - ⟨ Capstan section ⟩
    - Soft switching drive
    - Bi-direction drive
    - Built-in standby circuit
  - ⟨ Cylinder section ⟩
    - Hard switching drive
    - One direction drive

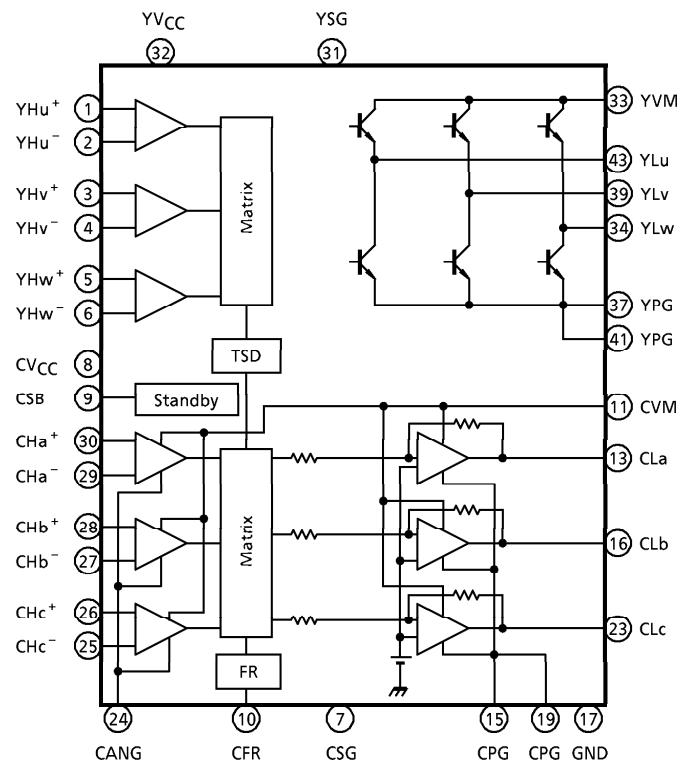


Weight : 1.15g (Typ.)

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## BLOCK DIAGRAM



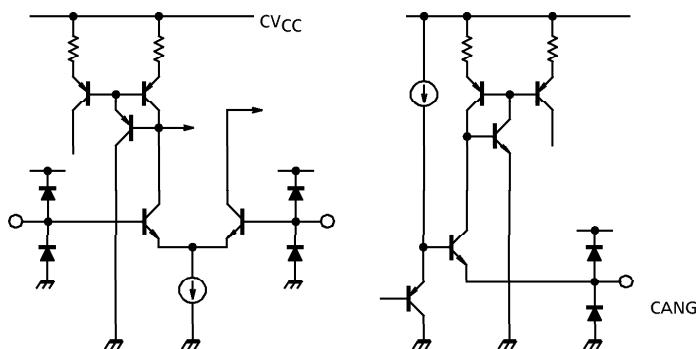
**PIN FUNCTION**

PIN No.	SYMBOL	FUNCTION	PIN No.	SYMBOL	FUNCTION
1	YHu <sup>+</sup>	u-phase Hall amp positive input pin	23	CLc	c-phase drive output pin
2	YHu <sup>-</sup>	u-phase Hall amp negative input pin	24	CANG	Hall amp gain control pin
3	YHv <sup>+</sup>	v-phase Hall amp positive input pin	25	CHc <sup>-</sup>	c-phase Hall amp negative input pin
4	YHv <sup>-</sup>	v-phase Hall amp negative input pin	26	CHc <sup>+</sup>	c-phase Hall amp positive input pin
5	YHw <sup>+</sup>	w-phase Hall amp positive input pin	27	CHb <sup>-</sup>	b-phase Hall amp negative input pin
6	YHw <sup>-</sup>	w-phase Hall amp negative input pin	28	CHb <sup>+</sup>	b-phase Hall amp positive input pin
7	CSG	Small signal section GND	29	CHA <sup>-</sup>	a-phase Hall amp negative input pin
8	CV <sub>CC</sub>	Small signal supply voltage input pin	30	CHA <sup>+</sup>	a-phase Hall amp positive input pin
9	CSB	Standby pin	31	YSG	Small signal section GND
10	CFR	Forward / reverse switching pin	32	YV <sub>CC</sub>	Small signal section supply voltage input pin
11	CV <sub>M</sub>	Output section drive voltage input pin	33	YV <sub>M</sub>	Output section drive voltage input pin
12	NC		34	YLw	w-phase drive output pin
13	CLA	a-phase drive output pin	35	NC	
14	NC		36	NC	
15	CPG	Output section GND	37	YPG	Output section GND
16	CLb	b-phase drive output pin	38	NC	
17	GND	GND pin	39	YLv	v-phase drive output pin
18	NC		40	NC	
19	CPG	Output section GND	41	YPG	Output section GND
20	NC		42	NC	
21	NC		43	YL <sub>u</sub>	u-phase drive output pin
22	NC		44	NC	

## EXPLANATION OF SECTIONS

## &lt;Capstan section&gt;

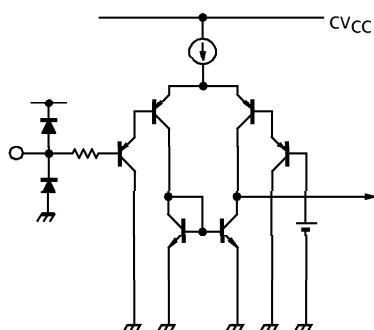
- Hall amp circuit



The Hall amp is a differential amp, and the common-phase input voltage range is  $CV_{CMR} = 1.4\sim 2.8$  [V]. For signals from Hall elements, input sinusoidal waves. Noise, etc. which causes malfunctions when found in signals, must be prevented by a condenser.

Grounding the CANG pin with a resistor makes it possible to change the input/output gains in the Hall amp. Determine the resistance value within  $1k\Omega\sim$ several  $k\Omega$ .

- Standby circuit

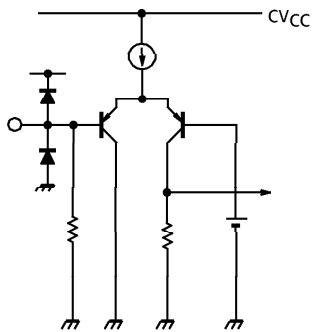


A standby state turns off all circuits in the capstan section except for the standby circuit.

H : Start

L : Standby

- FR circuit



H : Reverse rotation

L : Forward rotation

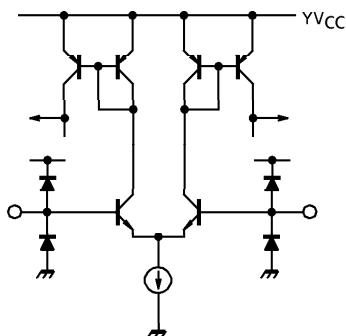
In an open state, the circuit causes the motor to rotate forward.

- Output circuit

This IC uses an amplitude control mode to control output currents by changing output amplitude.

<Cylinder section>

- Hall amp circuit



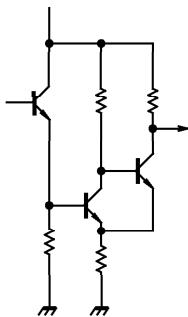
The Hall amp is a differential amp, and the common-phase input voltage range is  $YV_{CMR} = 1.3 \sim YV_{CC} - 1.3$  [V]. For signals from Hall elements, input sinusoidal waves. Noise, etc., which causes malfunction when found in signals, must be prevented by a condenser.

This circuit has a high gain amp at the latter stage, making the input sensitivity as high as about 20mV<sub>p-p</sub> (Typ.).

- Output circuit

This circuit uses a hard switching drive mode and controls output currents by changing the emitter-collector voltage of the Pw Tr.

- Thermal shutdown circuit



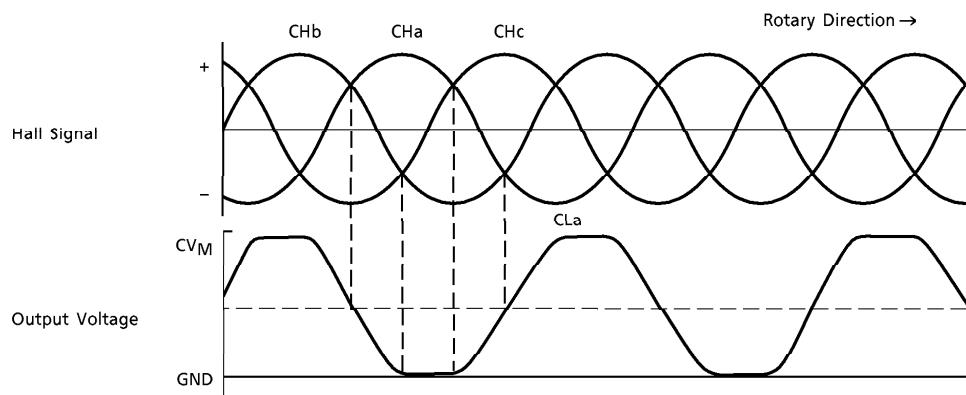
When the temperature exceeds  $T_j = 170^\circ\text{C}$  (Typ.) (design target value), the output circuits in the capstan and cylinder sections are turned off. This circuit has an approximately  $30^\circ\text{C}$  Hysteresis, and the recovery temperature is  $T_j = 140^\circ\text{C}$  (Typ.) (design target value).

## TRUTH TABLE / TIMING CHART

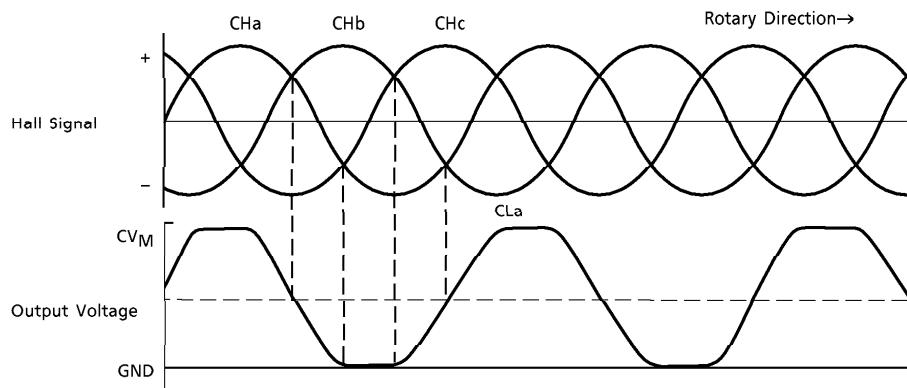
&lt;Capstan section&gt;

CHa	CHb	CHc	CLa	CLb	CLc	
L	H	L	H	L	M	(Forward Rotation) CLa = -(CHa - CHb) CLb = -(CHb - CHc) CLc = -(CHc - CHa)
H	H	L	M	L	H	
H	L	L	L	M	H	
H	L	H	L	H	M	
L	L	H	M	H	L	
L	H	H	H	M	L	CFR = "L"
H	L	L	H	M	L	
H	H	L	M	H	L	(Reverse Rotation) CLa = CHa - CHb CLb = CHb - CHc CLc = CHc - CHa
L	H	L	L	H	M	
L	H	H	L	M	H	
L	L	H	M	L	H	
H	L	H	H	L	M	CFR = "H"

(Forward rotation)



(Reverse rotation)



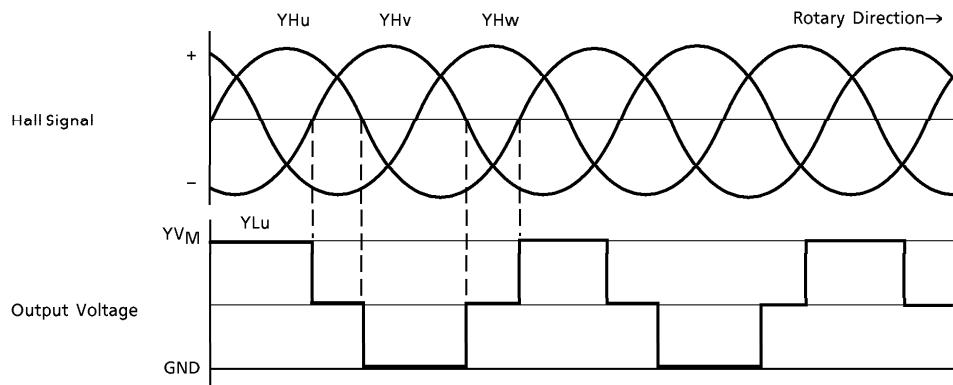
## &lt;Cylinder section&gt;

YHu	YHv	YHw	YLu	YLv	YLw	
H	L	L	H	M	L	
H	H	L	M	H	L	
L	H	L	L	H	M	
L	H	H	L	M	H	
L	L	H	M	L	H	
H	L	H	H	L	M	

$$YL_u = YHu - YHv$$

$$YL_v = YHv - YHw$$

$$YL_w = YHw - YHu$$



**MAXIMUM RATINGS (Ta = 25°C)**

CHARACTERISTIC	SYMBOL	RATING		UNIT
		CAPSTAN SECTION	CYLINDER SECTION	
Small Signal Section Supply Voltage	V <sub>CC</sub>	10	10	V
Output Section Supply Voltage	V <sub>M</sub>	10	10	V
Output Current	I <sub>O</sub>	1.5	1.5	A
Power Dissipation	P <sub>D</sub>	(Note 1) 1		W
Operating Temperature	T <sub>opr</sub>	-20~75		°C
Storage Temperature	T <sub>stg</sub>	-55~150		°C

(Note 1) When mounted on board (100×100×1.6mm Cu 24%)

**OPERATING SUPPLY VOLTAGE RANGE (Ta = 25°C)****CAPSTAN SECTION**

CHARACTERISTIC	SYMBOL	OPERATING RANGE	UNIT
Small Signal Section Supply Voltage	CV <sub>CC</sub>	4.2~6.0	V
Output Section Supply Voltage	CVM	2.8~8.0	V

**CYLINDER SECTION**

CHARACTERISTIC	SYMBOL	OPERATING RANGE	UNIT
Small Signal Section Supply Voltage	YV <sub>CC</sub>	4.2~6.0	V
Output Section Supply Voltage	YVM	1.5~8.0	V

## ELECTRICAL CHARACTERISTICS

CAPSTAN SECTION ( $CV_{CC} = 5.0V$ ,  $CV_M = 3V$ ,  $T_a = 25^\circ C$ )

CHARACTERISTIC	SYMBOL	TEST CIR-CUIT	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
Supply Current	ClCC1	1	Output open, standby	—	60	80	$\mu A$
	ClCC2	1	Output open, start	—	5	8	mA
	ClM1	2	Output open, standby	—	2	5	mA
	ClM2	2	Output open, start	—	7	12	mA
Hall Amp Circuit	Input Current	ClH	$CV_{CMR} = 2.5V$	—	—	5	$\mu A$
	Common-Phase Voltage Range	$CV_{CMR}$	—	1.4	—	2.8	V
	Input Sensitivity	$CV_H$	5 (Note)	20	—	—	$mV_{p-p}$
	Hall Input Output Voltage Gain	$CG_{VHO}$	$R_{ANGLE} = 6.8k\Omega$	20	23	26	dB
Output Circuit	Saturation Voltage (Upper Side + Lower side)	$CV_{sat}(H+L)$	$I_O = 0.1A, CV_M = 3V, CV_H = 50mV_{p-p}$	—	1.3	1.8	V
	Quiescent Voltage	$CV_{OS}$		—	2.3	2.8	
	Quiescent Voltage Difference	$\Delta CV_{OS}$	—	—	—	80	mV
	Input Voltage (H)	$CV_{SH}$	8 (Start)	3.0	—	$CV_{CC}$	V
Standby Circuit	Input Voltage (L)	$CV_{SL}$	8 (Stop)	0	—	1.2	V
	Input Current	ClINS	11 $CV_S = 0V$	—	—	5	$\mu A$
	Input Voltage (H)	$CV_{FH}$	12 (Reverse rotation)	3.0	—	$CV_{CC}$	V
FR Circuit	Input Voltage (L)	$CV_{FL}$	12 (Forward rotation)	0	—	1.2	V
	Input Current	ClINF	12 $CV_F = 5.0V$	—	—	70	$\mu A$
Thermal Shutdown Circuit Operating Temperature		$T_{SD}$	— (Junction temperature)	—	170	—	$^\circ C$

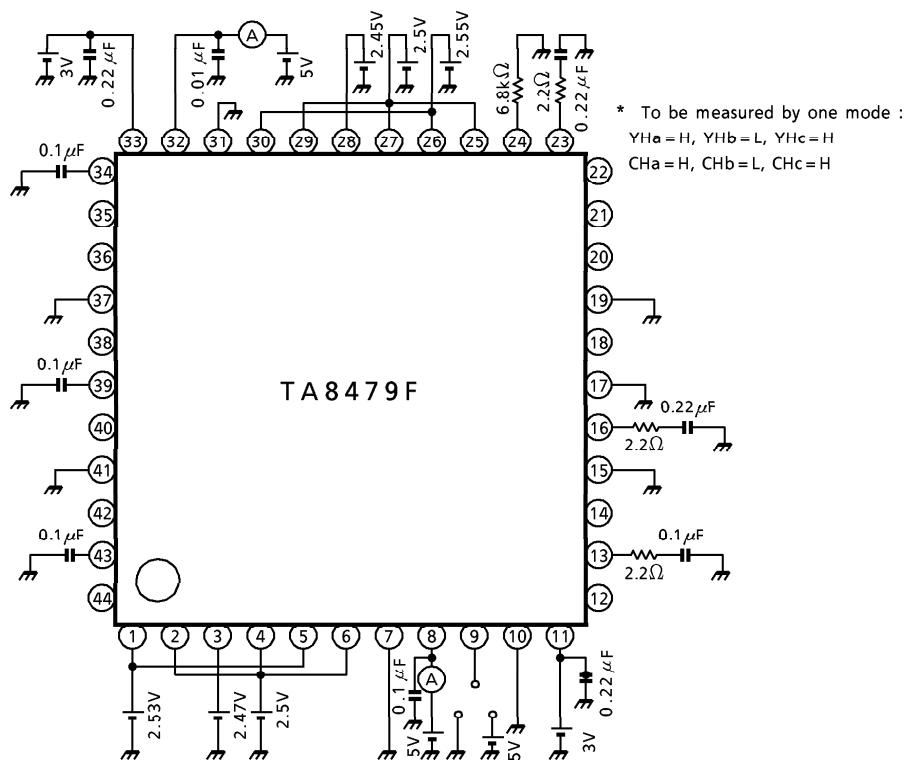
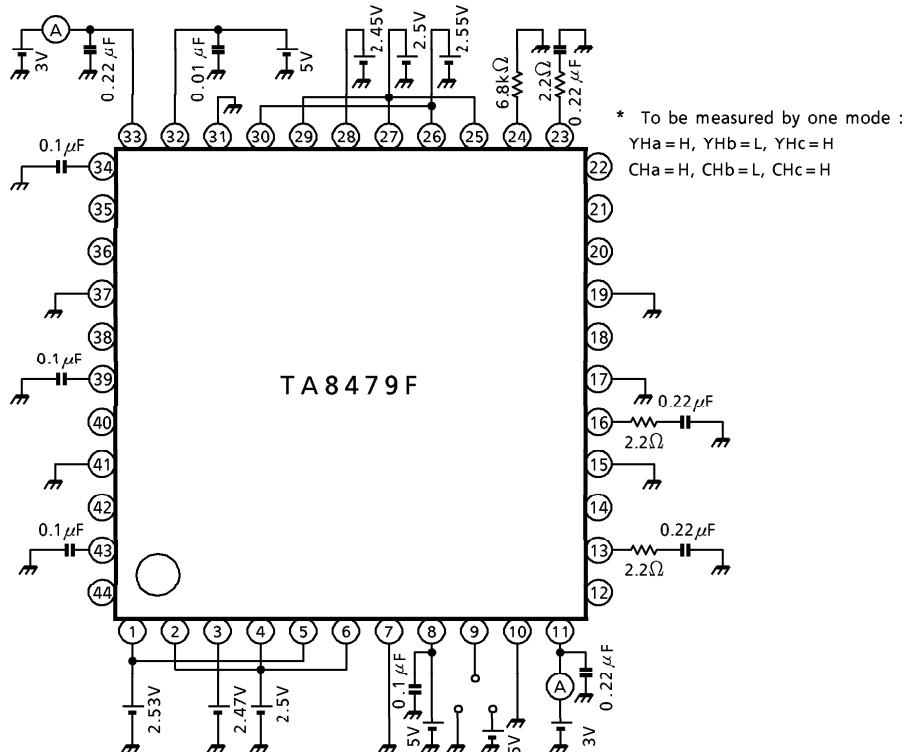
(Note) Defined by output functioning

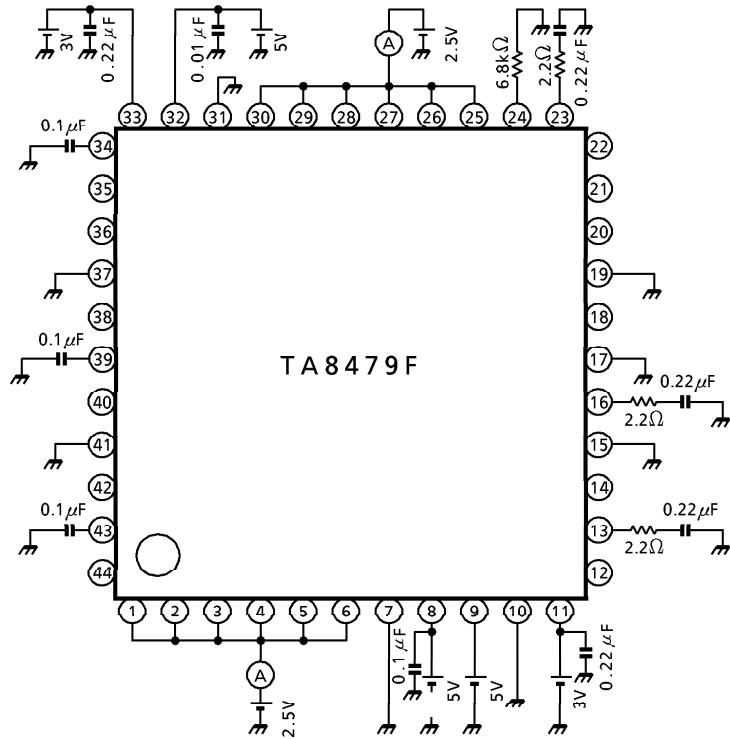
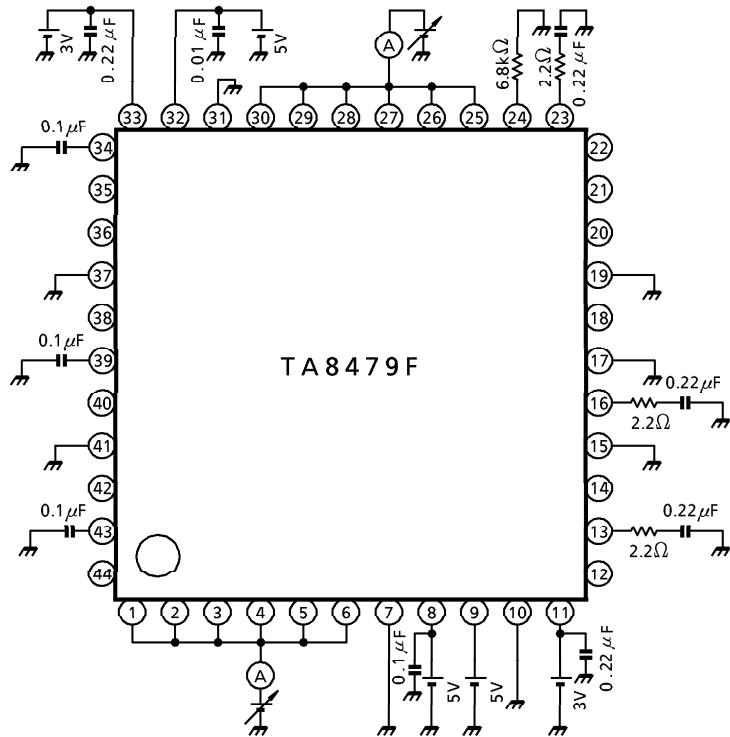
CYLINDER SECTION ( $YV_{CC} = 5.0V$ ,  $YV_M = 3V$ ,  $T_a = 25^\circ C$ )

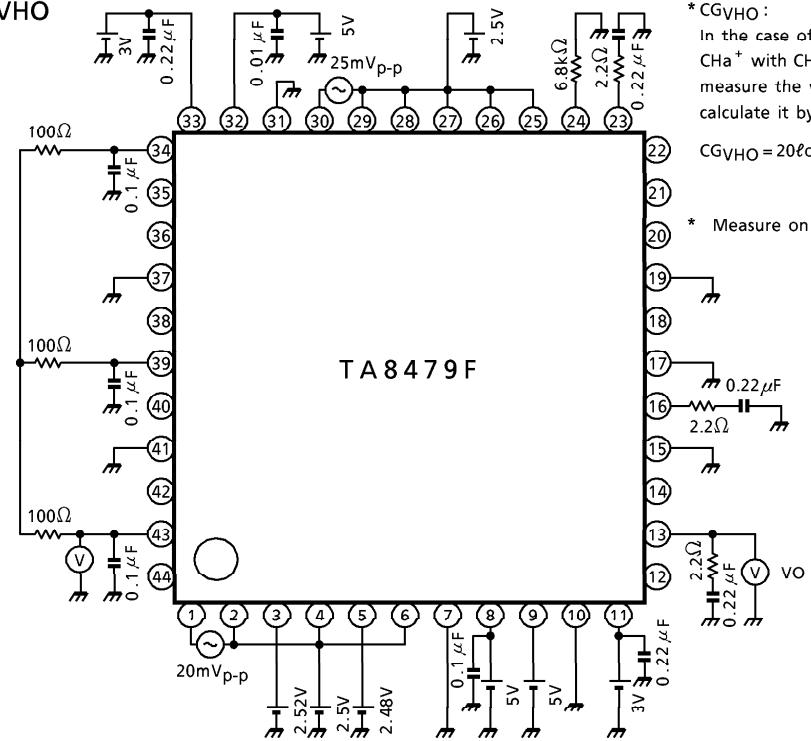
CHARACTERISTIC	SYMBOL	TEST CIR-CUIT	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
Supply Current	$YI_{CC}$	1	Output open	—	5	8	mA
	$YI_M$	2	Output open	—	25	40	mA
Hall Amp Circuit	Input Current	$YI_H$	$YV_{CMR} = 2.5V$	—	—	5	$\mu A$
	Common-Phase Input Voltage Range	$YV_{CMR}$	4	1.3	—	$YV_{CC} - 1.3$	V
	Input Sensitivity	$YV_H$	5 (Note)	20	—	—	$mV_{p-p}$
Output Circuit	Saturation Voltage (Upper Side + Lower side)	$YV_{sat}(H+L)$	6 $I_O = 1.0A$ , $YV_H = 30mV_{p-p}$	—	2.2	2.7	V
	Leakage Current (Upper Side)	$YV_{OL}(H)$	9 $YV_M = 10V$	—	—	10	$\mu A$
	Leakage Current (Lower Side)	$YV_{OL}(L)$	10 $YV_M = 10V$	—	—	10	$\mu A$
Thermal Shutdown Operating Temperature	$T_{SD}$	—		—	170	—	$^\circ C$

(Note) Defined by output functioning

## TEST CIRCUIT

1. YI<sub>CC</sub>, CI<sub>CC1</sub>, CI<sub>CC2</sub>2. YM<sub>M</sub>, CI<sub>M1</sub>, CI<sub>M2</sub>

3. YI<sub>H</sub>, CI<sub>H</sub>4. YV<sub>CMR</sub>, CV<sub>CMR</sub>

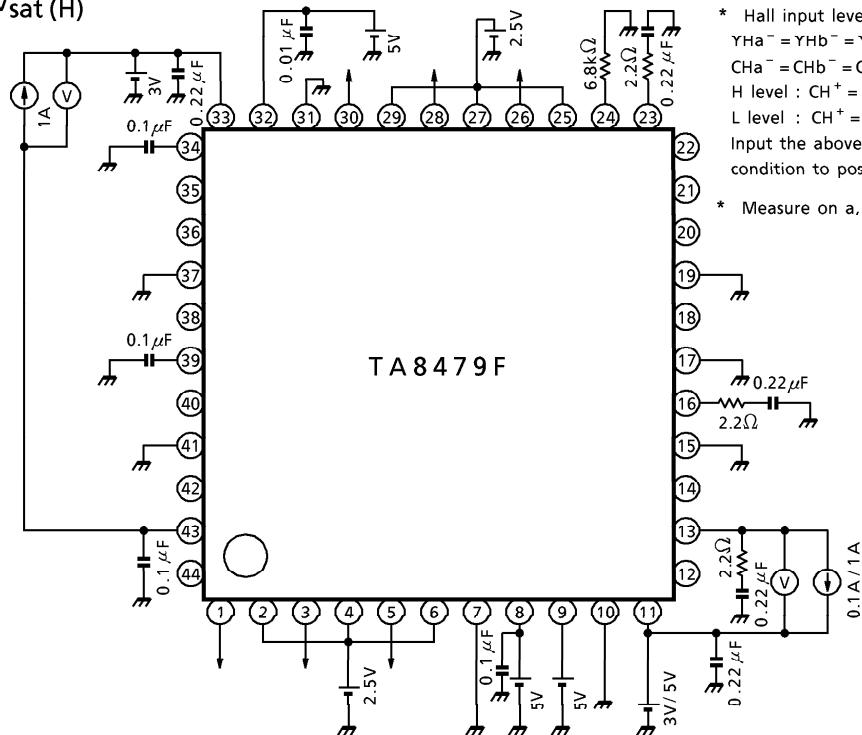
5. YV<sub>H</sub>, CV<sub>H</sub>, CGVHO

\* CGVHO :

In the case of a-phase CGVHO, change  
 $CH_a^+ = CH_b^- = CH_c^- = 2.5V$ ,  
measure the voltage of  $CL_a$  in that case, and  
calculate it by the following formula :

$$CGVHO = 20 \log \frac{V_O(2.525) - V_O(2.475)}{2.525 - 2.475} (\text{dB})$$

\* Measure on a, b, and c phases.

6. YV<sub>sat</sub>(H), CV<sub>sat</sub>(H)

\* Hall input level

$$YH_a^- = YH_b^- = YH_c^- = 2.5V$$

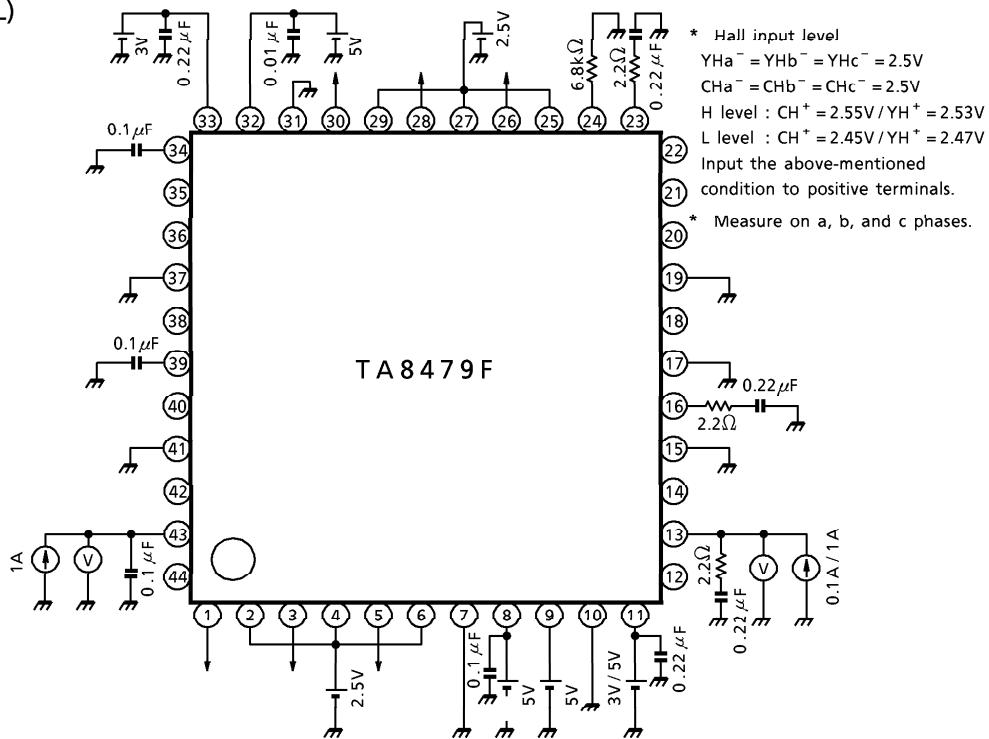
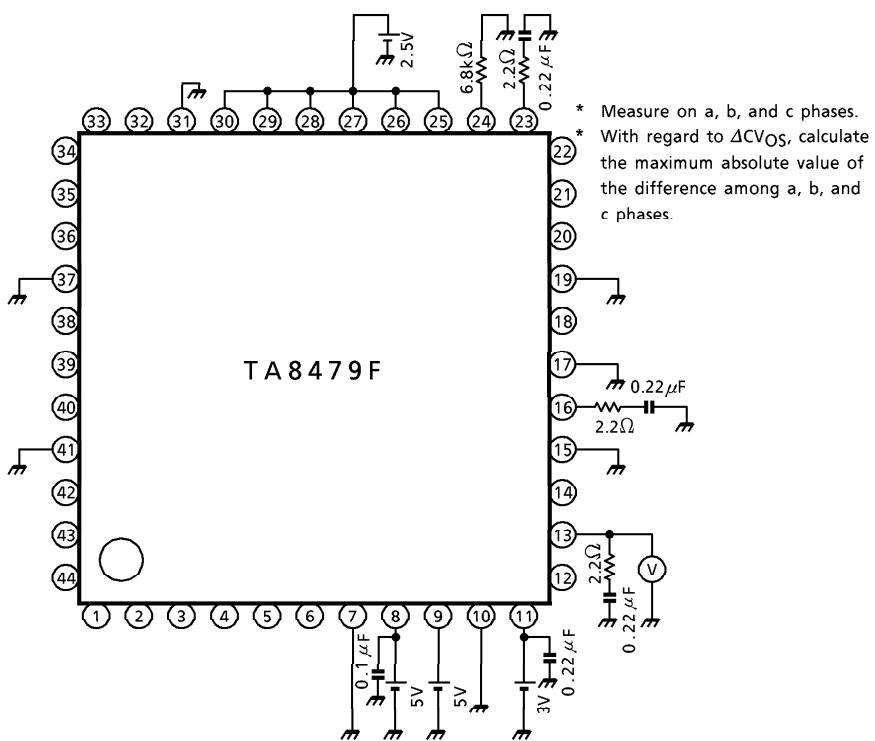
$$CH_a^+ = CH_b^- = CH_c^- = 2.5V$$

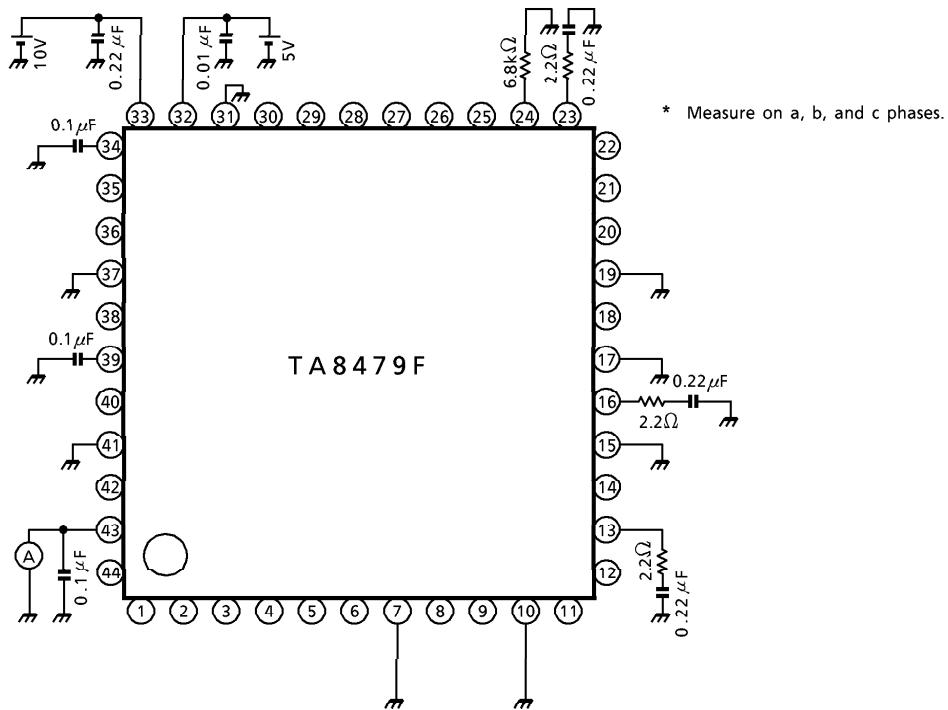
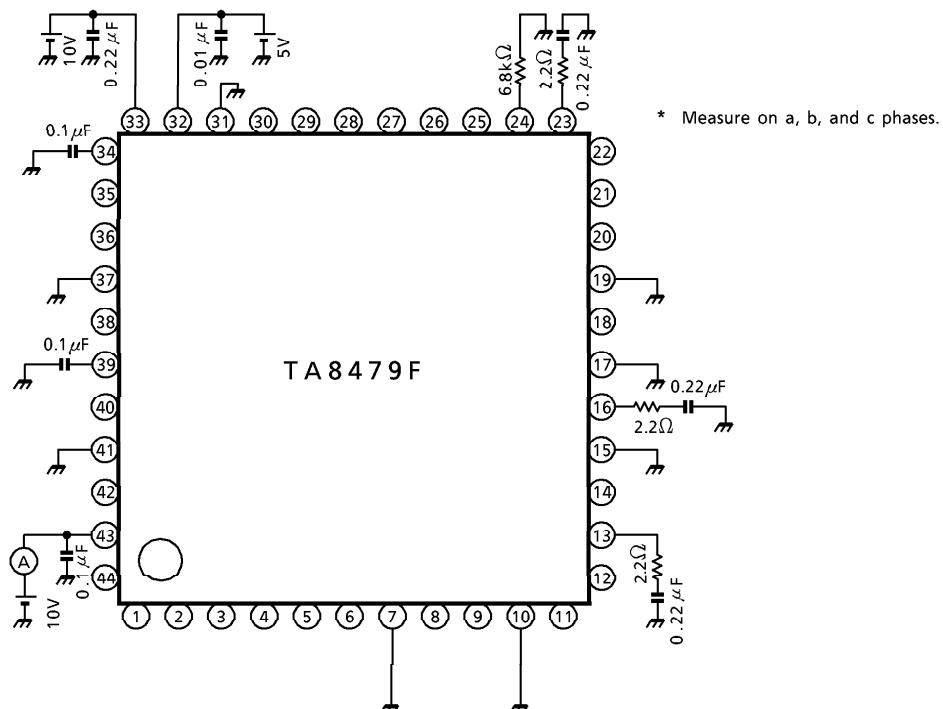
$$H \text{ level : } CH^+ = 2.55V / YH^+ = 2.53V$$

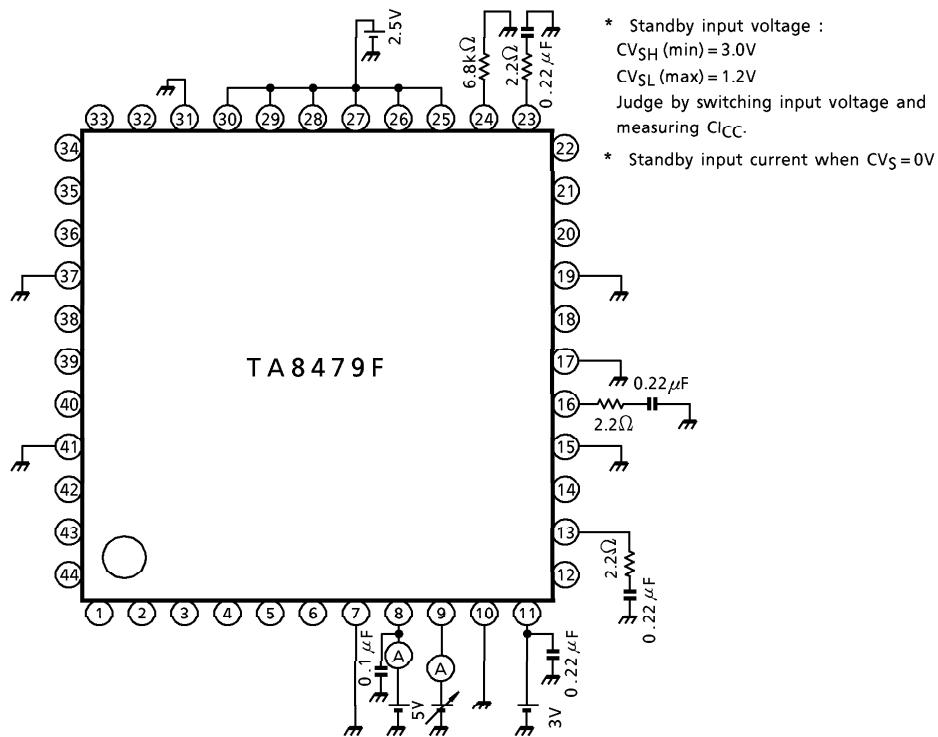
$$L \text{ level : } CH^+ = 2.45V / YH^+ = 2.47V$$

Input the above-mentioned  
condition to positive terminals.

\* Measure on a, b, and c phases.

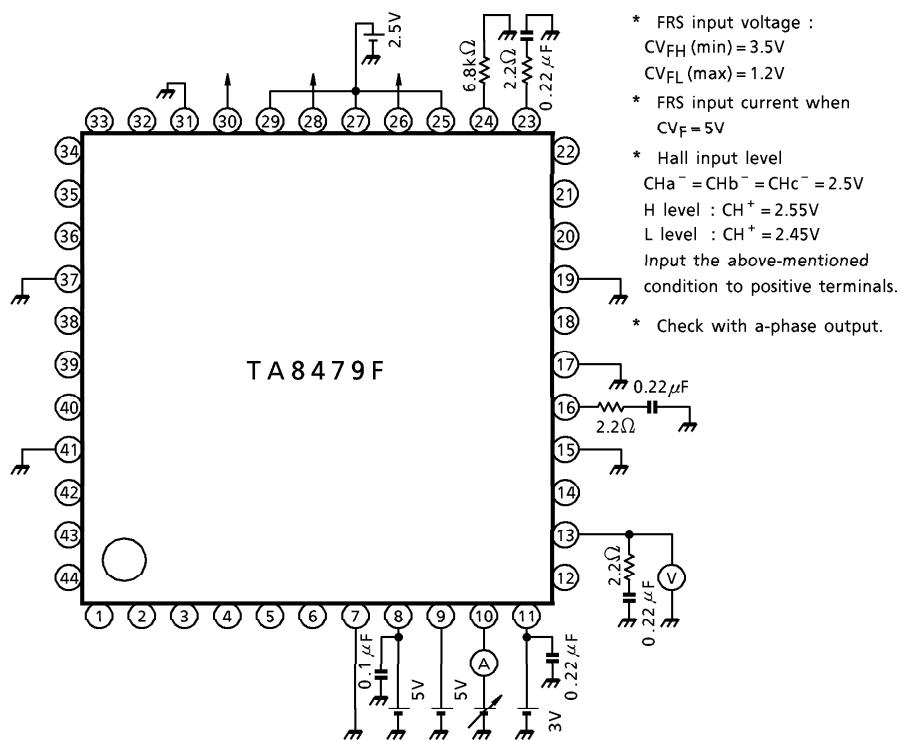
7.  $YV_{sat}(L)$ ,  $CV_{sat}(L)$ 8.  $CV_{OS}$ ,  $\Delta CV_{OS}$ 

9.  $\text{YI}_{\text{OL}}(\text{H})$ 10.  $\text{YI}_{\text{OL}}(\text{L})$ 

11.  $CV_{SH}$ ,  $CV_{SL}$ ,  $Cl_{INS}$ 

\* Standby input voltage :  
 $CV_{SH}$  (min) = 3.0V  
 $CV_{SL}$  (max) = 1.2V  
 Judge by switching input voltage and measuring  $Cl_{CC}$ .

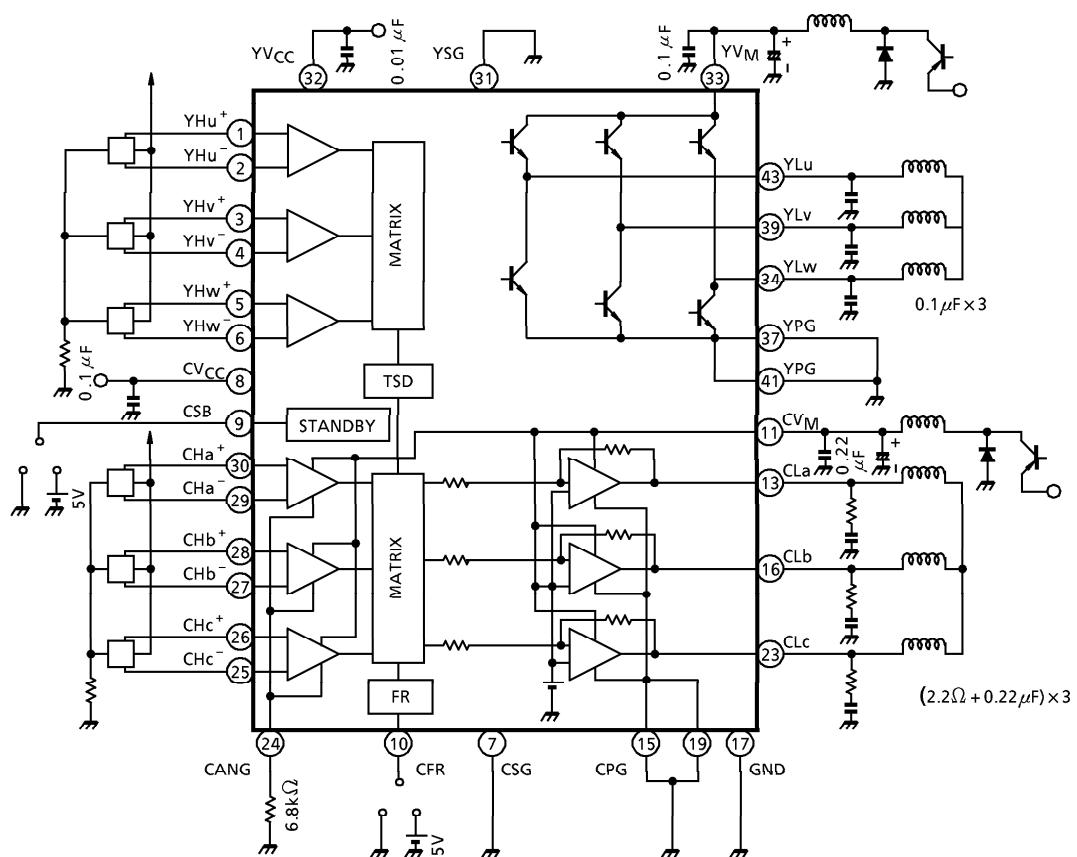
\* Standby input current when  $CV_S = 0V$

12.  $CV_{FH}$ ,  $CV_{FL}$ ,  $Cl_{INF}$ 

\* FRS input voltage :  
 $CV_{FH}$  (min) = 3.5V  
 $CV_{FL}$  (max) = 1.2V  
 \* FRS input current when  $CV_F = 5V$   
 \* Hall input level  
 $CH_a^- = CH_b^- = CH_c^- = 2.5V$   
 H level :  $CH^+ = 2.55V$   
 L level :  $CH^+ = 2.45V$   
 Input the above-mentioned condition to positive terminals.

\* Check with a-phase output.

## APPLICATION CIRCUIT

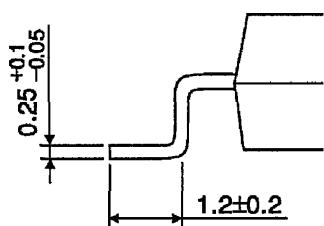
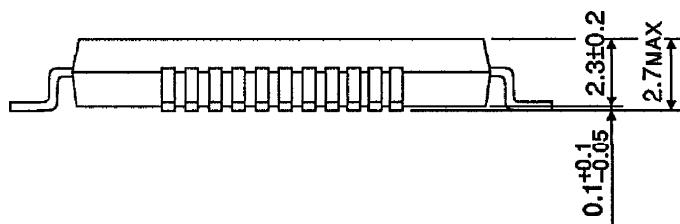
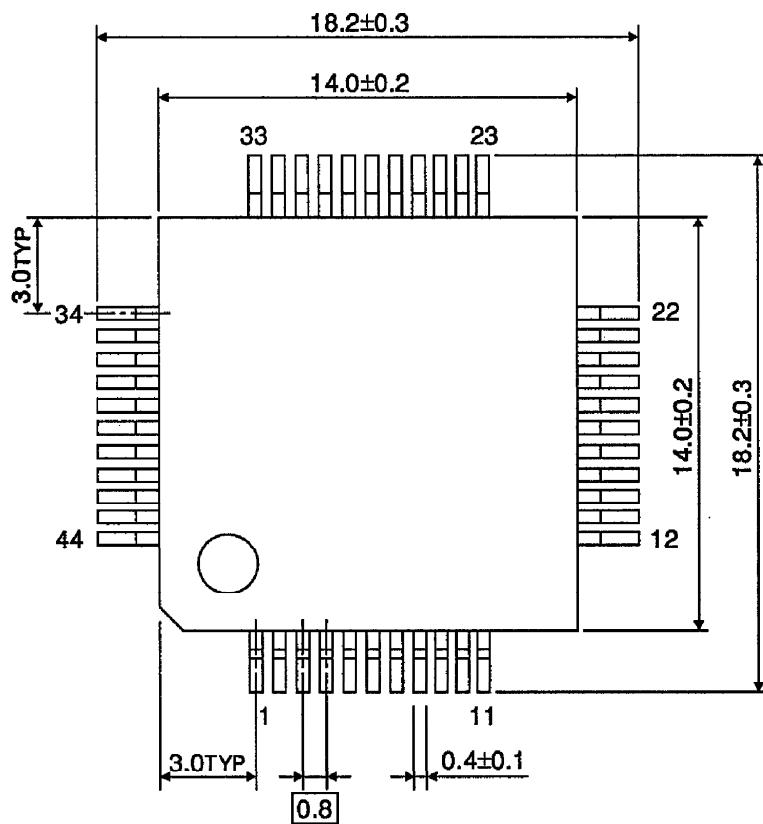


(Note) Utmost care is necessary in the design of the output line,  $YV_M$ ,  $CV_M$  and GND line since IC may be destroyed due to short-circuit between outputs, air contamination fault, or fault by improper grounding.

## OUTLINE DRAWING

QFP44-P-1414-0.80B

Unit : mm



Weight : 1.15g (Typ.)