

TOSHIBA BIPOLAR LINEAR INTEGRATED CIRCUIT SILICON MONOLITHIC

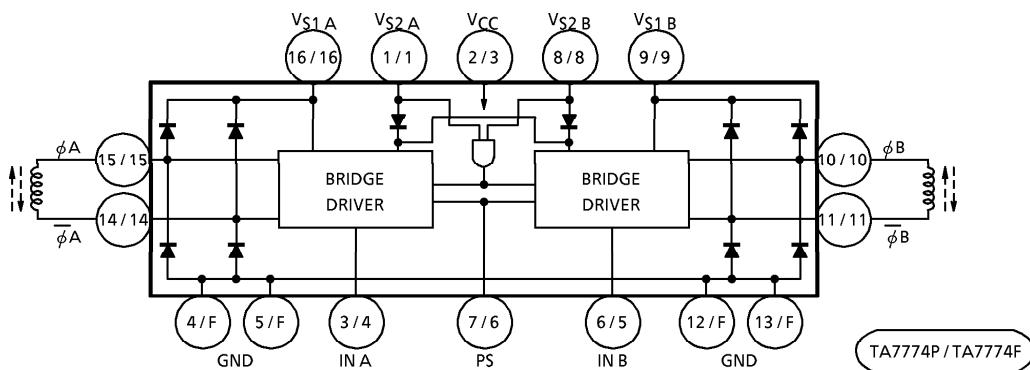
**TA7774P, TA7774F****STEPPING MOTOR DRIVER IC**

The TA7774P, TA7774F is 2 phase Bipolar stepping motor driver IC designed especially for 3.5 or 5.25 inches FDD head actuator drives.

It consists of TTL compatible input circuit, dual bridge driver outputs with flyback diodes, changing circuit of motor coil drive voltage (Power saving circuit) and stand-by circuit.

**FEATURES**

- One Chip 2 Phase Bipolar Stepping Motor Driver.
- Power Saving and Stand-by Operation are available.  
I stand-by ( $I_{CC3}$ )  $\leq 115\mu A$
- Build-in Punch Through Current Restriction Circuit for System Reliability and Noise Suppression.
- TTL Compatible Inputs
- Surface Mount is available with F Type.
- Output Current up to 0.4A (peak)

**BLOCK DIAGRAM**

(Note) Pin ②, ⑦, ⑪, ⑬ of TA7774F are all NC and Heat Fin is connected to GND.

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## PIN FUNCTION

PIN No.	SYMBOL	FUNCTIONAL DESCRIPTION
1/(1)	V <sub>S2 A</sub>	Low-voltage power supply terminal, or stand-by signal input terminal
2/(3)	V <sub>CC</sub>	Power voltage supply terminal for control
3/(4)	IN A	A-ch forward rotation / reverse rotation signal input terminal
4/(F)	GND	GND terminal
5/(F)	GND	GND terminal
6/(5)	IN B	B-ch forward rotation / reverse rotation signal input terminal
7/(6)	PS	Powersave signal input terminal
8/(8)	V <sub>S2 B</sub>	Low-voltage powersupply terminal, or stand-by signal input terminal
9/(9)	V <sub>S1 B</sub>	High-voltage power supply terminal
10/(10)	φB	Output B
11/(11)	φ̄B	Output B̄
12/(F)	GND	GND terminal
13/(F)	GND	GND terminal
14/(14)	φ̄A	Output Ā
15/(15)	φA	Output A
16/(16)	V <sub>S1 A</sub>	High-voltage power supply terminal.

( ) : TA7774F

## TRUTH TABLE 1

INPUT		OUTPUT		
PS	IN	φ	φ̄	
L	L	L	H	Enable V <sub>S1</sub>
L	H	H	L	Enable V <sub>S1</sub>
H	L	L	H	Enable V <sub>S2</sub> (Power save)
H	H	H	L	Enable V <sub>S2</sub> (Power save)

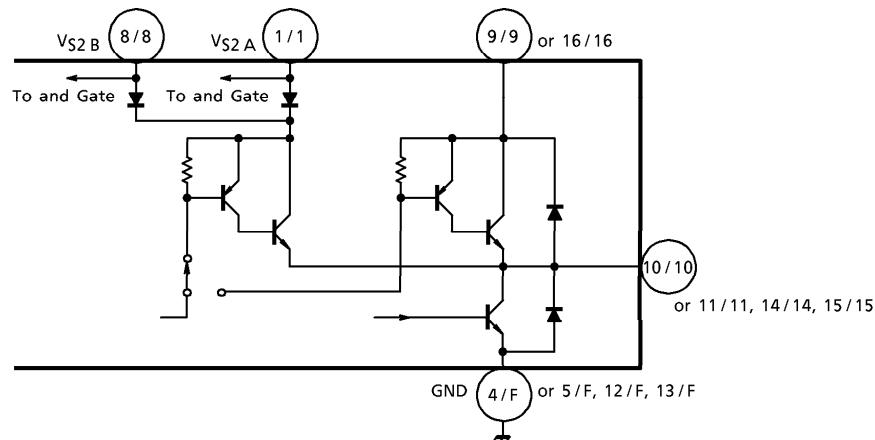
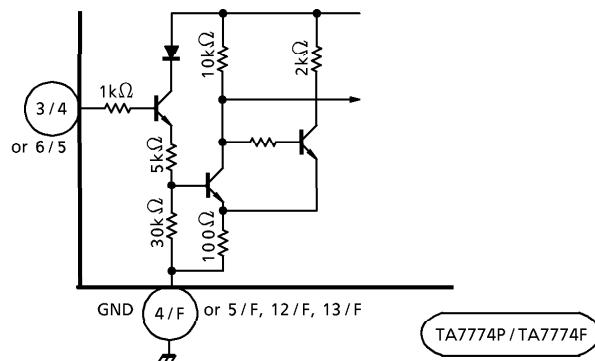
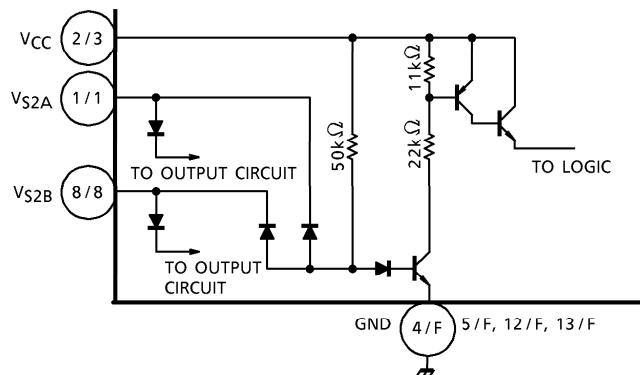
## TRUTH TABLE 2

V <sub>S2 A</sub>	V <sub>S2 B</sub>	
L	(*)	Power Off (stand-by)
(*)	L	Power Off (stand-by)
H	H	Operation

(\*) H or L

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**OUTPUT CIRCUIT****INPUT CIRCUIT IN A, IN B****INPUT CIRCUIT  $V_{S2\ A}$  or  $V_{S2\ B}$** **MAXIMUM RATINGS ( $T_a = 25^\circ\text{C}$ )**

CHARACTERISTIC	SYMBOL	RATING	UNIT
Supply Voltage	$V_{CC}$	7.0	V
	$V_{S1}$	17.0	
	$V_{S2}$	$\sim V_{CC}$	
Output Current	$I_O$ (PEAK)	$\pm 400$	mA
	$I_O$ (START)	$\pm 350$	
	$I_O$ (HOLD)	$\pm 100$	
Input Voltage	$V_{IN}$	$\sim V_{CC}$	V
Power Dissipation	TA7774P	(Note 1) 1.4	W
		(Note 2) 2.7	
		(Note 3) 1.4	
Operating Temperature	$T_{opr}$	$-30 \sim 75$	°C
Storage Temperature	$T_{stg}$	$-55 \sim 150$	°C

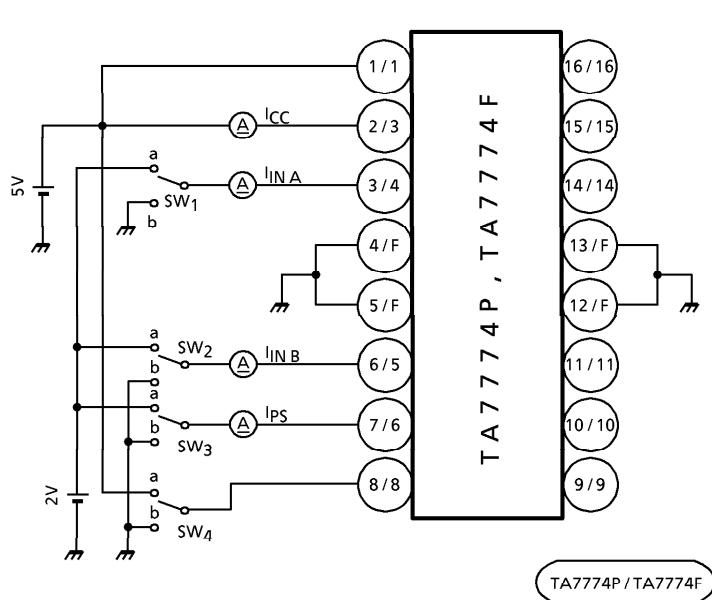
(Note 1) No heat sink

(Note 2) This value is obtained by  $50 \times 50 \times 0.8\text{mm}$  PCB mounting occupied copper area in excess of 60%.(Note 3) This value is obtained by  $60 \times 30 \times 1.6\text{mm}$  PCB mounting occupied copper area in excess of 50%.

ELECTRICAL CHARACTERISTICS (Unless otherwise specified,  $T_a = 25^\circ\text{C}$ ,  $V_{CC} = 5\text{V}$ ,  $V_{S1} = 12\text{V}$ ,  $V_{S2} = 5\text{V}$ )

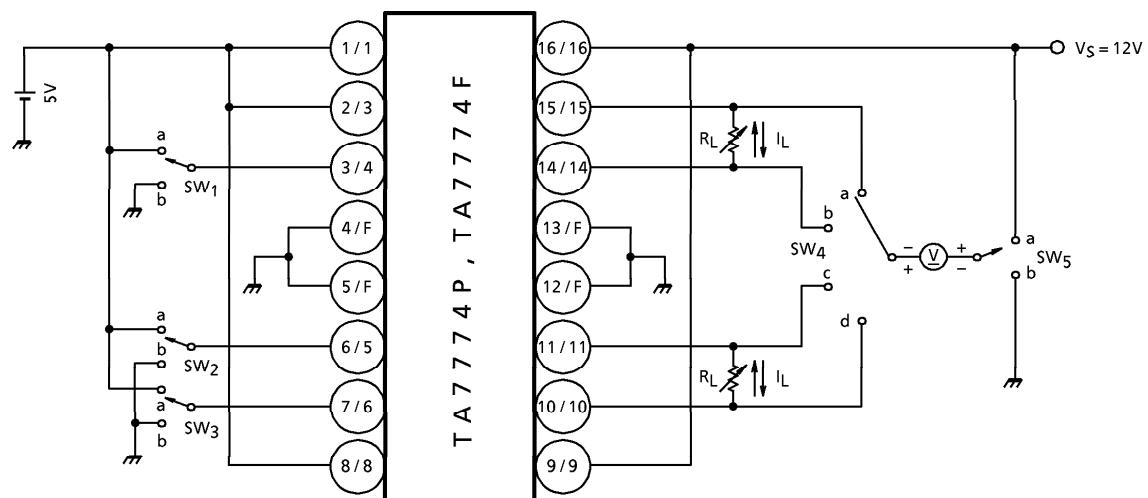
CHARACTERISTIC	SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Supply Current	$I_{CC1}$	1	PS : H, $V_{S2}$ : H	—	9	14	mA
	$I_{CC2}$		PS : L, $V_{S2}$ : H	—	8.5	13	
	$I_{CC3}$		$V_{S2}$ : L	70	90	115	$\mu\text{A}$
Input Voltage	$V_{IN\ H}$	—	$T_j = 25^\circ\text{C}$ $V_{S2}$ : H	Pin ③, ⑥	2.0	—	$V_{CC}$
	$V_{IN\ L}$				GND	—	0.8
	$V_{PS\ H}$			Pin ⑦	2.0	—	$V_{CC}$
	$V_{PS\ L}$		$T_j = 25^\circ\text{C}$		GND	—	0.8
	$V_{VS2\ H}$		Pin ⑧	3.5	—	$V_{CC}$	
	$V_{VS2\ L}$			GND	—	0.4	
Input Current	$I_{IN}$	1	$T_j = 25^\circ\text{C}$ , $V_{S2}$ : H $V_{IN/PS}$ : Sink current	Pin ③, ⑥	—	2.6	30
	$I_{PS}$			Pin ⑦	—	2.6	30
Output Saturation Voltage	$V_{SAT\ 1H1}$	2	PS : L, $V_{S2}$ : H	$I_{OUT} = 100\text{mA}$	—	0.9	—
	$V_{SAT\ 1H2}$			$I_{OUT} = 400\text{mA}$	—	1.2	1.5
	$V_{SAT\ 2H1}$	3	PS : H, $V_{S2}$ : H	$I_{OUT} = 20\text{mA}$	—	1.6	—
	$V_{SAT\ 2H2}$			$I_{OUT} = 100\text{mA}$	—	1.8	2.1
	$V_{SAT\ L1}$	2	$V_{S2}$ : H	$I_{OUT} = 20\text{mA}$	—	0.03	—
	$V_{SAT\ L2}$			$I_{OUT} = 100\text{mA}$	—	0.15	—
	$V_{SAT\ L3}$			$I_{OUT} = 400\text{mA}$	—	0.35	0.6
Diode Forward Voltage	$V_{F\ U}$	4	$I_F = 350\text{mA}$	—	1.5	—	V
	$V_{F\ L}$			—	1.0	—	
Delay Time	$t_{pLH}$	—	IN - $\phi$	—	7	—	$\mu\text{s}$
	$t_{pHL}$			—	2	—	
Operating Voltage	$V_{CC\ (\text{opr.})}$	—	$V_{CC} = \text{ST}$	4.5	5.0	7.0	V

Recommendable Operating Voltage       $V_{S1\ (\text{opr.})} \quad 12\text{V} \pm 10\%$      $V_{S2\ (\text{opr.})} \quad 5\text{V} \pm 10\%$ Operating Voltage Restriction       $V_{S1} \geq V_{S2}$

TEST CIRCUIT 1     $I_{CC1}$ ,  $I_{CC2}$ ,  $I_{CC3}$ ,  $I_{IN\ A}$ ,  $I_{IN\ B}$ ,  $I_{PS}$ 

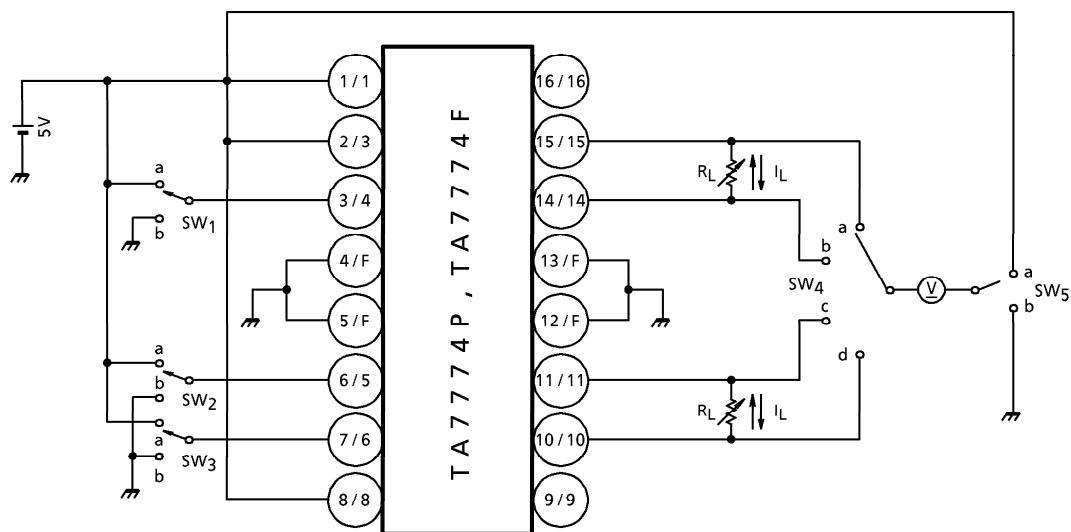
ITEM	SW <sub>1</sub>	SW <sub>2</sub>	SW <sub>3</sub>	SW <sub>4</sub>
$I_{CC1}$	b	b	a	a
$I_{CC2}$	b	b	b	a
$I_{CC3}$	b	b	—	b
$I_{IN\ A}$	a	—	—	a
$I_{IN\ B}$	—	a	—	a
$I_{PS}$	—	—	a	a

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TEST CIRCUIT 2  $V_{SAT\ 1H1}$ ,  $V_{SAT\ 1H2}$ ,  $V_{SAT\ L2}$ ,  $V_{SAT\ L3}$ 

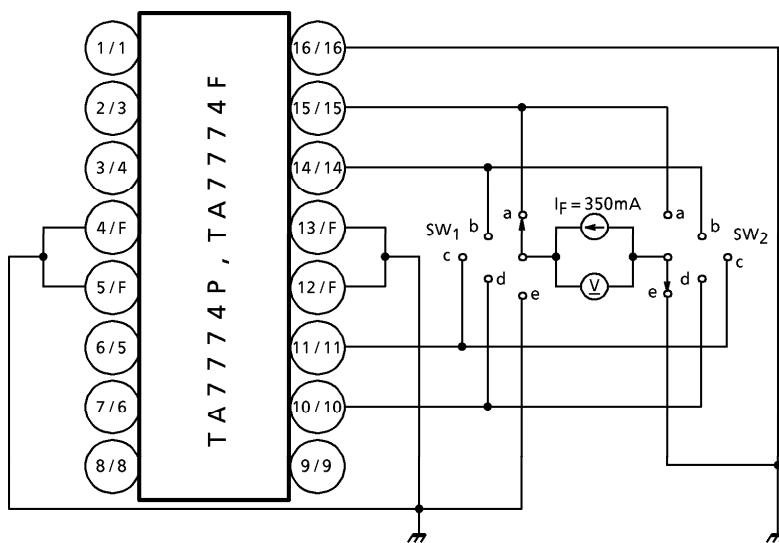
(\*) Calibrate  $I_L$  to 0.4/0.1A by  $R_L$ .

ITEM	SW1	SW2	SW3	SW4	SW5	$I_L$ (mA)
$V_{SAT\ 1H1}$	a	—	b	a	a	100
	b	—		b		
	—	a		d		
	—	b		c		
$V_{SAT\ 1H2}$	a	—	b	a	a	400
	b	—		b		
	—	a		d		
	—	b		c		
$V_{SAT\ L2}$	a	—	—	b	b	100
	b	—		a		
	—	a		c		
	—	b		d		
$V_{SAT\ L3}$	a	—	b	b	b	400
	b	—		a		
	—	a		c		
	—	b		d		

TEST CIRCUIT 3  $V_{SAT\ 2H1}$ ,  $V_{SAT\ 2H2}$ ,  $V_{SAT\ L1}$ 

(\*) Calibrate  $I_L$  to 20 / 100mA by  $R_L$ .

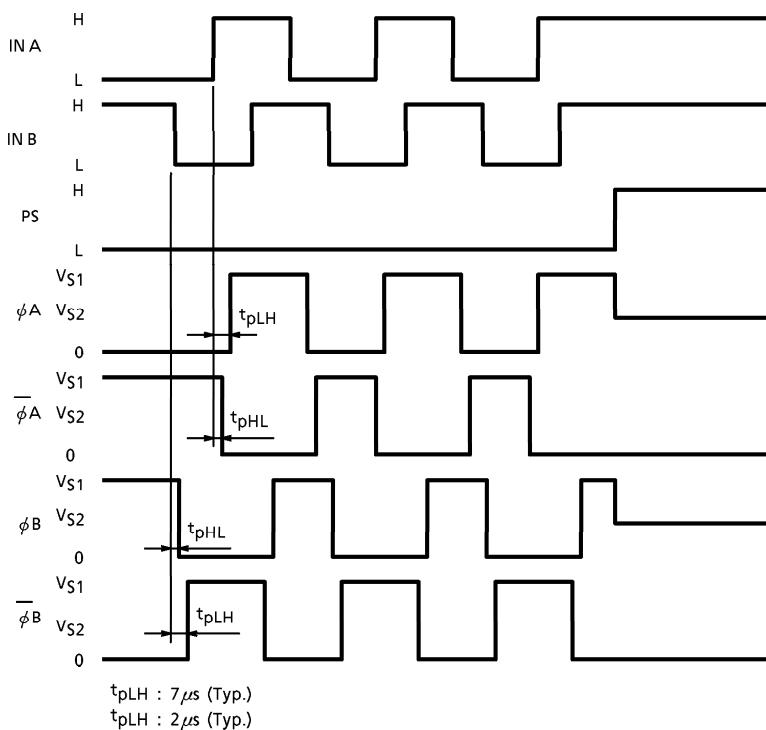
ITEM	SW1	SW2	SW3	SW4	SW5	$I_L$ (mA)
$V_{SAT\ 2H1}$	a	—	a	a	a	20
	b	—		b		
	—	a		c		
	—	b		d		
$V_{SAT\ 2H2}$	a	—	a	a	a	100
	b	—		b		
	—	a		c		
	—	b		d		
$V_{SAT\ L1}$	a	—	a	b	b	20
	b	—		a		
	—	a		c		
	—	b		d		

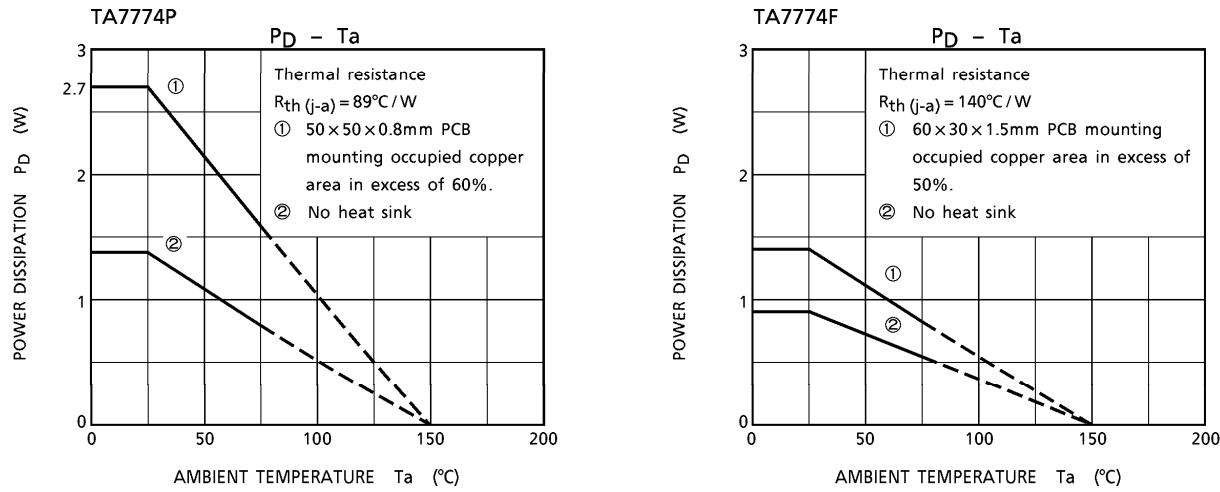
TEST CIRCUIT 4  $V_{FU}$ ,  $V_{FL}$ 

## MEASURING METHOD

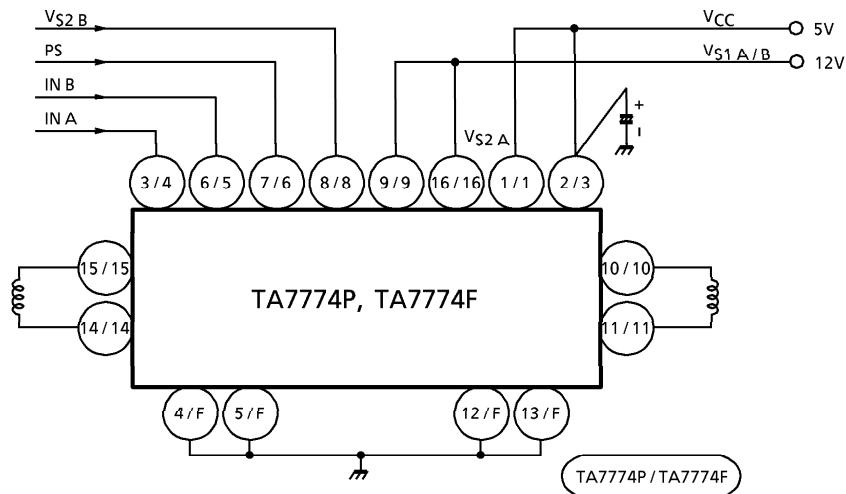
ITEM	SW1	SW2
$V_{FU}$	a	e
	b	
	c	
	d	
$V_{FL}$	e	a

## TIMING CHART (2 phase excitation)





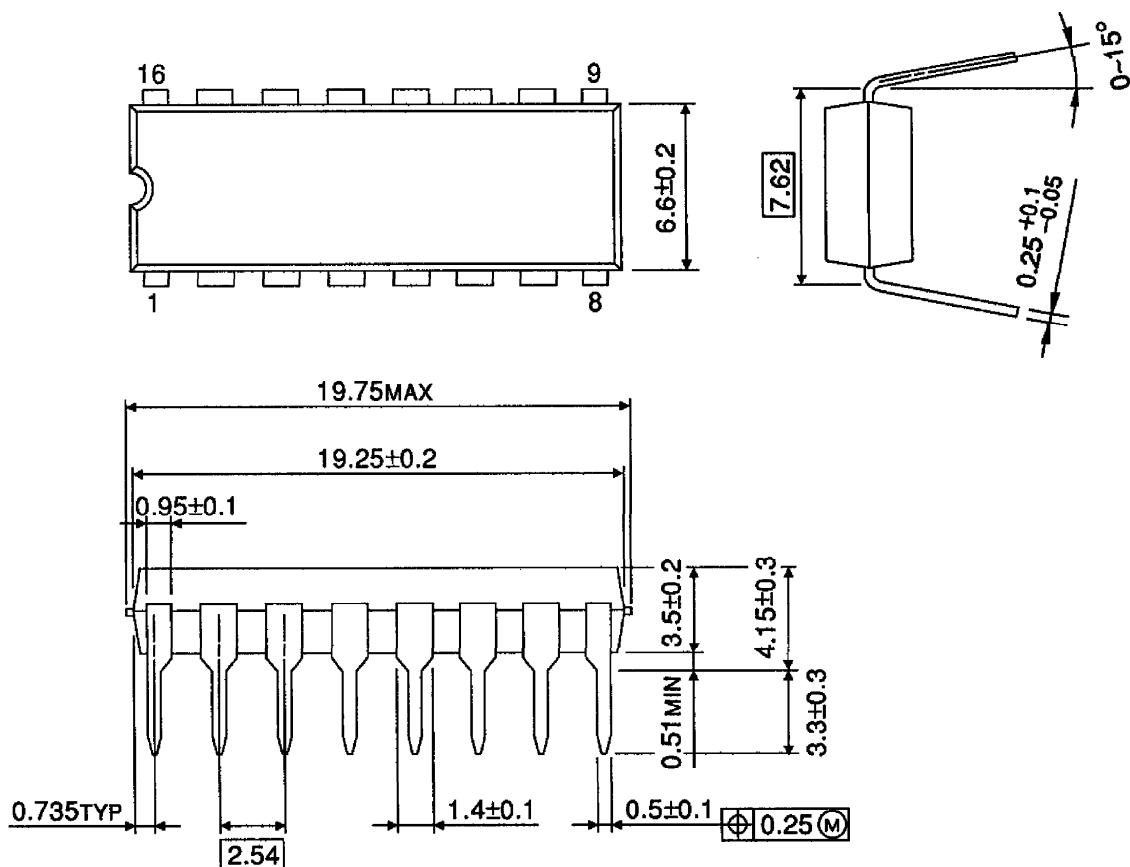
### APPLICATION CIRCUIT



(Note) Utmost care is necessary in the design of the output line,  $V_S$  and GND line since IC may be destroyed due to short-circuit between outputs, air contamination fault, or fault by improper grounding.

**OUTLINE DRAWING**  
DIP16-P-300-2.54A

Unit : mm

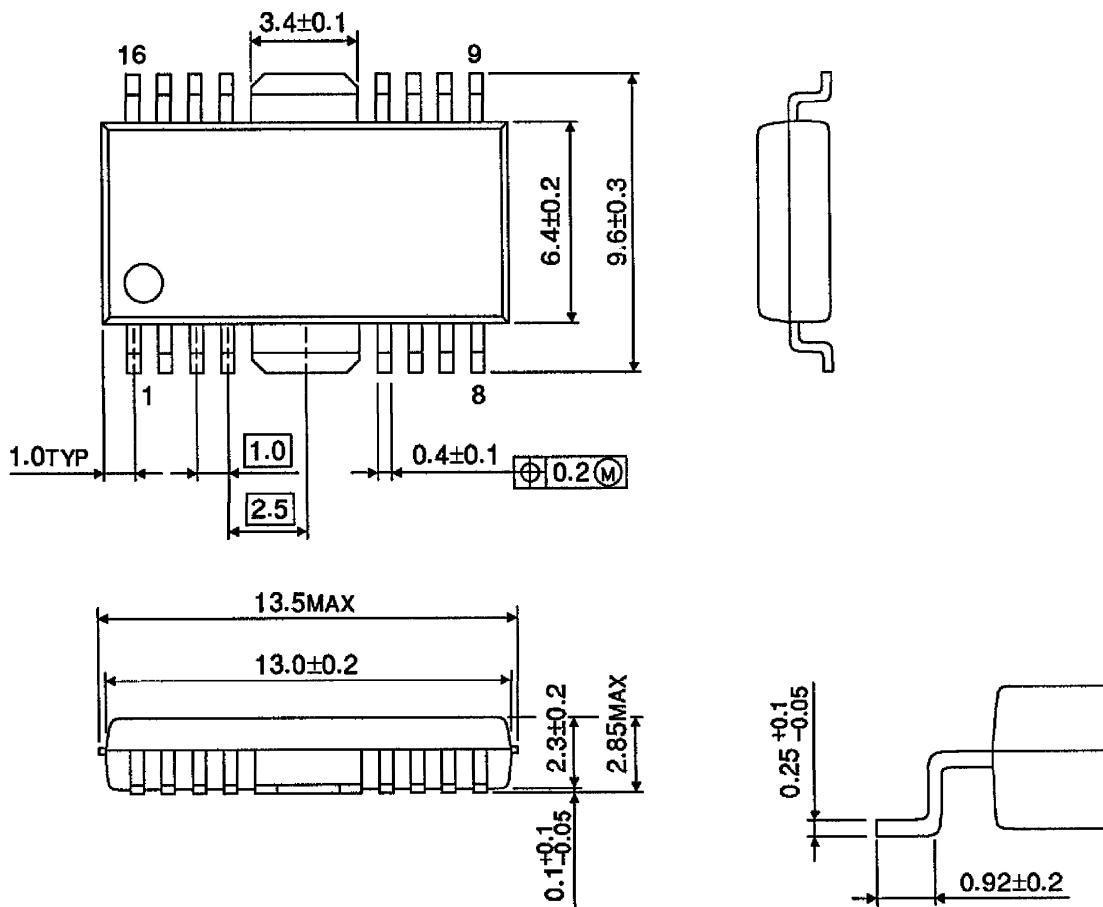


Weight : 1.11g (Typ.)

## OUTLINE DRAWING

HSOP16-P-300-1.00

Unit : mm



Weight : 0.50g (Typ.)