#### **FEATURES**

- 384x series pin-to-pin compatible
- Linearly decreasing PWM frequency
- Burst-mode at low/zero load
- 5uA start-up current
- 5mA operating current
- Vcc over voltage protection
- Cycle-by-cycle current limiting
- Zero cross-conduction
- Slew rate controlled high current totem pole output
- Fast current sense propagation delay
- Under voltage lockout (UVLO) with hysteresis

#### **APPLICATIONS**

- Switching mode power supplies
- Power converters

#### **DESCRIPTION**

The SG348xG series of current-mode PWM controllers combines high performance with Green-mode power saving features. SG348xG controllers are fully pin-to-pin compatible with bipolar UC384x devices, but they have improved features and functionality. SG384xG series controllers are compatible with the BiCMOS fabrication process, enabling the use of low start-up current and operating currents. This feature further improves power conversion efficiency. The minimal

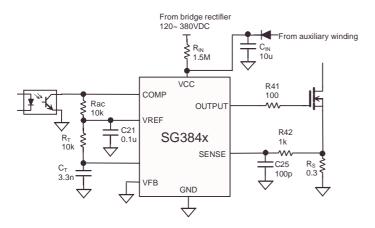
start-up current has been reduced to 5uA, and the minimum operating current has been reduced to 5mA. Each SG384xG has a slew rate controlled high current totem pole output, ideally suited for driving a power MOSFET while keeping EMI low.

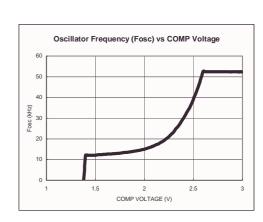
The current-sense propagation delay is typically 50ns, resulting in significantly more effective constant power protection. During normal operation, a SG384xG controller acts as a fixed frequency PWM controller. The PWM frequency can be easily programmed by changing external R<sub>T</sub> and C<sub>T</sub> values. The SG384xG includes two Green-mode functions that dramatically reduce power usage, helping the power supply comply with the latest international power saving guidelines. To cut power consumption under light load conditions, the controller's Green-mode function will linearly decrease the PWM frequency in response to decreases in the output load. Under ultra light-load/zero-load conditions, the RT/CT PWM oscillator periodically shuts down, and enters into Burst-mode. This causes the IC's supply voltage to begin gradually dropping. Just before the supply voltage drops below the UVLO voltage threshold, the RT/CT PWM oscillator turns back on, to prevent the supply voltage from going below the UVLO voltage.

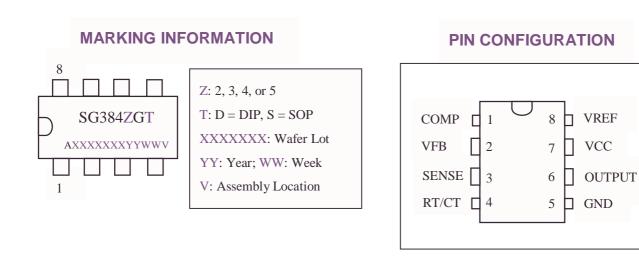
SG384xG controllers also come with Over Voltage Protection (OVP). This shuts down PWM output if the supply voltage ever exceeds 27V. The SG384xG series comes in 8-pin DIP and SOP packages.

#### TYPICAL APPLICATION

# Green-mode Operation Oscillator Frequency vs. COMP







## **ORDERING INFORMATION**

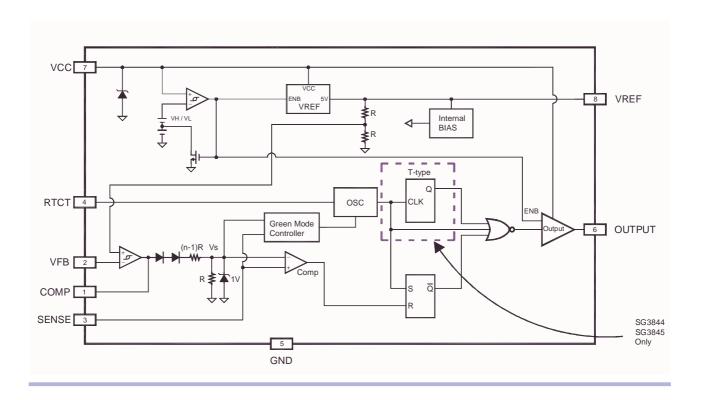
Part Number	U\	/LO	Maximum duty cycle	Package
r art Number	Start threshold	Stop threshold	Maximum duty Cycle	rackage
SG3842GAD	16V±1V	10V±1V	98%	8-Pin DIP
SG3842GAS	100110	TOVETV	90 /0	8-Pin SOP
SG3843GAD	8.9V±0.5V	8.1V±0.5V	98%	8-Pin DIP
SG3843GAS	0.9 V ±0.5 V	0.1 V±0.5 V	96 /6	8-Pin SOP
SG3844GAD	16V±1V	10V±1V	49%	8-Pin DIP
SG3844GAS	100±10	V   10V±1V   49		8-Pin SOP
SG3845GAD	8.9V±0.5V	.5V 8.1V±0.5V 49%		8-Pin DIP
SG3845GAS	0.3 v ±0.3 v	0.1 V±0.5 V	73 /0	8-Pin SOP

#### **PIN DESCRIPTIONS**

Pin No.	Symbol	Function	Description
1	COMP	Compensation	Output of the Error Amplifier and input to the PWM comparator. It is used for feedback loop compensation.
2	VFB	Feedback	Inverting input of the Error Amplifier. It is normally connected to the switching power supply output through a resistor divider.
3	SENSE	Current sense	Current sense comparator input. It is internally set to 1V maximum. A voltage proportional to the inductor current is connected to this input.
4	RT/CT	Oscillator control	Oscillator RC timing connection. Connecting a resistor RT from this pin to Vref, and a capacitor CT from this pin to ground, programs the oscillator frequency and the maximum output duty cycle.
5	GND	Ground	This pin is the combined control circuit ground and power ground.
6	OUTPUT	Output	High-power, totem-pole driver output. This output drives the gate of a power MOSFET.
7	VCC	Power supply	Supply voltage input.
8	VREF	Reference voltage	5V-reference voltage output.



## **BLOCK DIAGRAM**



## **ABSOLUTE MAXIMUM RATINGS**

Symbol	Parameter	Test Condition	Value	Unit
Vcc	Supply voltage	Low impedance source Zener clamp	25 28	V
lz	Zener current		10	mA
V <sub>IN</sub>	FB/SENSE terminal input voltage	FB, SENSE	-0.3 to 5.5V	V
Isink	Error amplifier sink current		10	mA
Pd	Power dissipation	at Ta<50°C DIP SOP	800 400	mW
R <sub>⊕ j-a</sub>	Thermal resistance	Junction-air DIP SOP	82.5 141	°C/W
T <sub>J</sub>	Operating junction temperature	-	+150	°C
Ta	Operating ambient temperature	-	-40 to 125	°C
Tstg	Storage temperature range	-	-65 to +150	°C
TL	Lead temperature (Soldering)	10 sec DIP 20 sec SOP	260 220	°C
	ESD Capability, HBM model		3.0	kV
	ESD Capability, Machine model		200	V

## **OPERATING CONDITIONS**

Symbol	Parameter	Min.	Max.	Unit
Vcc	Supply voltage	-	20	V
C <sub>T</sub>	Oscillation timing capacitor	0.47	10	nF
$R_T$	Oscillation timing resistor	2.0	100	kΩ
fosc	Oscillation frequency	10	500	kHz
Ta	Operating ambient temperature	-40	105	°C

## **ELECTRICAL CHARACTERISTICS**

# **Reference Voltage Section**

Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit
Vref	Reference output voltage	Ta=25°C, Io=1mA	4.75	5.0	5.25	V
Line	Line regulation	Vcc=10 to 20V	-	2	20	mV
Load	Load current regulation	Io=1mA to 20mA	-	20	50	mV
Vtc	Temperature stability	-	-	0.5	-	mV/°C
los	Short-circuit output current	-	-30	-85	-180	mA
Vref	Total output variation	Line, Load, Temperature	4.75	5.0	5.25	V
Vn	Output noise voltage	f=10Hz to 10kHz , Ta=25°C	-	50	-	uV
S	Long term stability	Ta=125°C for 1000 hours	-	5	25	mV

# Oscillator Section (VFB=0V, SENSE=0V)

Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit
Fosc	Oscillator frequency	SG3842G, SG3843G, SG3842G2, SG3844G2	49	52	55	kHz
		SG3844G, SG3845G	24	26	28	kHz
Fosc-G	Green-mode frequency (note 1)	Vsense=0V	8	12	16	kHz
	Comp Voltage that initiates Green-mode	SG3842G, SG3844G		2.60		V
$V_{\text{comp},H}$		SG3842G2, SG3843G, SG3844G2, SG3845G		2.00		V
		SG3842G, SG3844G		1.40		V
$V_{\text{comp,L}}$	Comp Voltage that shuts down PWM	SG3842G2, SG3843G, SG3844G2, SG3845G		1.30		V
fdv	Frequency change with Vcc	Vcc=10 to 20V	-	0.2	1	%
fdt	Frequency change with temp.	Ta=-40 to 85°C	-	0.02	-	%/°C
I <sub>DISCHG</sub>	Discharge current	Ta=25°C	7	9	12	mA

Note 1:  $F_{\rm OSC-G}$  is the last PWM frequency before completely turned off @ Vcc=15V

## **Error Amplifier Section**

Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit
$V_{FB}$	Input voltage	Comp=2.5V	2.45	2.5	2.55	V
lib	Input bias current	-	-	-	0.1	uA
Avol	Open-loop voltage gain	-	45	55	-	dB
BW	Unity gain bandwidth	-	0.7	1.2	-	MHz
PSRR	Power supply rejection ratio	-	50	-	-	dB
Isource	Output source current	FB=2.3V,COMP=0V	-0.8	-1.8	-3	mA
Isink	Output sink current	FB=2.7V,COMP=1V	2	6.5	-	mA
V <sub>H COMP</sub>	Output voltage	FB=2.3V, R <sub>L</sub> =15K to GND	6	6.6	-	V
V <sub>L COMP</sub>	Output voltage	FB=2.7V, R <sub>L</sub> =15K to VREF	-	-	700	mV



#### SG3842G/3843G/3844G/3845G

## **Current Sense Section**

Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit
		SG3842G, SG3844G	4.60	5.00	5.40	V/V
AV	Current sense input voltage gain (n)	SG3842G2, SG3844G2, SG3843G, SG3845G	2.76	3.00	3.24	V/V
I <sub>IB</sub>	Input bias current	-	-	-1	-5	uA
$T_PD$	Delay to output	Ta=25°C	-	50	150	nS
V <sub>TH(IS)</sub>	Maximum input signal	-	0.9	1.0	1.1	V

## **Output Section**

Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit
Vol	Output voltage low	Vcc=15V, Io=20mA	-	-	0.5	V
Voh	Output voltage high	Vcc=15V, Io=20mA	13	-	-	V
Tr	Rising time	Ta=25°C, CL=1nF	-	50	150	nS
Tf	Falling time	Ta=25°C, CL=1nF	-	50	150	nS

# **Under-Voltage Lockout Section**

Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit
\/ Ctort	Start threshold voltage	SG3842G, SG3844G	15	16	17	V
V <sub>TH(ON)</sub>	Start tilleshold voltage	SG3843G, SG3845G	8.4	8.9	9.4	V
V <sub>TH(OFF)</sub> Minimur	Minimum operating voltage	SG3842G, SG3844G	9	10	11	V
	Minimum operating voltage	SG3843G, SG3845G	7.6	8.1	8.6	V

## **PWM Section**

Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit
DCY <sub>(MAX)</sub>	Maximum duty avala	SG3842G, SG3842G2, SG3843G	90	95	98	%
DC T (MAX)	Maximum duty cycle	SG3844G, SG3844G2, SG3845G	45	47	49	%
DCY <sub>(MIN)</sub>	Minimum duty cycle	FB=5V, COMP=Open	-	-	0	%

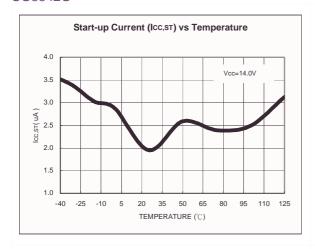
## **Total Standby Current Section**

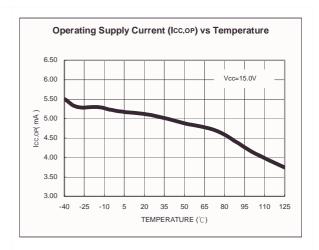
Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit
I <sub>CC ST</sub>	Start-up current	SG3842G, SG3844G Vcc=15V	-	5	15	uA
	·	SG3843G, SG3845G Vcc=8	3V -	3	10	uA
I <sub>CC OP</sub>	Operating supply current	FB=SENSE=0V, VDD=15V, CL=1000pF	-	5.0	6.5	mA
Vz	Power supply zener voltage	Icc=10mA	25	28	-	V
V <sub>P</sub>	Power supply protection voltage			27		V

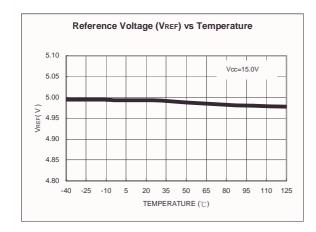


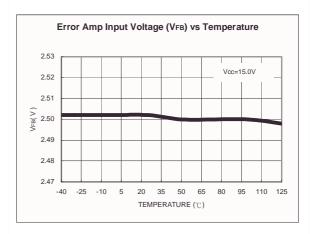
## **TYPICAL CHARACTERISTICS**

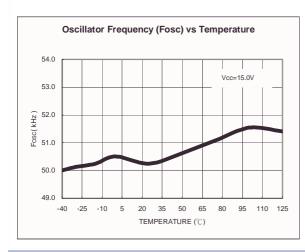
#### SG3842G

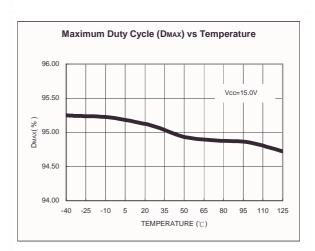




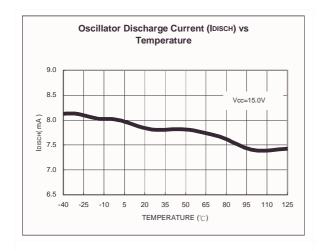


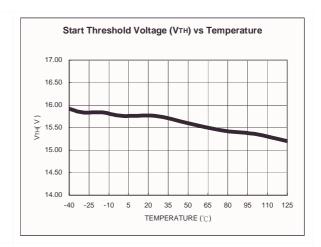


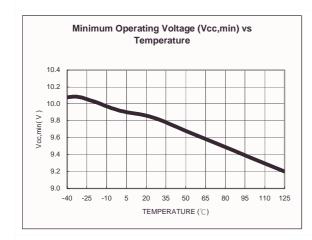


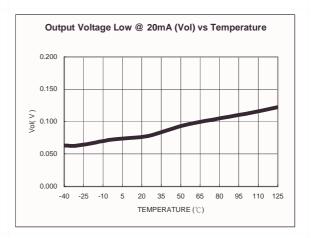


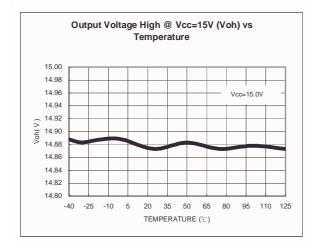


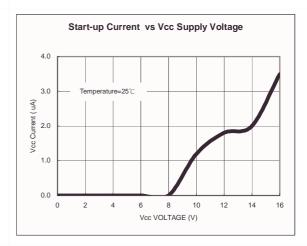






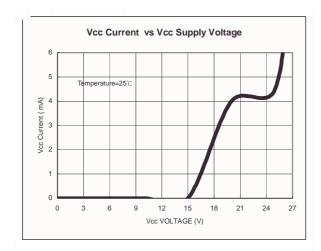


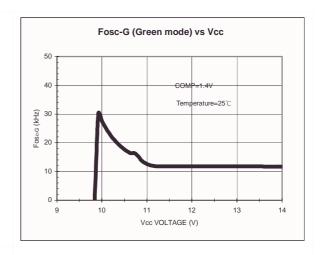


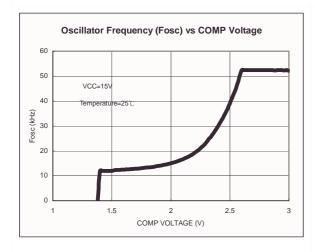




## SG3842G/ 3843G/ 3844G/ 3845G



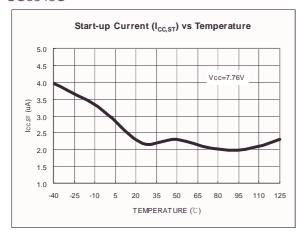


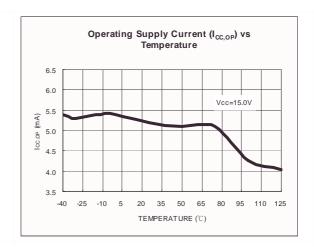


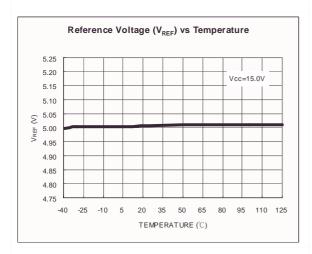


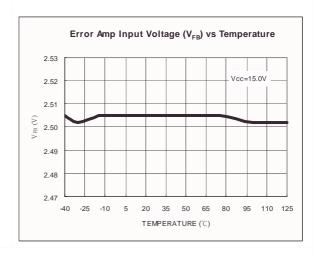
#### **BiCMOS Green-Mode PWM Controllers**

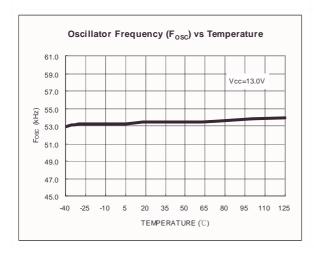
#### SG3843G

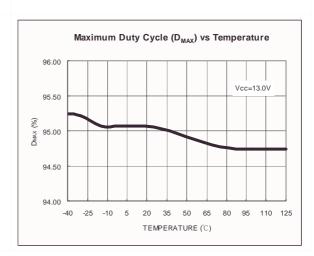




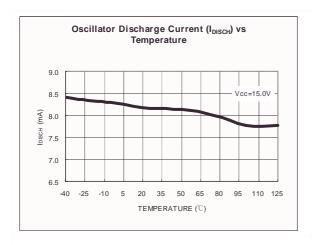


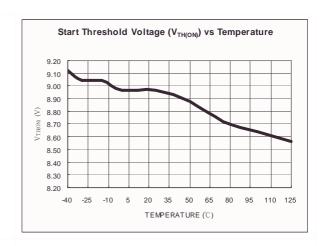


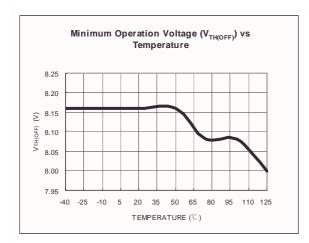


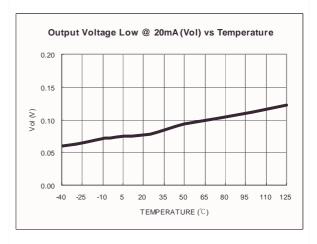


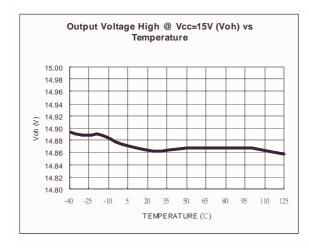


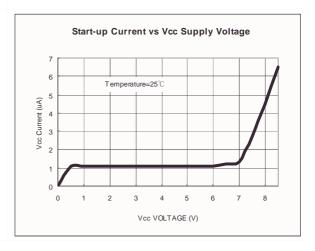






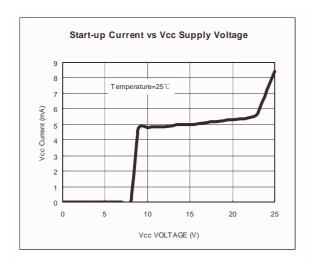


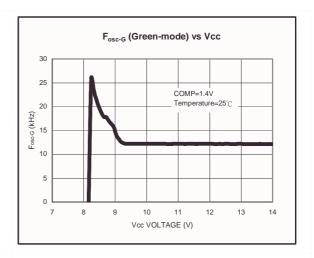


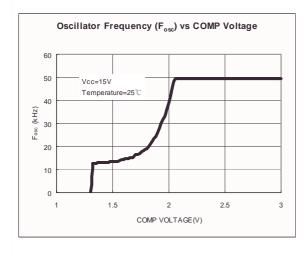




## SG3842G/ 3843G/ 3844G/ 3845G









#### **OPERATION DESCRIPTION**

SG384xG devices have many advantages over traditional 384x devices and are completely pin-to-pin compatible with them. The following descriptions highlight the advantages and the differences of the SG384xGA designs.

#### **Start-up Current**

The required start-up current is typically only 5uA. This ultra-low start-up current allows designers to supply the start-up power required by the SG384xG using a high-resistance and a low-wattage start-up resistor. For example, an application using wide input range  $(100V_{AC}\!\!\sim\!\!240V_{AC})$  AC-to-DC power adapter could work with a 1.5 M $\Omega$ /0.25W resistor, and a 10uF/25V Vcc hold-up capacitor.

## **Operating Current**

The operating current has been reduced to 5.0mA. This low operating current results in higher efficiency and reduces the required Vcc hold-up capacitance.

#### **Oscillator Operation**

The resistor  $R_T$  and the capacitor  $C_T$ , both connected to the pin RT/CT, determine the oscillation frequency. The capacitor  $C_T$  is normally charged to 2.9V through the resistor  $R_T$ , which is connected to a 5V reference voltage and discharged to 1.3V by a built-in constant current sink. The dead-time is generated during the discharge period. The SG3844G/45G both have an internal divide-by-two flip-flop driven by the oscillator, resulting in a 50% maximum duty cycle. Thus, the output switching frequency is 1/2 of the oscillation frequency determined by  $R_T$  and  $C_T$ .

$$f(kHz) = \frac{1.72}{\left[R_{T}(k\Omega) \times C_{T}(\mu F)\right]}$$

## **Error Amplifier**

The error amplifier's inverting input is connected to the FB pin, and the output is connected to the COMP pin. The COMP output is available for external compensation, allowing designers to control the feedback-loop frequency-response. Non-inverting input is not wired out to a pin, but it is internally biased to a fixed  $2.5 \rm V \pm 2\%$  voltage.

## **Current Sensing and PWM Limiting**

The SG384xG current-sense input is designed for current-mode control. Current-to-voltage conversion is done externally through the current-sense resistor Rs. Under normal operation, the COMP voltage determines the peak-voltage across Rs.  $V_{\rm COMP}$  is the voltage at the pin COMP and n is the current-sense input voltage gain.

$$I_{pk} = \frac{V_{COMP} - 1.4}{n * \times R_S}$$

\*n = is typically 5 (4.60 ~ 5.40) for the <u>SG3842G</u> and the <u>SG3844G</u> standard versions. n = 3 typically (2.76 ~ 3.24) for the <u>SG3842G2</u>, <u>SG3844G2</u>, <u>SG3843G</u>, and the <u>SG3845G</u> models.

This feature is compatible with general 384x series products. A higher n value attenuates the feedback and ensures loop stability under light-load conditions. The inverting input to the SG384xG current-sense comparator is internally clamped to 1V.

## **Under Voltage Lockout (UVLO)**

The Under Voltage Lockout (UVLO) function ensures the SG384xG's supply voltage Vcc will be sufficiently high before the output stage is enabled. The turn-on and turn-off threshold voltages are fixed internally at 16V/10V for the SG3842G/44G and at 8.9V/8.1V for the SG3843G/45G. The hysteresis voltage between turn-on and turn-off prevents Vcc from being unstable during power on/off sequencing. At start-up, before the output



#### **BiCMOS Green-Mode PWM Controllers**

switch is enabled, the Vcc hold-up capacitor C<sub>IN</sub> must be charged up to 16V (SG3842G/44G) through the start-up resistor R<sub>IN</sub>, The ultra-small start-up current of 5uA allows very large resistance values for the resistor R<sub>IN</sub> to be used, even with low input voltages. For example, if  $V_{AC}$  = 90Vrms,  $R_{\rm IN}$  can be as large as 1.5  $M\Omega$  and still charge the hold-up capacitor C<sub>IN</sub>. The power dissipation from this larger resistance R<sub>IN</sub> would then be less than 70mW (0.07W), even under high line conditions  $(V_{AC} =$ 240Vrms). After the IC starts-up and begins normal operation, one of the transformer's auxiliary windings generates the supply voltage Vcc, which supplies the operating current of the SG384xG controller.

#### **Slew Rate Controlled Output Driver**

The BiCMOS output stage directly drives the external power MOSFET up to the full supply voltage. The output driver, with a low ON-resistance and high current-driving capability, can easily drive an external capacitive load larger than 1000pF. If operating under recommended conditions, the switching frequency can go up to 500kHz.

The output stage is designed to ensure zero crossconduction current. This minimizes heat dissipation, increases efficiency, and enhances reliability. The output driver is also slew-rate controlled to minimize EMI.

# **Green-Mode: Linearly Decreasing** Frequency and Burst-Mode

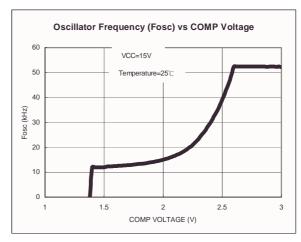
System General's patented Green-mode function reduces the switching frequency under light-load and zero-load conditions. Modulation of the PWM frequency can reduce power consumption under light-load and zero-load conditions, because the power loss is directly proportional to the switching frequency.

Most of the power loss in a power supply occurs due to the switching loss of the transistor, the core loss of the transformer and inductors, and the power loss of the snubber. These sources of power loss all lose power in proportion to the switching frequency.

The controller uses the output of the error amplifier as a feedback voltage to calculate load conditions. When the feedback voltage goes below the Green-mode threshold voltage, the switching frequency will be reduced. Under normal-load and high-load conditions, the PWM operates as usual, and the frequency modulation feature does not affect its operation.

There are two factors that determine the PWM frequency:

- The resistor  $R_T$  and the capacitor  $C_T$  determine the RC charge and discharge times, and therefore, the circuit frequency. They are both connected to the pin RT/CT.
- 2. Internal comparator threshold voltages. Under normal-load conditions, the internal comparator threshold voltages are fixed at 1.3V (V<sub>comp,L</sub>) and 2.9V (V<sub>comp,H</sub>). Under light-load conditions, the V<sub>comp,H</sub> internal threshold voltage gradually increases. This will increase the RC charging/discharging time, therefore decreasing the frequency. Under ultra-light or zero-load conditions, the  $V_{comp,H}$  voltage is increased to 4.6V. This will put the circuit into the lowest frequency it can operate at. Assuming  $R_T$  = 10k and  $C_T = 3.3nF$ , this is about 12kHz. The frequency vs. COMP voltage (feedback from the



output load) is shown in Fig.1.

Fig.1 Oscillator Frequency vs. COMP Voltage

If 12kHz is not low enough to meet stand-by power conservation requirements, a shunt resistor R<sub>C</sub> can be connected in parallel with the capacitor C<sub>T</sub> between RT/CT and GND. This will allow the SG384xG to enter into burst-mode.

For example, assuming  $R_T=10k\Omega$  and  $R_C=47k\Omega$ , the peak RT/CT voltage would only be:

$$5V \times \frac{47}{(10+47)} = 4.12V$$

Since 4.12V is less than the internal  $V_{comp,H}$  4.6V voltage under light-load conditions, the RT/CT oscillator would take a long time to charge up to 4.6V. In this situation, the RT/CT oscillator will stop oscillating.

When oscillation stops, there is no PWM output. Consequently, the energy required to supply the SG384xG from the auxiliary winding also gets cut off. This causes the supply voltage Vcc to start dropping. If the supply voltage Vcc drops below the UVLO voltage, it will take the SG384xG several hundred milliseconds to start-up. This delay will cause too much fluctuation to the output voltage. To avoid this, the SG384xG will automatically reduce the internal  $V_{\text{comp},H}$  voltage, turning the RT/CT oscillator back on when the Vcc supply voltage falls within 1.5V of the UVLO voltage. In Burst-mode, the PWM frequency is burst between 0Hz and the light-load tens of kHz region, not over the full frequency range. Fig.2 shows the Green-mode frequency vs. the supply voltage Vcc. The Green-mode frequency is fixed at 12kHz when Vcc is above 11V. When Vcc is below 11V and approaching UVLO, the PWM frequency is gradually increased. This increases the energy supplied to Vcc, and pulls up the Vcc supply voltage to prevent it from dropping below UVLO.

These techniques help achieve optimal power savings. The SG384xG can linearly decrease the PWM frequency under light-load conditions, and enter into burst-mode under ultra-light load and zero-load conditions. Linear frequency reduction and burst-mode enable the SG384xG to deliver excellent power savings and load regulation.

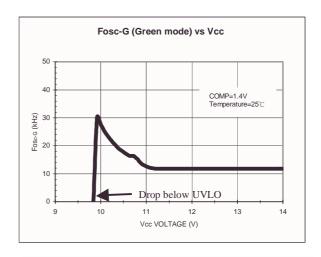


Fig.2 Green-mode Frequency vs. Supply Voltage Vcc

## Vcc Over Voltage Protection (OVP)

When the SG384xG's supply voltage increases to 27V due to abnormal conditions, such as an open loop from the photo-coupler, or a short circuit on the output side, the SG384xG will stop PWM output, to protect the entire power supply from being damaged.

## **Noise Immunity**

Noise from the current-sense or the control signal can cause significant pulse-width jitter, particularly under continuous-mode operation. Slope compensation partially alleviates this problem, but the designer should be aware of its presence.

The 384x has a single ground pin. High sink current in the output therefore cannot be returned separately. Ceramic bypass capacitors (0.1uF) from Vcc and VREF to ground will provide low-impedance paths for high-frequency transients.

For best results, good high-frequency and RF layout practices should be followed. The designer should avoid long PCB traces and component leads. The oscillator, compensation, and filter components should be located near the 384x. In order to minimize noise interference to the oscillator, it is recommended that  $C_T$  should never be less than 1000pF.

Noise caused by the output (pin 6) also causes problems sometimes. This is because the pin is being pulled below ground at turn-off by the external parasitic. This is



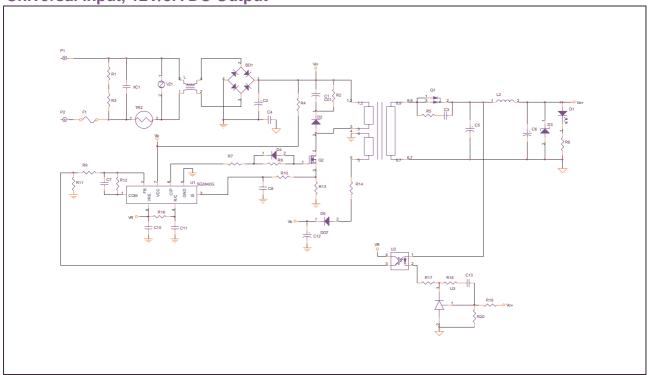
SG3842G/ 3843G/ 3844G/ 3845G

particularly true when driving a MOSFET. A resistor series connected from the output (pin 6) to the gate of the

MOSFET will prevent such output noise.

## **REFERENCE CIRCUIT**

# **Universal Input, 12V/5A DC Output**

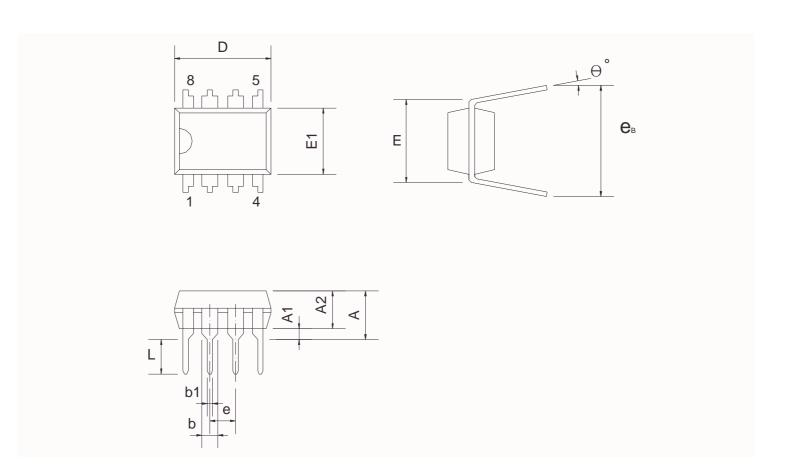


## **BOM**

Symbol	Components	Symbol	Components	
BD1	BD 1A/600V	R1,3	470K 1/4W	
C1		R2		
C2	EC 68u/400V	R4	1M 1/4W	
C3	CC 102P/1KV	R5	43 1/2W	
C4	YC 222P	R6	4.7K 1/4W	
C5	EC 1200u/16V	R13	0.5 1W	
C6	EC 680u/16V	R14	10 1/8W	
C12	EC 10u/25V	R17	100 1/8W	
D1	LED	TR2	SCK054	
D2		T1	El28	
D3	ZD 15V	U1	SG384xG	
D4	1N4148	U2	4N35D	
F1	2A/250V	U3	TL431	
L1	UU10.5	VZ1	VZ	
L2		XC1	XC 0.22u	•
Q2	MOS 2A/600V			•



# PACKAGE INFORMATION 8 DIP Outline Dimensions

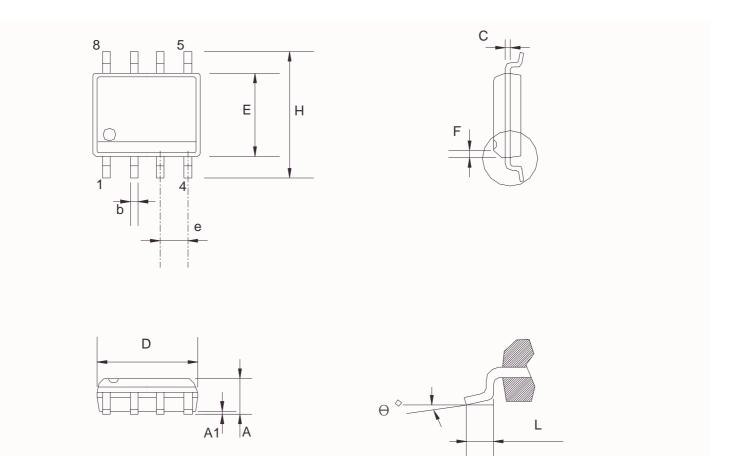


## **Dimensions**

Symbol	Millimeter			Inch	Inch		
	Min.	Тур.	Max.	Min.	Тур.	Max.	
A			5.334			0.210	
A1	0.381			0.015			
A2	3.175	3.302	3.429	0.125	0.130	0.135	
b		1.524			0.060		
b1		0.457			0.018		
D	9.017	9.271	10.160	0.355	0.365	0.400	
E		7.620			0.300		
E1	6.223	6.350	6.477	0.245	0.250	0.255	
е		2.540			0.100		
L	2.921	3.302	3.810	0.115	0.130	0.150	
e <sub>B</sub>	8.509	9.017	9.525	0.335	0.355	0.375	
$\theta$ °	0°	7°	15°	0°	7°	15°	



## **8 SOP Outline Dimensions**



# **Dimensions**

Symbol	Millimeter			Inch		
	Min.	Тур.	Max.	Min.	Тур.	Max.
Α	1.346		1.752	0.053		0.069
A1	0.101		0.254	0.004		0.010
b		0.406			0.016	
С		0.203			0.008	
D	4.648		4.978	0.183		0.196
Е	0.381		3.987	0.150		0.157
е		1.270			0.050	
F		0.381X45°			0.015X45°	
Н	5.791		6.197	0.228		0.244
L	0.406		1.270	0.016		0.050
$\theta$ °	0°		8°	0°		8°



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