

# QR0001

*QR0001 QuickRing(TM) Data Stream Controller*



Literature Number: SNOS705A

# QR0001 QuickRing™ Data Stream Controller

## General Description

QuickRing is a point-to-point data transfer architecture designed to facilitate high speed data streams. The QuickRing architecture can be applied both inside the chassis as well as outside the chassis environments to increase data throughput. Each QR0001 QuickRing Controller node in the ring is capable of streaming up to 231 MSamples/s per signal line simultaneously, including protocol overhead. This device is intended for use in applications that handle high-bandwidth data streams associated with graphics, uncompressed video, disk arrays, high-speed local area networks, multiprocessor systems, and to interconnect peripherals over a few meters of cable. The QR0001 QuickRing Controller can be used to augment the performance of traditional backplane buses in personal computers, workstations, and high-end systems. The QR0001 is useful for routing high-bandwidth streams in systems that are larger or topologically more complex than bus-based systems.

## Features

- 160-pin PQFP package
- 16 node single ring capability
- Peak theoretical rate over 1 GByte/sec for 16 node ring
- Support for Multi-Ring topologies
- Error detection detects 1- and 2-bit errors

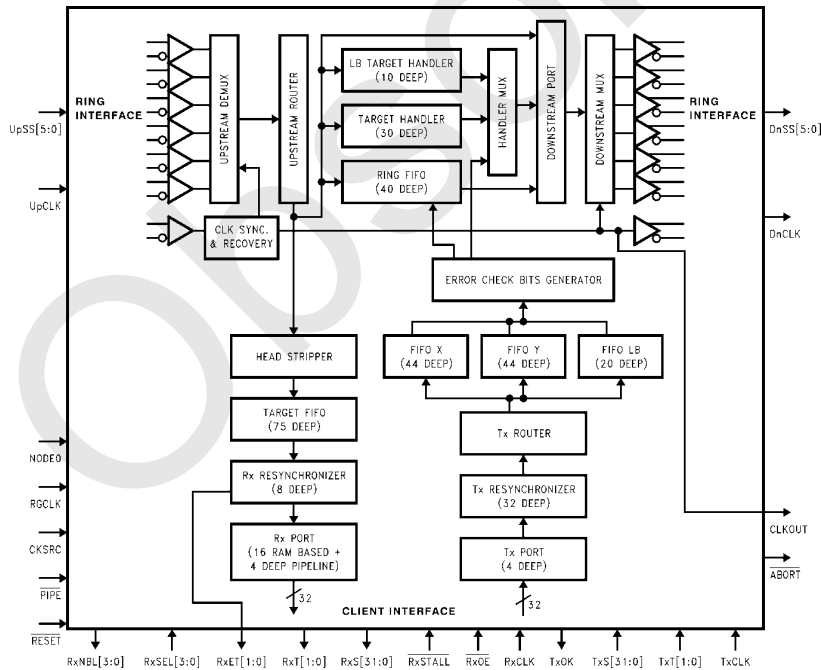
## RING INTERFACE

- Precision PLL captures data at 231 MSamples/s max
- 33 MHz maximum ring clock frequency
- Low Voltage Differential Signaling (LVDS) ring interface (IEEE P1596.3)

## CLIENT INTERFACE

- 132 MBytes/s data transfer rate at both Tx and Rx ports
- 32-bit transmit and receive data ports
- Readable internal diagnostic register
- TTL signal interface

## Block Diagram



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## 1.0 Signal Description

Pin Name	I/O	No.	Description
RESET	I	1	<b>RESET:</b> When this input is released, the initialization sequence begins.
ABORT	O	1	<b>ABORT:</b> When asserted, it indicates that a failure was detected. $\overline{\text{ABORT}}$ is negated by asserting Reset.
PIPE	I	1	<b>PIPE:</b> When $\overline{\text{PIPE}}$ is negated (non-pipelined timing), at the Client ports, both the symbol and type fields correspond to each other during the same clock cycle. When $\overline{\text{PIPE}}$ is asserted (pipelined timing), the timing of the Type field leads by one clock at the receive port and trails by one clock at the transmit port. (The type and symbol fields are pipelined.)
NODE0	I	1	<b>NODE0:</b> When asserted, the controller is configured as having Node ID 0. Node 0 is responsible for governing the initialization process in the ring.
RGCLK	I	1	<b>RING CLOCK:</b> This clock input is the time-base for the ring interface. A clock input should be present when the CKSRC pin is asserted. When CKSRC is negated, RGCLK should be tied low.
CKSRC	I	1	<b>CLOCK SOURCE:</b> Designates the source of the ring clock. When asserted, RGCLK is the clock source used for the Ring interface. When this pin is negated, the clock is derived from the differential UpCLK.
CLKOUT	O	1	<b>CLOCK OUT:</b> If CKSRC is asserted, then CLKOUT is frequency-locked to the RGCLK. If CKSRC is negated, then CLKOUT is frequency-locked to the UpCLK.
UpCLK	I	2	<b>UPSTREAM CLOCK:</b> This LVDS input clock comes from the neighbor upstream node and drives the ring interface when CKSRC is negated.
UpSS[5:0]	I	12	<b>UPSTREAM SUB-SYMBOL:</b> These 6 LVDS inputs for the Ring interface carry the divided 42-bit symbol from the downstream port of the previous node.
DnCLK	O	2	<b>DOWNSTREAM CLOCK:</b> This LVDS output clock signal is derived from the clock that drives the Ring interface. The transitions on the DnSS are in phase with transitions on the DnCLK signal.
DnSS[5:0]	O	12	<b>DOWNSTREAM SUB-SYMBOL:</b> These 6 LVDS outputs for the Ring interface carry the divided 42-bit symbol for the upstream port of the next node.
TxCLK	I	1	<b>TRANSMIT CLOCK:</b> On the Client interface, all transmit port signals are synchronous to the rising edge of this clock.
TxT[1:0]	I	2	<b>TRANSMIT TYPE:</b> On the Client interface, this field defines (as head, data, frame or null) the contents of TxS: in the previous clock cycle when $\overline{\text{PIPE}}$ is asserted, pipelined timing. in the current clock cycle when $\overline{\text{PIPE}}$ is negated, non-pipelined timing.
TxS[31:0]	I	32	<b>TRANSMIT SYMBOL:</b> On the Client interface, these signals form the data path of the transmit port.
TxOK	O	1	<b>TRANSMIT OKAY:</b> On the Client interface, this is the transmit port status signal. It tells the client whether or not another non-null symbol can be accepted. Loading of non-null symbols must cease within 20 symbols of the negation of TxOK. Transmission may not resume until TxOK is reasserted.
RxCLK	I	1	<b>RECEIVE CLOCK:</b> On the Client interface, all receive port signals are synchronous to the rising edge of this clock. Except RxSTALL, which is sampled on the following edge of RxCLK.
RxT[1:0]	O	2	<b>RECEIVE TYPE:</b> On the Client interface, this field defines (as head, data, frame or null) the contents of RxS: in the next clock cycle for when $\overline{\text{PIPE}}$ is asserted, pipelined timing. in the current clock cycle when $\overline{\text{PIPE}}$ is negated, non-pipelined timing.
RxS[31:0]	O	32	<b>RECEIVE SYMBOL:</b> On the Client interface, these signals form the data path of the receive port.

## 1.0 Signal Description (Continued)

Pin Name	I/O	No.	Description
RxSTALL	I	1	<b>RECEIVE STALL:</b> On the Client interface, when RxSTALL is asserted: When $\overline{\text{PIPE}}$ is asserted, pipelined timing: RxS shall remain for the next clock cycle. When $\overline{\text{PIPE}}$ is negated, non-pipelined timing: RxT will indicate a null for the next clock cycle and RxS shall remain.
RxOE	I	1	<b>RECEIVE OUTPUT ENABLE:</b> On the Client interface, when asserted, this signal enables outputs RxS[31:0]. When negated, the RxS are TRI-STATE.
RxET[1:0]	O	2	<b>RECEIVE EARLY TYPE:</b> On the Client interface, this field identifies in advance whether the information entering the Rx Port block is a head, data, frame or null.
RxNBL [3:0]	O	4	<b>RECEIVE NIBBLE:</b> On the Client interface, it contains one of the 16 selectable fields of two readable internal areas (Diagnostics bits, RxS driver).
RxSEL [3:0]	I	4	<b>RECEIVE SELECT:</b> On the Client interface, selects one of the 16 fields appearing on the RxNBL. Codes from 0 to 7 select 4 bit fields at the current output driver of RxS, codes of 8 or above select internal diagnostics status bits.
V <sub>CC</sub>	N/A	13	<b>POWER PINS</b>
GND	N/A	29	<b>GROUND PINS</b>

**Note 1:** SignalName: The indicates that the signal is active low.

The following sections assume a 50 MHz ring clock. Note that the QR0001 has a maximum ring clock frequency of 33 MHz.

## 2.0 Basic Structure

The QuickRing Controller has two interfaces: the Ring Interface and the Client Interface. Each interface has two ports. All ports on the QR0001 are unidirectional so that incoming and outgoing data can be queued simultaneously.

The two **Ring interface** ports are:

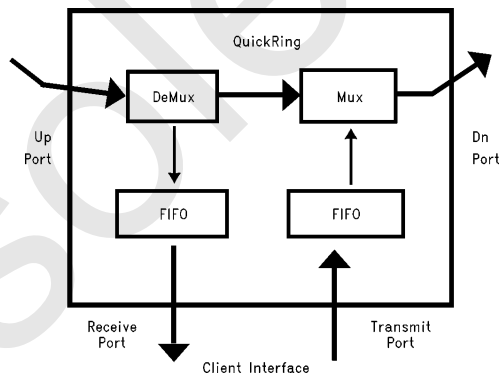
1. upstream port for arriving traffic,
2. downstream port for departing traffic.

The Ring Interface forms the link to other nodes on the point-to-point QuickRing architecture. QuickRing connects multiple nodes by attaching the upstream port of each node to the downstream port of another node. The ring ports, upstream and downstream, are 6 bits wide plus a clock. The ring interface is implemented using LVDS drivers and receivers. The Ring Interface signals are not accessible from the board except through the controller. The on board logic connects to the QR0001 controller via the Client interface.

The two **Client interface** ports are:

1. the transmit port for locally generated symbol streams, and
2. the receive port for locally-absorbed symbol streams.

The transmit and receive ports have a 32-bit data path which use TTL compatible I/Os. The Transmit (Tx) and Receive (Rx) ports each have a separate clock plus control signals for information flow. Also, some QR0001 internal status bits can be read through the receive interface. All on board circuitry interfaces to the Client transmit and receive ports, never to the Ring ports.

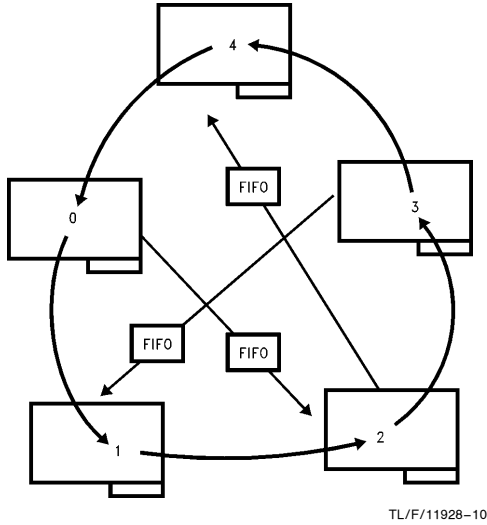


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**FIGURE 2.1. The QuickRing Controller has four ports**

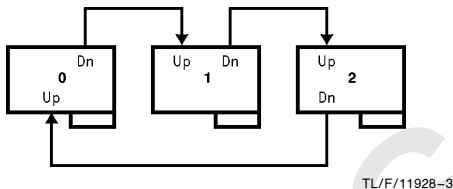
QuickRing transmits data streams between nodes on the ring. The goal of QuickRing is to pipeline data streams and not just to facilitate memory access. Imagine connecting two cards together via a FIFO chip. One card can load data into its side of the FIFO, and the other card can extract data from the other side of the FIFO. QuickRing is logically equivalent to placing a large FIFO between pairs of QuickRing nodes. Cards connected through QuickRing form a ring. Refer to *Figure 2.2*.

## 2.0 Basic Structure

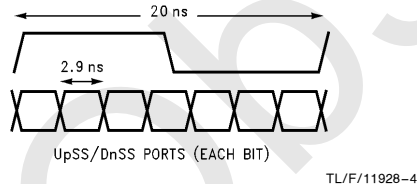


**FIGURE 2.2. Logical Data flow (QuickRing Virtual FIFOs)**

Figure 2.3 shows that data physically moves in a ring from card to card, data traverses the ring until it arrives at the final destination. Physical data flow is unidirectional, and propagates downstream between nearest neighbors.



**FIGURE 2.3. Physical Data Flow in QuickRing**



**FIGURE 2.4. A Sub-Symbol is Multiplexed Every 2.9 ns**

The ring, formed by connecting Up and Dn ports of adjacent QuickRing controllers, carries one 42-bit symbol every 20 ns. The 42-bit symbol is composed of:

- 32 bits of data,
- 1 Frame bit,
- 2 control bits and
- 7 bits of EDC.

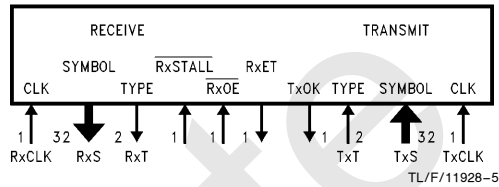
To transmit 42 bits in 20 ns, QuickRing divides the 42-bit symbol into 7 sub-symbols, each sub-symbol is 6 bits wide. The controller then multiplexes the sub-symbols onto the 6 LVDS pairs on the downstream port. A 7th LVDS clock signal, at 50 MHz (maximum), accompanies every 42-bit symbol transmission. Refer to Figure 2.4.

## 3.0 Client Interface

### 3.1 Type and Symbol Fields at the Client Ports

The QuickRing client can multiplex multiple independent data streams onto and from the transmit (Tx) and receive (Rx) ports of the controller. The type fields (TxT[1:0], RxT[1:0]) distinguishes the contents of the symbol (main data) fields (TxS[31:0], RxS[31:0]). The type field identifies the nature of the symbol field information at the 32-bit ports as: head, data, frame or null.

The transmit port can be thought of as the input to a bank of fast, deep FIFOs, connected to other nodes on the ring. The receive port can be treated as the output of the bank of FIFOs connected to other nodes on the ring. Figure 3.1 illustrates the controller's client interface.



**FIGURE 3.1. Client Ports of a QuickRing Controller**

### 3.2 Client Transmit Port

Figure 3.2 shows the block diagram of the transmit port. The transmit block of QR0001 is formed by: Tx Port, Tx Resynchronizer, Tx Router, and 3 independent FIFOs. All of these blocks form the transmit pipeline.

1. The Tx Port is the first stage into the transmit pipeline. The Transmit port is a 4 deep pipeline.
  2. The Tx Resynchronizer is a 32-deep asynchronous FIFO in the path between the Tx Port and the Tx Router.
- Note:** The Tx Resynchronizer will handle the frequency disconnect between the Tx Port and ring logic. This function will be implemented on the next QuickRing device—QR1001.
3. The Tx Router directs the streams to the appropriate channel efficiently (described later).
  4. FIFOs X and Y are meant for handling one independent high bandwidth stream each, and the LB (Low Bandwidth) FIFO is meant for low bandwidth transmissions. The FIFOs contain the data/frame part of the client stream. (The Head information is held in a separate holding latch internally.)

The sole purpose of providing two normal (high bandwidth) FIFOs (X and Y) is so that the client may switch from transmitting one stream to another without slowing down or wasting available ring bandwidth during the context switch.

On release of  $\overline{\text{RESET}}$  any payload symbols at the transmit port are ignored until the first head symbol is presented at the input of the Tx Port. QR0001 always checks for consecutive heads and ignores all redundant heads. The type and symbol fields are latched internally according to the timing specified by the state of the PIPE signal.

When the client starts a transmission, it writes a head followed by a stream of payloads. QR0001 receives these symbols through the transmit port and directs them to either the X, Y or LB FIFO. Any head symbol with the CONN (see Section 3.6) field equal to 1 is always routed to the LB FIFO, as is every payload symbol following such a head. Any other head with the CONN field equal to 0 and all payloads following such a head are routed to either the X or Y FIFO.

### 3.0 Client Interface (Continued)

QR0001 can handle **one Independent data stream through each of the X and Y FIFOs, a total of two streams at once**. Even if the FIFO is not full, the FIFO will store data associated only with a single head. Multiple data streams with various heads will not be held in a single FIFO. The subsequent data streams, with different heads, will be held in the Tx pipeline, until either FIFO X or Y empties, and the data (with the different head) is allowed to further proceed in the pipeline.

5. The LB FIFO. Several streams with different heads can flow through the LB FIFO at one time. When several payloads are loaded, following a signal head, a head will be generated for each payload.

For all transmissions, low bandwidth or normal, QR0001 will keep TxOK asserted for as long as there is space for 20 or more symbols in the transmit pipeline. As soon as the transmit pipeline has space for **only 20** more symbols, TxOK negates. The initial negation of TxOK indicates to the client interface that it must stop transmitting non-null symbols soon. TxOK is the only handshake mechanism at the transmit port. If TxOK asserts again, the count is voided and the client can write to the TxPort as many symbols as it wants. If TxOK negates again, the client must stop writing non-null symbols within 20 valid transactions.

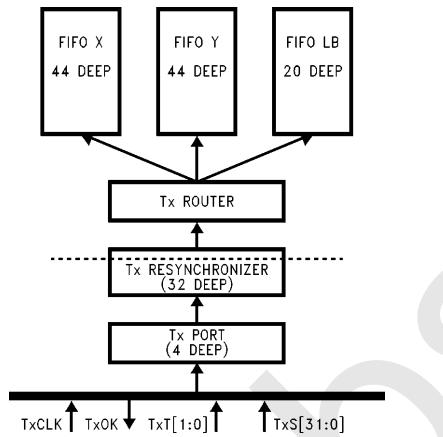


FIGURE 3.2. Tx Port Client Interface

The client may pause transmission at any time by presenting the null symbol code to the transmit port.

When the client interface wishes to begin transmission of a data stream, the client first writes a head (H) to the transmit port. From then on, every payload symbol (type = data or frame) sent to the transmit port is assumed to belong to the stream identified by the head. The data stream that the client writes at the transmit port is unbounded. However, if a new head is written to the transmit port, the data stream that follows is associated with the new head. If at any time the client is not prepared to transmit either a payload or a new head, a null symbol (N) may be introduced into the transmit data stream. Null symbols do not propagate into the QR0001 QuickRing controller. Logically distinct data streams can be multiplexed together and loaded into the QR0001 transmit port. The client is free to switch between source streams at its convenience, as long as it introduces a new head when the switch occurs.

Figure 3.3 shows how three independent streams (high bandwidth) may be multiplexed from the Client Transmit Port into the QuickRing controller. Stream Q goes first, sending 2 payloads. It is followed by 1 payload from stream R, then by 2 payloads from stream S. Two more symbols from stream Q are sent, etc.

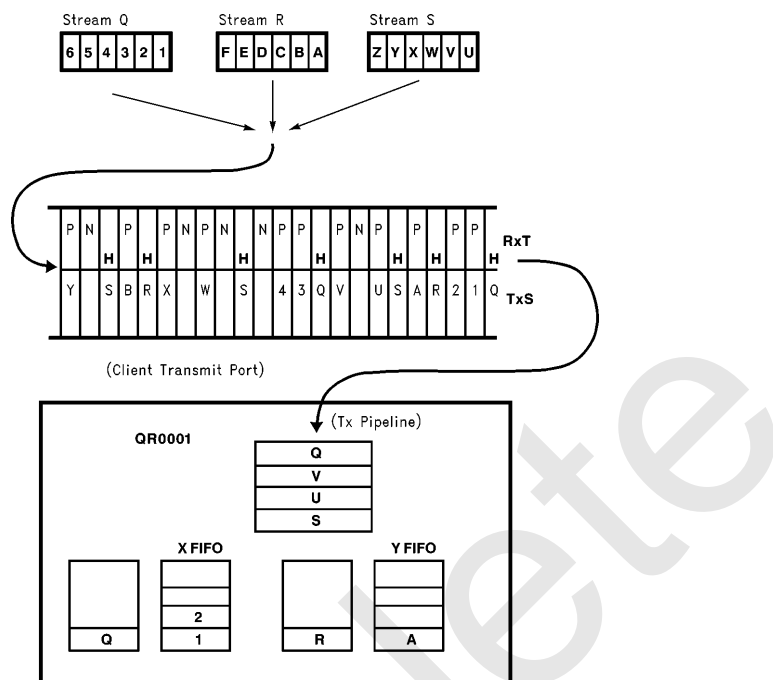
### 3.3 Transmit Port Timing Relationships

When  $\overline{\text{PIPE}}$  is asserted (low voltage level) the type field, TxT, accompanying the symbol field, TxS, is loaded into the controller one clock cycle after the symbol that it identifies. See Figure 3.4. When a symbol is presented on TxS at time  $t$ , then the corresponding code is presented on TxT at time  $t + 1$ . The purpose of delivering the TxT field one clock cycle after the symbol is so that a simple, synchronous state machine has one full clock cycle to compute the TxT code without using external latches on the symbol field.

When  $\overline{\text{PIPE}}$  is negated (high voltage level), the type field TxT accompanying the symbol field TxS is loaded into the controller during the same clock cycle as the symbol it identifies. Refer to Figure 3.5.

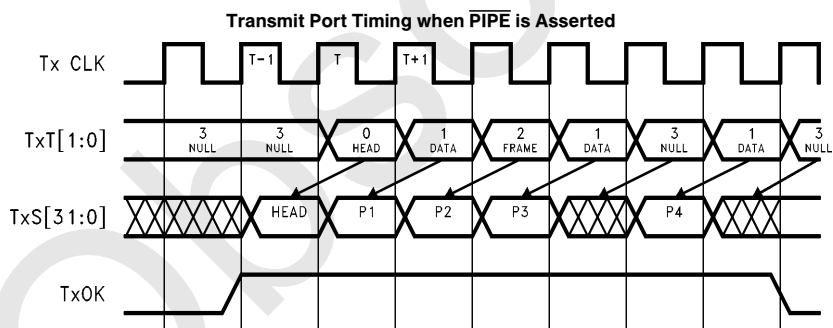
The TxOK function and timing remains unchanged regardless of the level of the  $\overline{\text{PIPE}}$  signal. Giving a 20 symbol warning that transmission of non-null symbols may need to cease.

### 3.0 Client Interface (Continued)



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**FIGURE 3.3. Logically Distinct Streams of Data can be Multiplexed Into the Tx Port**

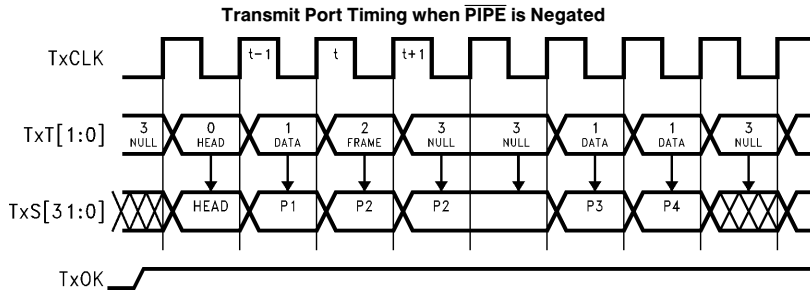


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**FIGURE 3.4. When  $\overline{\text{PIPE}}$  is asserted, the Type Field Lags the Symbol Field by One Clock Cycle at the Transmit Port**

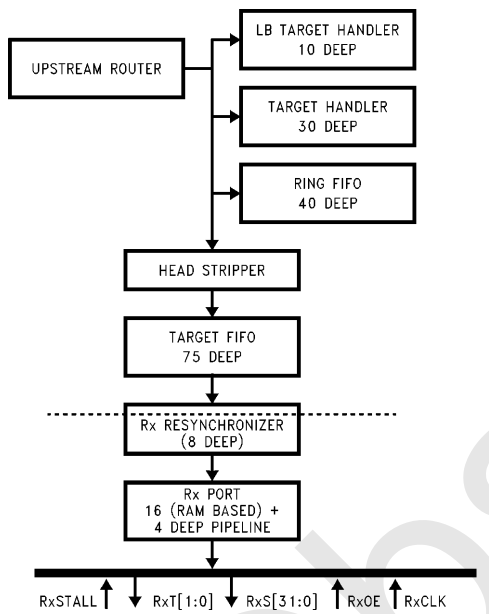


### 3.0 Client Interface (Continued)



**FIGURE 3.5. When  $\overline{\text{PIPE}}$  is negated, the Type Field and the Symbol Field are Loaded during the Same Clock Cycle**

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**FIGURE 3.6. Rx Port Client Interface**

#### 3.4 Client Receive Port

Figure 3.6 shows the QR0001 receive block and part of the forwarding path.

1. The Upstream Router, LB Target Handler, Target Handler, and the Ring FIFO are part of the forwarding path. The LB Target Handler processes LB vouchers targeted to this node into tickets. These tickets are forwarded to the source node through the downstream port. The Target Handler processes vouchers targeted to this node into tickets. These tickets are forwarded to the source node through the downstream port.

The Ring FIFO stores incoming data from the upstream port that is intended to be forwarded to other nodes on the ring, when the downstream pipe is allocated to launching local data generated by this node.

Now the receive block:

2. The Head Stripper removes all heads except those identifying the beginning of a stream.
  3. The Target FIFO reserves space for 3 normal packets and 6 LB packets.
  4. The Rx Resynchronizer is an 8-deep FIFO in the path between Target FIFO and the Rx Port.
- Note:** The Rx Resynchronizer will handle the discontinuity between the client interface and the ring logic of the controller. This function will be implemented on the next QuickRing device—QR1001.
5. The Rx Port is the last stage between a data stream and the client interface.

On release of Reset: the first two non null symbols that appear at the RxS[31:0] are the node ID of the controller, and the largest/maximum ID number on the ring. (See Section 9.1.)

RxET alerts the client interface, up to 20 symbols prior to the output stage, the type of data entering the receive pipeline. The RxT, when  $\overline{\text{PIPE}}$  is asserted, leads by one clock the symbol that it identifies; thus, giving the client a one clock cycle advance notice of the symbol about to appear at the RxS[31:0]. The client may choose to stall the symbol at RxS[31:0] if desired.

At the Rx Port, a contiguous data stream is unbounded, and data belonging to the same head is marked by a single initial head appearance. At the Rx Port there is no evidence of a packet. A new head will appear only when there is a change in data stream. A long data stream transmitted in multiple packets from one node to another, will appear at the Rx Port as a single head followed by a long data stream, unless broken by a different stream from a third node.

In cases where one target node is the subject of multiple transmissions from several nodes, multiple streams, marked by head symbols, will appear multiplexed at the Rx Port. The same will occur if one source node is sending different streams to the same target. A stream is treated as a different stream if the 32-bit head symbol varies in at least one bit.

## 3.0 Client Interface (Continued)

### 3.5 Receive Port Timing Relationships

When  $\overline{\text{PIPE}}$  is asserted (low level), the type field, RxT, at time t indicates the type of symbol presented at the output, RxS, at time t+1. See *Figure 3.7*. This is true as long as  $\overline{\text{RxSTALL}}$  is negated.

If  $\overline{\text{RxSTALL}}$  is asserted when  $\overline{\text{PIPE}}$  is asserted (pipeline timing mode):

1. **The RxS[31:0] output will stall at the first non-null symbol encountered in the pipeline after  $\overline{\text{RxSTALL}}$  is asserted.** The symbol on RxS will persist through next clock cycle unless it corresponds to a null symbol. The  $\overline{\text{RxSTALL}}$  input signal is only capable of holding a non-null symbol at the RxS output.

The client may need to examine some symbols within the symbol stream in order to determine their disposition. It is highly desirable to do so without employing added data path buffering external to the controller. QuickRing allows the client to examine the contents of the symbol at the RxS output through a combination of  $\overline{\text{RxSTALL}}$ , RxSEL and RxNBL, even while the RxS output drivers may be disabled.

To further aid in the receive stream management, the symbol type field just entering the Rx Port Block of the receive pipeline is visible on RxET. Thereby the client can preview the symbol type in the receive pipeline before it appears on the RxS outputs. Thus it is possible to detect the presence of a head, data, or frame in the pipeline even if up to 19 more symbols are stored ahead of it.

When  $\overline{\text{PIPE}}$  is negated (high level), then the value of the type field RxT, TxT at time t corresponds to the value of the symbol field at the same time t. (See *Figure 3.8*.) When two QuickRing controllers are connected to form a bridge, the TxOK is connected to  $\overline{\text{RxSTALL}}$  of the other controller. (Currently, an external flip-flop may be needed to satisfy the setup/hold times.)

If  $\overline{\text{RxSTALL}}$  is asserted when  $\overline{\text{PIPE}}$  is negated (high level), at the next positive edge of clock:

1. RxT is forced to Null and
2. The RxS[31:0] persists.

To summarize the Client Port Timing:

At the Rx Port, a non-null symbol remains valid at the RxS output in the presence of  $\overline{\text{RxSTALL}}$ .

At the Tx Port, when TxOK negates it indicates that the FIFO is nearly full and the client must stop transmission within 20 non-null symbols.

The  $\overline{\text{PIPE}}$  input determines how the type fields, RxT and TxT, identify a symbol as it appears at RxS and TxS respectively.

At the receive port, many different arriving streams may be multiplexed together. Every switch to a new stream context is marked by a new head symbol. The multiplexed stream that is loaded into a controller at a source node is probably different than the de-multiplexed stream that arrives at the target node.

The QuickRing protocol does not preserve the order of multiplexed streams, but it does preserve the first-in-first-out ordering of each individual stream.

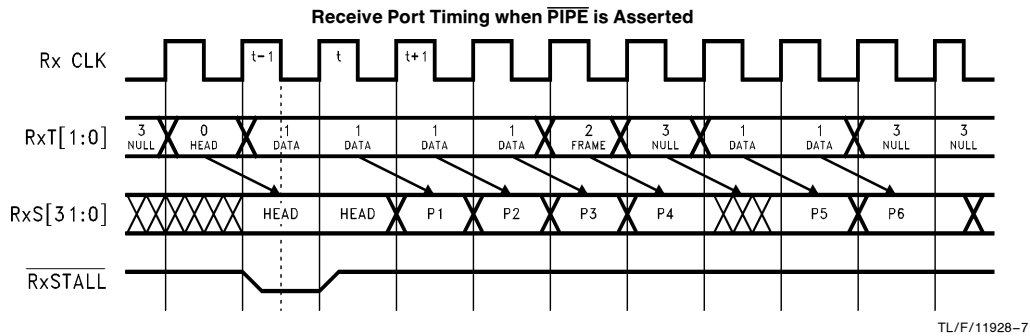
*Figure 3.3* relates to *Figure 3.9*. It shows that even though stream Q was loaded first, in *Figure 3.3*, stream R, arrives first, in *Figure 3.9*. Notice that at the output, the order within each individual stream is preserved.

#### 3.5.1 Client Receive Port Interface Recommendations (PIPE asserted)

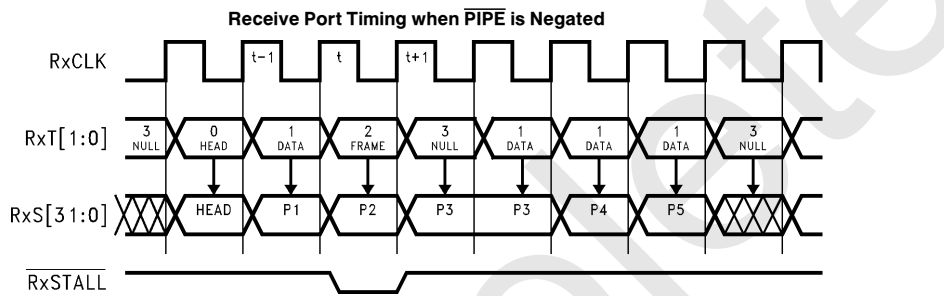
It is recommended, when interfacing to the Client Receive Port, to hold  $\overline{\text{RxSTALL}}$  negated during normal operation. When the Client interface detects a Non-Null type, it may assert  $\overline{\text{RxSTALL}}$  during the next clock cycle to stall that particular symbol and the next Non-Null type (if available). See *Figure 3.10*.

BE AWARE that if  $\overline{\text{RxSTALL}}$  is asserted during a clock cycle of a NON-NULL Type that follows (later in time) a NULL type, the Receive Client interface will stall a NULL type for the next clock cycle. A Null Type will be inserted into the next clock cycle even if the Receive FIFO contains a NON-NULL type next. This could reduce the performance of the receive client interface by half. See *Figure 3.11*.

### 3.0 Client Interface (Continued)

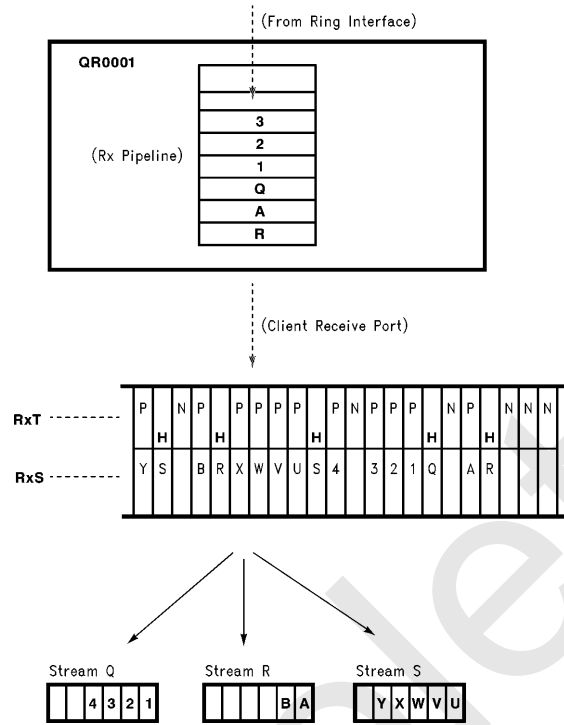


**FIGURE 3.7. When  $\overline{\text{PIPE}}$  is asserted, the Type Field Leads the Symbol Field by one Clock Cycle at the Receive Port**



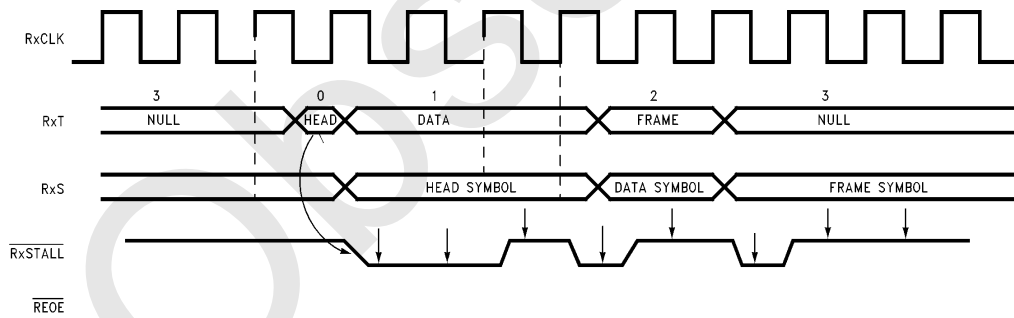
**FIGURE 3.8. When  $\overline{\text{PIPE}}$  is negated, the Type Field and the Symbol Field are Loaded during the same Clock Cycle**

### 3.0 Client Interface (Continued)



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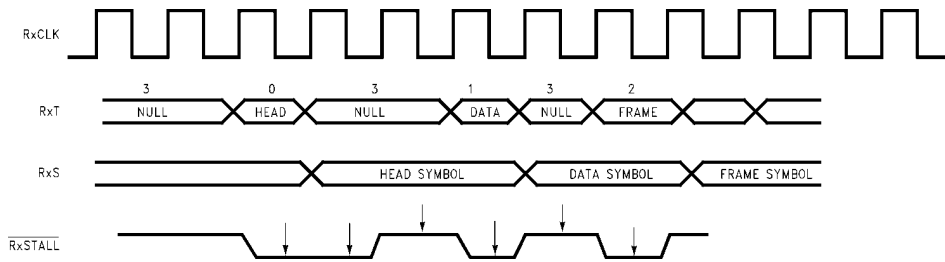
FIGURE 3.9. The Individual Ordering of each Stream is Preserved



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FIGURE 3.10. Holding Head Symbols for 2 Clocks and Holding Data and Frame Symbols for 1 Clock each

### 3.0 Client Interface (Continued)



**FIGURE 3.11. Null Type is Inserted when RxSTALL is Asserted during the same Clock Cycle as a Null Symbol (i.e., in above Figure Null is Inserted after Head Symbol, see also Table 3.0 State #9)**

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**TABLE 3.0. Client Receive Port State Table (Pipeline Timing)**

	Input		Present State			Next State			Output		
	RxSTALL	T[ ]	RxT[ ]	Nullout	Stalled	RxT[ ]	Nullout	Stalled	Next	RxS[ ]	
1	F	Null	Null			Null	T	F	F	Sx	1,2,5,6
2	F	Ty	Null			Ty	T	F	F	Sx	3,4,9
3	F	Null	Ty			Null	F	F	T	Sy	1,2,10,11
4	F	Tz	Ty			Tz	F	F	T	Sy	3,4,8
5	T	Null	Null	T		Null	T	T	F	Sx	1,2,5,6
6	T	Ty	Null	T		Ty	T	T	F	Sx	3,4,9
7	T	Ty	Null	F	T	Null	F	T	F	Sx	1,2,7,11
8	T		Ty	F		Ty	F	T	F	Sx	3,4,8
9	T		T	T		<b>Null</b>	F	T	T	Sy	1,2,7,11
10	T	Ty	F	F	F	Ty	T	T	F	Sx	3,4,9
11	T	Null	F	F		Null	F	T	F	Sx	1,2,7,11

RxSTALL	Chip input signal which holds non-null data at RxS[ ].
T[ ]	(Not externally observable.) The type of symbol which should appear on RxT[ ] during the next clock cycle unless the symbol marked by RxT[ ] is waiting behind another stalled symbol at RxS[ ].
RxT[ ]	The type code for the symbol that should appear at RxS[ ] during the next clock cycle, unless RxS[ ] is currently non-null and is being stalled by RxSTALL.
Nullout	(Not externally observable.) A state variable that is set to TRUE when the current value of RxS[ ] is volatile—not stallable and subject to being overwritten by an arriving non-null symbol.
Stalled	(Not externally observable.) A state variable that takes on the value of RxSTALL during the previous clock cycle.
Next	(Not externally observable.) The state machine output that loads the RxS[ ] output with the next non-null value in the pipeline.
RxS[ ]	The 32-bit symbol output bus of the Receive Port.
T	TRUE.
F	FALSE.
Null	The symbol type code representing the absence of a symbol.
Ty, Tz	Symbol type codes for a non-null symbol.
Sx	The value of RxS[ ] unchanged from the previous cycle.
Sy	The new value of RxS[ ] whose symbol type code appeared on RxT[ ] during the previous clock cycle.

The state table on the previous page describes the behavior of the QR0001 Receive Port. For convenience each table row has been numbered on the left-hand side, and each of the possible next-case rows is listed on the right-hand side. Following the state table is a description of the input, output, and state variables, as well as of the entries within the state table.

Row number 9 of the state table shows that the next state always indicates a null symbol on RxT[ ], regardless of whether or not a non-null symbol is pending behind symbol Sy. This is an *inefficient but legal* behavior, as no symbol is

lost. Unfortunately, until RxSTALL is released, the Receive Port will remain in rows 9, 7, and 11, none of which will allow the arrival of the next non-null symbol to be detected on RxT[ ].

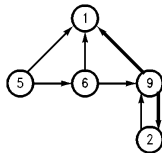
Entry number 10, however, represents a condition where a non-null symbol can arrive at, and disappear from, RxS[ ] without the possibility of being stalled. This represents *illegal behavior* of the QR0001 Receive Port. Entry into the condition represented by row 10 must be handled specially or system data loss will result.

### 3.0 Client Interface (Continued)

#### Workarounds for No-Stall Bug

There are three alternatives available to work around the no-stall bug: (1) Release  $\overline{\text{RxSTALL}}$  for one clock cycle only when  $\text{RxT}[]$  takes on a non-null value, leaving  $\overline{\text{RxSTALL}}$  asserted at all other times; (2) build a client system that is guaranteed not to require that any symbol remain on  $\text{RxS}[]$  for more than two clock cycles; or (3) provide an external latch to save symbols that might have been lost due to entry to row 10, and stall the next symbol in row 7 or 11 until the external latch can be read.

**Alternative #1.** Leave  $\overline{\text{RxSTALL}}$  normally asserted. This is the easiest method. It restricts the Receive port to rows, 1, 2, 5, 6, and 9.  $\overline{\text{RxSTALL}}$  is released only to enter rows 1 and 2. This is easily accomplished by releasing  $\overline{\text{RxSTALL}}$  in response to each non-null value, but only when that value is no longer needed at  $\text{RxS}[]$ .  $\text{RxT}[]$  will remain non-null for only one clock cycle, and this event will have to be remembered by the client state machine. Unfortunately, because the next state result of row 9 does not update  $\text{RxT}[]$ , the fastest that a client may receive data is once every other clock cycle. If there is always another symbol ready in the pipeline, then the Receive Port will toggle between rows 9 and 2, and  $\text{RxS}[]$  will be updated only on the exit from row 9.



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**Alternative #2.** Design a client system that can always consume a received symbol within two clocks. This may be impractical, but if the client system fits this description, then there is no problem. This is because the next state of row 10 is entered in order to stall a symbol that just appeared upon the exit from row 3, and row 10 preserves the symbol for exactly one more clock cycle. Every next-case row out of row 10 will advance  $\text{RxS}[]$  to the next symbol, so the un-stallable symbol always appears at  $\text{RxS}[]$  for exactly two clock cycles.

**Alternative #3.** Provide external storage for the volatile symbol, and stall the next symbol at  $\text{RxS}[]$  until the saved copy can be used. The only entrance to row 10 is from row 3. External logic must monitor the interface for the transition from row 3 to row 10 or 11, and must both save the un-stallable symbol and hold  $\overline{\text{RxSTALL}}$  asserted until the external copy can be used. This solution requires that external logic emulate the QR0001 Receive Port state machine. Although the  $\text{T}[]$  input variable and the Nullout and Stalled state variables are not observable on output pins of the chip, it is possible to compute them externally. An external state machine can deterministically compute the previous state and the value input  $\text{T}[]$  that helped cause it. Although this information is available one cycle late, there is time to stall the next symbol until the no-stall symbol register is being freed up.

The advantage of alternative 1 is its simplicity, if it is not necessary to receive symbols more often than once every other clock cycle. The advantage of alternative 2 is that, if it happens to describe your system (if it's free), then you will not encounter the no-stall bug. The advantage of alternative 3 is that the client can keep up with high-bandwidth received streams that deliver symbols on every clock cycle.

#### 3.6 Client Interface Field Definitions

Table 3.1 shows the symbol field definitions for the Tx and Rx ports. Refer to Section 3.13 for details.

**TABLE 3.1. Tx and Rx Port Symbol Field Definitions**

Field	Descriptions
Type[1:0]	At the client ports, distinguishes head, data, frame, and null.
CONN[1:0]	The connection code (CON[1:0]) provides two types of transmission, normal and low bandwidth. Low-bandwidth streams are transmitted with higher priority.
TRGT[3:0]	The target field contains the node ID of the target of the associated payload.
SRCE[3:0]	The source field contains the node ID of the source of the associated payload.
HOP1[3:0] HOP2[3:0] HOP3[3:0] HOP4[3:0] HOP5[3:0]	They distinguish between unique streams whose source-to-target routes are identical. In a multiple-ring topology, they supplement source and target ID fields to route streams as they hop from ring to ring (See section on Ring of Rings).

At the client ports ACCess field should be [00]. The ACC field is valid only in the ring ports. Refer to Sections 4.7 and 4.13 for more details.

Table 3.2 shows the values of the connection field (CONN[1:0]). If a LB connection is requested, QuickRing parcels the data or frame symbols presented at the Tx Port and transmits every payload in 2 symbol ring packets, 1 head and 1 payload.

**TABLE 3.2. Connection Field Definitions**

CONN[1:0]	Name	Description
0	Normal	Queue and accumulate symbols from the same stream at will, to maximize system efficiency and minimize system load.
1	Low Bandwidth (LB)	Do not concatenate with other data symbols from the same stream. Results in two symbol packets, head and payload.
2	N/A	Reserved
3	N/A	Reserved

#### 3.7 Client Type Fields

The  $\text{TxT}[1:0]$  and  $\text{RxT}[1:0]$  fields are the type fields at the transmit and receive ports, respectively. They are encoded as shown in Table 3.3. Each 32-bit symbol written or read from the client ports is associated with one type field.

### 3.0 Client Interface (Continued)

**TABLE 3.3. Client Type (TxT/RxT) Field Definitions**

T [1]	T[0]	Name	Description
0	0	Head	Associated symbol is a head symbol
0	1	Data	Associated payload symbol is a data symbol
1	0	Frame	Associated payload symbol is a frame symbol
1	1	Null	No associated symbol

#### 3.8 Transmit Port Head Fields

A head symbol must be loaded into the transmit port whenever the client wants to start a transmission, or when the context of the loaded symbols is switched to another stream. Redundant heads are acceptable to the controller transmit port. If multiple heads are loaded without intervening data or frame symbols, then all but the last head are ignored. The transmit port evaluates the connection, target, and all hop fields. The controller adds its own ID to the source field internally, based on the local node ID value that was set during initialization. The ACCess field is ignored and should be set to zero by the client. Table 3.4 shows the format of a head symbol that the local client must load into the Tx Port to establish a connection.

**TABLE 3.4. Transmit Port Head Fields**

TxT[1:0]	TxS[31:0]									
1:0	31:30	29:28	27:24	23:20	19:16	15:12	11:8	7:4	3:0	
Type	Acc	Conn	Src	Trgt	HOP					
[0]	XX	Conn	XXXX	Trgt	Hop1	Hop2	Hop3	Hop4	Hop5	

#### 3.9 Receive Port Head Fields

The receive port head symbol format contains the same fields as are found in heads at the transmit port, but are shifted from their original positions when they exit the receive port. The purpose is to support routing of streams in multiple-ring topologies. Head symbols only appear at the receive port when there is an actual change of head. Redundant head symbols are always deleted. Head symbols at the receive port hold valid information in the connection, source, target, and all hop fields. The ACCess field is undefined and should be ignored by the client.

Table 3.5 shows the format of the head field at the receive port of the controller.

**TABLE 3.5. Receive Port Head Fields**

RxT[1:0]	RxS[31:0]									
1:0	31:30	29:28	27:24	23:20	19:16	15:12	11:8	7:4	3:0	
Type	Acc	Conn	Trgt	HOP						Src
0	XX	Conn	Trgt	Hop1	Hop2	Hop3	Hop4	Hop5	Src	

#### 3.10 Payload Symbols at the Rx and Tx Ports

Payload symbols at the transmit or receive ports follow the head symbol that identifies them. A payload consists of a sequence of data and/or frame symbols that are distinguished by a 1 or 2 in the accompanying type field, refer to Table 3.6. The identification of a frame or data symbol is

encoded in the Type field at the Tx and Rx port. If the type field has a value of 1, it is a data symbol, and if the value is 2, then it is a frame symbol. The type field at the receive port leads the symbol field that it identifies by one clock cycle, and at the transmit port it lags the symbol field by one clock, when PIPE is asserted. However, if the controller is in non-pipelined timing, PIPE is negated, the type field corresponds to the symbol at the same clock

**TABLE 3.6. Payload Symbols at Tx/Rx Ports**

Type[1:0]	Tx/Rx S[31:0]
1	DATA. User Defined Information
2	FRAME. User Defined Information

#### 3.11 Null Symbols at the Rx and Tx Ports

The lack of a head symbol or payload symbol is indicated, at the Rx port, by null symbols whose type field is 3, and whose other bits are undefined outputs or don't care inputs. At the Tx port, if a head or payload is not ready to be transmitted, a null symbol code should be presented at the TxT. The value of the type fields at the client ports is as indicated in Table 3.7.

**TABLE 3.7. Null Symbol Format**

Type[1:0]	Tx/Rx S[1:0]
3	NULL. Don't Care

#### 3.12 The HOP fields and the Uniqueness of Symbol Streams

The identity of a symbol stream is fixed by the combination of the connection, source, target, and hop fields. If the heads of symbol streams differ in any of these fields, then they represent different symbol streams.

The symbols of a unique stream will always arrive in order. Multiple streams targeted at the same node may arrive interleaved. The interleaving will always be indicated by an appropriate head symbol, identifying the switch in stream context.

The Hop Fields were created to route packets through bridges in multiple ring topologies. In single ring topologies they have the function of identifying different streams. The hop fields can be used to distinguish between 2<sup>20</sup> different data streams in a single ring. However, in multiple ring topologies, every time a bridge is crossed, one hop field is used. Therefore, it is lost for identifying unique data streams. Table 3.8 shows the hop field locations at the transmit port and Table 3.9 shows the hop fields at the receive port.

If the particular node is a bridge to another ring, the PIPE signal should be negated, high voltage level. The HOP fields rotate the same regardless of the state of the PIPE input.

The actual rotation of the Source, Target, and HOP fields occurs at the client receive port, see Tables 3.8, 3.9. The HOP fields rotate between the Transmit Client and the Receive Client as follows (from Receive Client perspective):

- Source bits (27:24) shift to bit field (3:0)
- All other HOP fields (including Target field) move up one HOP field to the next more significant 4-bit positions (Ex HOP 5 moves from (3:0) → 7:4).

Given this information the system interface should be able to determine how the Source, Target and HOP fields rotate up to a Ring of Rings architecture including 5 HOPs.

### 3.0 Client Interface (Continued)

When the Client Port Receives a data stream the head contains the path taken by the stream to reach this particular target. To look at the Head and determine where the source is and how many HOPs the stream encountered requires knowledge of the ring topology. It is assumed that during the initialization process each node will build up a table of addresses of all the NODEs in the system. When a Head is received, it can be compared to the addresses in the table to determine the source of the data stream. All un-used HOP fields may be used as Stream ID.

**TABLE 3.8. HOP Fields at the Tx Port**

27:24	23:20	19:16	15:12	11:8	7:4	3:0
Src	Trgt	Hop 1	Hop 2	Hop 3	Hop 4	Hop 5

**TABLE 3.9. HOP Fields at the Rx Port**

27:24	23:20	19:16	15:12	11:8	7:4	3:0
Trgt	Hop 1	Hop 2	Hop 3	Hop 4	Hop 5	Src

Obsolete



### 3.0 Client Interface (Continued)

#### 3.13 Summary of Client Port Field Formats

TABLE 3.10. Client Port Field Formats

Tx Port Head Field									
Type	Acc	Conn	Src	Trgt	HOP				
TxT[1:0]	TxS[31:30]	TxS[29:28]	TxS[27:24]	TxS[23:20]	TxS[19:16]	TxS[15:12]	TxS[11:8]	TxS[7:4]	TxS[3:0]
0	XX	Conn	XXXX	Trgt	HOP 1	HOP 2	HOP 3	HOP 4	HOP 5

Rx Port Head Field									
Type	Acc	Conn	Trgt	HOP					Src
RxT[1:0]	RxS[31:30]	RxS[29:28]	RxS[27:24]	RxS[23:20]	RxS[19:16]	RxS[15:12]	RxS[11:8]	RxS[7:4]	RxS[3:0]
0	XX	Conn	Trgt	HOP1	HOP2	HOP3	HOP4	HOP5	Src

Tx and Rx Ports Payload Symbols	
T[1:0]	Tx/Rx S[31:0]
1	DATA. User Defined Information
2	FRAME. User Defined Information

Tx and Rx Port Null Symbols	
T[1:0]	Tx/Rx S[31:0]
3	Null. Don't Care

Node ID Format		
RxT[1:0]	RxS[31:28]	RxS[27:0]
non-null	Node ID	111111.....1

Max ID Format		
RxT[1:0]	RxS[31:28]	RxS[27:0]
non-null	Max ID	111111.....1

#### 3.14 Readable Registers

The client can read the two internal registers, Diagnostics Register and Receive Symbol Register at any time, through inputs RxSEL[0:3] and outputs RxNBL[0:3]. The RxS register can also be read while RxSTALL is asserted. RxSEL[0:3] selects a 4-bit field within the 32-bit internal registers and shows that field on the RxNBL[0:3] outputs. Diagnostic error status bits [18:8] will remain latched until the Quick Ring is reset.

TABLE 3.11. Diagnostics Register (Read Only)

31:19	18:12	11:8	7:4	3:0
Reserved	Syndrome Word: S[6:0]	Error Status	MaxID	Node ID

**Node ID:** Address of the Node.

**MaxID:** Largest ID on the ring.

**Error Status:** Individual bits are set depending on the origin of the error.

**Bit 8** is set due to an EDC detection.

**Bit 9** is set due to an Abort symbol received at the upstream port.

**Bit 10** is set due to an error in the packets sequence, i.e., two consecutive heads. (Detected on the upstream port of the ring.)

**Bit 11** is set due to an invalid address detected (on the ring).

**Syndrome Word:** Points to the bit in error detected through EDC. All zeros if no error(s).

**Reserved:** Reserved for future expansion.

### 3.0 Client Interface (Continued)

**TABLE 3.12. Receive Symbol Register (Read Only)**

<b>31:0</b>
The most recent 32 Bits of the RxS received.

Table 3.13 gives the decode for reading the various register bits.

**TABLE 3.13. Register Access Decode**

RxSEL[3:0]	RxNBL[3:0]	Description
0	RxS[3:0]	
1	RxS[7:4]	
2	RxS[11:8]	
3	RxS[15:12]	
4	RxS[19:16]	
5	RxS[23:20]	
6	RxS[27:24]	
7	RxS[31:28]	
8	Diagnostics[3:0]	Node ID
9	Diagnostics[7:4]	No. of Nodes
10	Diagnostics[11:8]	Error Status
11	Diagnostics[15:12]	Syndrome Word
12	Diagnostics[19:16]	Syndrome Word*
13	Diagnostics[23:20]	Reserved
14	Diagnostics[27:24]	Reserved
15	Diagnostics[31:28]	Reserved

\*Note: Bit 19 is reserved.

#### 3.15 Error Detection (see also Section 3.16)

The error detection code (EDC) field, CB[6:0] provides redundant parity checking to verify symbol integrity. The QR0001 implements a modified Hamming code algorithm that provides Double Error Detection (DED).

To reduce latency effects, this version of the QR0001 provides the syndrome word that can be read from the Diagnostics register to show bit(s) detected in error.

**The syndrome word, S[6:0], consists of the Ex-OR of the Incoming check bits that were sent within the packet, CB[6:0], and new generated check bits for the packet (new generated, NGCB[6:0]).**

A correct EDC field is transmitted with each symbol emitted from the downstream port. Every symbol that is received at the upstream port is passed through an EDC checking circuit. Any inconsistency causes the ABORT signal to assert, and an abort symbol to be transmitted at the downstream port. EDC fields are propagated through the chip core as required to support the above described functionality. The EDC field is not visible at the client ports.

The ABORT signal will also be asserted if an illegal address or illegal sequence of symbols is detected. The symbol which triggers ABORT assertion will continue to move along the ring until reaching its target node. This requires that the ring be reset every time an abort is detected. The initial occurrence of an abort is captured in the diagnostic register. No subsequent abort will be logged (until the ring is reset).

Table 3.14 shows the matrix of data bits. An "X" indicates the bits that are "Exclusive-ORed" to generate each particular check bit. Check bit 6 is generated by "Exclusive ORing" all data and all check bits. CB[6:0] form the syndrome word.

Given a Single or Double bit error, the code has the following properties:

1. If the syndrome word: **S[6:0] is zero (0)**, then there is No Error.
2. If any of the syndrome bits: **S[5:0], is not zero (0), and S6 is zero**, then there is a Double Error. The particular bits in error can not be determined.
3. If any of the syndrome bits: **S[5:0] are not zero (0) and S6 is one**, then there is a Single Error in either the data or the check bits.

If a single bit in S[5:0] is one and S6 is one, then the corresponding CB is in error and the data is correct.

If more than 1 bit in S[5:0] is set to one and S6 is one, then the syndrome bits point to the data bit in error. See columns of Table 3.14. S[5:0] pinpoints to the position number in the mapping diagram at which bit is in error.

If all remaining bits, S[5:0] are zero and S6 is one, then CB6 is in error.

#### 3.16 QR0001 EDC Errors and Client "Abort" Pin Functionality

A bug has been identified in the abort operation. The QR0001 ABORT signal does not match the intended operation as mentioned above. The intended operation is that the following events will cause the ABORT pin to be asserted and generate an abort symbol that will propagate around

**TABLE 3.14. Error Detection Matrix**

CHECK BITS	35-Bit Data Word																																				
	35	34	33	32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1		
CB0	X		X		X		X		X		X		X		X		X		X		X		X		X		X		X		X		X		X		X
CB1			X	X			X	X			X	X			X	X			X	X			X	X			X	X			X	X			X	X	
CB2			X	X	X	X				X	X	X	X					X	X	X	X					X	X	X	X					X	X	X	
CB3	X	X								X	X	X	X	X	X	X									X	X	X	X	X	X							
CB4										X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
CB5	X	X	X	X	X	X	X	X	X																												
CB6	Exclusive "OR" All Data Bits (1–35) and All Check Bits (0–5)																																				

C6 Aids in DED. Double Error Detection.

### 3.0 Client Interface (Continued)

the ring: EDC error, illegal sequence error and node id out of maximum range. Once an error is detected at any node and the abort symbol has circulated the ring, all diagnostic registers will log the abort symbol except for the node which generated it. That node will log the original cause of the error.

In QR0001, an EDC error does NOT cause an abort symbol to be generated on the ring and propagate to all nodes. All other abort conditions do generate the abort symbol at the downstream port. An EDC error is displayed in the diagnostic register and causes the local ABORT pin to be asserted on all nodes which detect the EDC error. The symbol in error continues to the target. Multiple nodes could log an EDC error, but unless the node detects the EDC error it will not know other nodes have seen an error.

In QR1001 (the next device in the QuickRing family of products), when an EDC error is detected, the node will assert ABORT pin. The symbol in error will continue to its target. The abort symbol will then be sent downstream. Downstream nodes may see the symbol that causes EDC errors and log it. They will see the abort symbol and also log that in the diagnostic register. Since the ABORT pin has already been asserted by the EDC error condition, the abort symbol will have no affect on the ABORT pin.

### 4.0 Ring Interface

#### 4.1 Type and Symbol Field at the Ring Ports

On the ring path, upstream and downstream ports, type and symbol fields organize data transmissions. Data on the ring flows in bounded streams called packets. Before data flows in the ring, packets are formed by each controller internally. Packets have one head and one or more payload symbols. Since multiple independent packets can be found inside one controller and multiplexed at the downstream port, a type field accompanies each symbol. Inside a controller, packets can be found that may originate from any other node on the system. The type field marks each symbol as a head, payload, tail, or access. *Figure 4.1* shows a typical symbol on the ring.

#### 4.2 Data and Frames

In QuickRing there are two types of payload symbols, data symbols and frame symbols, but their distinction is only of interest to the clients. The QuickRing controller does not discriminate between them, except to preserve their identity. The payload on the ring is 33 bits wide, 32 bits of normal data plus a user/client defined Frame bit as the 33rd bit. The frame bit is encoded at the client port type fields, and it is transformed into an actual bit inside QuickRing before transmission at the down stream port

The Frame bit can be used to identify a special kind of data of interest to the clients. It also can be used to designate

the beginning or end of a stream or to distinguish between data streams at the client interface.

#### 4.3 Symbol Flux on Ring

At the transmit and receive ports, the length of a data stream that is uninterrupted by a head is unbounded. On the ring, upstream and downstream ports, data is bounded; there is an upper bound that gives the concept of a packet. There are two types of packets: normal and low bandwidth (LB). There is a ring protocol defining the symbol sequence. For normal packets, the maximum number of payload symbols associated with one head is fixed at 20 symbols. **The largest packet is 21 symbols in all;** however, packets may be less than 21 symbols. The LB packet consists of a Head and one payload/Tail.

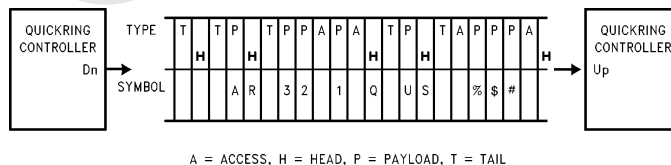
#### 4.4 Data on the Ring (Head, Payload, Tail)

QuickRing transports streams of payload symbols from source nodes to target nodes through the ring interconnect. QuickRing internally assembles packets from the data that the client writes into the transmit port. This data is eventually transmitted in packets of 1 to 20 payload symbols. A head symbol precedes the packet and the last payload symbol of a packet is specially marked as the tail of that packet. The head holds the source and the destination node IDs, plus other information that uniquely identifies the stream to which the payload symbols belong.

Payload symbols consists of 32 bits of user defined information plus one 33rd user controllable Frame identifier. A payload symbol whose frame bit is set to 1 may be called a Frame symbol. Otherwise it may be referred to as a Data symbol. The Frame identifier, the logical 33rd user defined bit is mapped in SS[3] in sub-symbol t, see *Figures 4.2* and *4.3*.

#### 4.5 Access on the Ring (Voucher, Ticket, Abort, Null)

Before a source node can send a packet, permission to transmit must first be granted by the target node. To get permission to transmit, the source node sends a voucher to the target node. To grant permission to transmit, the target node sends a ticket back to the source node. This is done only in response to a voucher. When the source node sends a voucher, the target node may (1) absorb the voucher and return a ticket or (2) return the voucher. If the source receives the ticket, then it may send one packet to the target that returned the ticket. If the source received its own returned voucher, then it will sink it and retransmit the voucher after 100 clocks for a new request to transmit. The number of retries for the voucher is unlimited until the target returns a ticket. Under normal circumstances the target should return a ticket in response to a voucher, even if it must save accumulated vouchers in a queue and issue corresponding tickets with significant delays. The return of a voucher to its source should occur only if resources for queuing vouchers in the target node are exhausted.



**FIGURE 4.1. Many streams from many nodes may be multiplexed onto the ring. Access symbols may appear interspersed anywhere within a data packet.**

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## 4.0 Ring Interface (Continued)

An abort symbol identifies the occurrence of a failure such as (1) an illegal symbol sequence, (2) a corrupted symbol or (3) a node ID for which no node is present. The node that creates the abort symbol deletes it once the abort symbol has circulated the ring.

For every tick of the ring clock, every node in the ring receives one symbol at its upstream port and transmits one symbol at its downstream port. In the absence of any other symbol, a null symbol is transmitted.

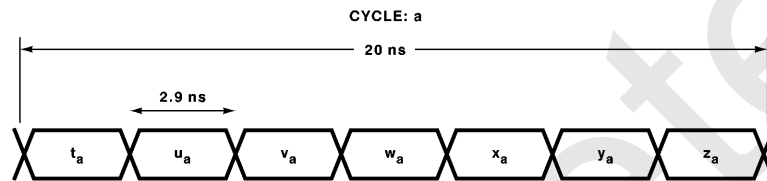
### 4.6 Mapping of Type, Frame, Data and EDC Code on the Ring

On the ring path, a 42-bit symbol is transferred on every tick of the 50 MHz clock. The 42-bit symbol is divided into 7 sub-symbols, 6 bits wide. Each sub-symbol is transferred sequentially at a rate of 1 sub-symbol every 2.9 ns. In all, 42 bits are transferred every 20 ns. Refer to *Figure 4.2*.

The type field, frame bit and the 3 MSB of the data are mapped to sub-symbol t. Data [28 to 0] are mapped onto sub-symbols u to y. The EDC field, CB[6:0], is mapped onto the last two sub-symbols of y and z. See *Figure 4.4*.

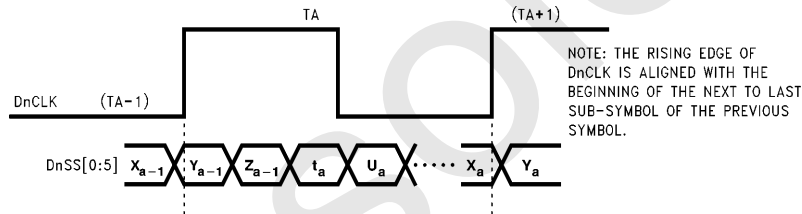
Later in this data sheet reference is made only to the fields that are multiplexed onto the SS[5:0] field as they appear on UpSS and DnSS. *Figure 4.2* and *4.3* show when each bit of any symbol is transmitted or received, and in what position of the sub-symbol it appears. For example, F (Frame) appears on SS[3] during "sub-symbol t". Data 0 (D0) appears on SS[1] during "y", the sixth sub-symbol.

**Note:** *Figure 4.3* shows that the rising edge of DnCLK is aligned with the beginning of the next to last sub-symbol of the previous symbol that gets sent out on DnSS[5:0].



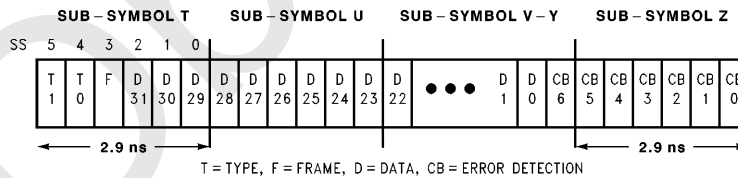
TL/F/11928-25

FIGURE 4.2. Seven Sub-Symbols in one Clock Cycle



TL/F/11928-12

FIGURE 4.3. Seven Sub-Symbols are Serially Transmitted Every 2.9 ns



TL/F/11928-13

FIGURE 4.4. Sub-Symbols are Serially Transmitted onto 6 Differential Pairs

## 4.0 Ring Interface (Continued)

### 4.7 Ring Interface Field Definitions

QuickRing organizes data with a combination of access symbols and packet symbols.

**Access** symbols are vouchers, tickets, nulls, and aborts.

**Packet** symbols are those that form packets such as heads and payloads.

These symbols can also be grouped into routing symbols and payload symbols.

**Routing** symbols hold source and target addresses such as voucher and ticket for access symbols, and heads for packet symbols.

**Payload** symbols are data or frame; they hold the information the clients are trying to transmit. At the client ports, a type field [01] represents a data symbol, a type field of [10] a frame symbol. A data or frame symbol at the ring ports are distinguished by an additional frame bit. The payload symbol, frame or data, at the end of a packet is called a **tail** and it is encoded as such in the type field.

**TABLE 4.1. Dn and Up Stream Port Symbol Field Definitions**

Field	Descriptions
Type[1:0]	At the ring ports, distinguishes access, head, payload and tail.
F	The Frame bit appears explicitly only at the upstream and downstream ports. (At the Tx and Rx ports the frame bit is encoded in the type fields.)
ACC[1:0]	The access code (ACC[1:0]) indicates the type of access symbol on the ring. Voucher, ticket, null and abort. (Doesn't apply to Tx or Rx ports.)
CONN[1:0]	The connection code (CON[1:0]) provides to types of transmission, normal and low-band-width Low-bandwidth streams are transmitted with higher priority.
TRGT[3:0]	The target field contains the node ID of the target of the associated payload.
SRCE[3:0]	The source field contains the node ID of the source of the associated payload.
HOP1[3:0] HOP2[3:0] HOP3[3:0] HOP4[3:0] HOP5[3:0]	They distinguish between unique streams whose source-to-target routes are identical. In a multiple-ring topology, they supplement source and target ID fields to route streams as they hop from ring to ring (See section on Ring of Rings).

Table 4.2 shows the possible values that the access field (ACC[1:0]) can take. The ACC field is valid only in the ring ports, upstream and downstream. At the client ports ACCess field should be [00].

**TABLE 4.2. Access Field Definitions**

ACC[1:0]	Name	Description
0	Abort	Abort. This symbol is forwarded by all nodes that receive it. Upon receipt of an abort symbol each node asserts an abort signal which the client uses to detect that an error has been detected somewhere on the ring. The system designer may elect that all nodes be re-initialized.
1	Voucher	Request to reserve target buffer space.
2	Ticket	Acknowledgment of reserved target buffer space.
3	Null	Ignore this symbol.

Table 4.3 shows the values of the connection field (CONN[1:0]). If a LB connection is requested, QuickRing parcels the data or frame symbols presented at the Tx Port and transmits every payload in 2 symbol packets, 1 head and 1 payload. LB connections carry higher priority than normal connections.

**TABLE 4.3. Connection Field Definitions**

CONN[1:0]	Name	Description
0	Normal	Queue and accumulate symbols from the same stream at will, to maximize system efficiency and minimize system load.
1	Low Bandwidth (LB)	Do not concatenate with other data symbols from the same stream. Results in two symbol packets, head and payload.
2	N/A	Reserved
3	N/A	Reserved

### 4.8 Routing Symbols are Common to All Ports

At all ports of the controller, vouchers, tickets and heads manage the flow of associated payload symbols. Nulls and aborts are special symbols to fill idle time or to indicate an anomalous situation respectively. All symbols on the ring share a common field format of control and status bits.

### 4.9 Ring Type Fields

The Type fields at the upstream and downstream ports are mapped onto UpSS/DnSS during sub-symbol time t.

## 4.0 Ring Interface (Continued)

**TABLE 4.4. Ring Port Type Field**

T[1]	T[0]	Name	Description
0	0	Head	A head symbol appears on Up or on the Dn Ports.
0	1	Payload	A data or frame symbol appears on the Up or on the Dn Ports.
1	0	Tail	The last payload symbol of a packet appears on the Up or Dn Ports.
1	1	Access	A Voucher, Ticket, Abort or Null symbol is present on the Up or the Dn Ports.

### 4.10 Head Symbol on the Ring

The Controller regenerates head symbols to mark the start of packets that it introduces to the ring. The head symbol is regenerated from the head written by the client at the transmit port. The number of heads that appear on the ring has no guaranteed relationship to the number of heads loaded at the transmit port. Head symbols on the ring carry information in the connection, source, target, and hop fields. Table 4.5 shows the field format for the head symbols on the ring ports.

**TABLE 4.5. Packet Head Format at the Ring Ports**

Type	F	31:30	29:28	27:24	23:20	19:16	15:12	11:8	7:4	3:0
0	0	0	Conn	Srcce	Trgt	Hop 1	Hop 2	Hop 3	Hop 4	Hop 5

### 4.11 Payload Symbols on the Ring

A type field of 1 identifies the symbol field as a payload symbol. A payload is 33 bits wide. The frame bit distinguishes frame from data symbols. Tables 4.6 and 4.7 show the field format for payload symbols on the ring.

**TABLE 4.6. Data Payload Format at the Ring Ports**

T(1:0)	F	31:0
1	0	Data Symbol

**TABLE 4.7. Frame Payload Format at the Ring Ports**

T(1:0)	F	31:0
1	1	Frame Symbol

### 4.12 Tail Symbol on the Ring

A type field of 2 identifies the symbol field as a tail symbol, which is nothing else but the last payload symbol of a packet. A tail may carry frame or data, as determined by the state of the frame bit. These format of these symbol are shown in Tables 4.8 and 4.9.

**TABLE 4.8. Tail-Data Format at the Ring Ports**

T(1:0)	F	31:0
2	0	Data Symbol Acting as a Packet Trail

**TABLE 4.9. Tail-Frame Format at the Ring Ports**

T(1:0)	F	31:0
2	1	Frame Symbol Acting as a Packet Trail

### 4.13 Access Symbols on the Ring

The fourth kind of symbols depicted by a type field of 3 are access symbols. There are four kinds of access symbols on the ring: vouchers, tickets, nulls, and aborts. These are identified in Table 4.10 through 4.13.

**Voucher:** Vouchers are sent by source nodes to obtain permission to launch packets of client generated payload symbols. QuickRing will send a voucher as soon as there is a head and a data are loaded at the transmit port. Table 4.10 shows the format for a voucher. A Type field value of 3 indicating an access symbol and the ACCess field value of 1 indicates that the symbol is a voucher.

**TABLE 4.10. Ring Port Voucher Field Format**

Type	F	31:30	29:28	27:24	23:20	19:16	15:12	11:8	7:4	3:0
3	0	[0,1]	Conn	Srcce	Trgt	Hop 1	Hop 2	Hop 3	Hop 4	Hop 5

**Ticket:** Tickets are returned by target nodes in response to vouchers. They indicate that the target has reserved FIFO space for one packet. QuickRing will send one packet upon receipt of one ticket. The format for a ticket is shown in Table 4.11. As in all access symbols, the type filed has a value of 3. In tickets, a value of 2 in the ACCess indicates that the symbol is in fact a ticket.

**TABLE 4.11. Ring Port Ticket Field Format**

Type	F	31:30	29:28	27:24	23:20	19:16	15:12	11:8	7:4	3:0
3	0	[1,0]	Conn	Srcce	Trgt	Hop 1	Hop 2	Hop 3	Hop 4	Hop 5

**Null:** Null symbols are sent to consume idle time on the ring. The symbol format is shown in Table 4.12. When ever a controller does not have any payload or other access symbol to send, it will send a null symbol at its downstream port.

**TABLE 4.12. Ring Port Null Field Format**

T(1:0)	F	31:30	29:0
3	1	3	XXX

**Abort:** An abort symbol is sent by any node that detects a failure of addressing, protocol, or data integrity during normal operation the QuickRing ring. The symbol format is shown in Table 4.13.

**TABLE 4.13. Ring Port Abort Field Format**

T(1:0)	F	31:30	29:18
3	0	0	XXX

## 4.0 Ring Interface (Continued)

### 4.14 Summary of Ring Port Field Format

TABLE 4.14. Ring Port Field Format

Packet Head Format										
Type (1:0)	Frame	31:30	29:28	27:24	23:20	19:16	15:12	11:8	7:4	3:0
Type	F	Acc	Conn	Src	Trgt	HOP				
0	0	0	Conn	Src	Trgt	HOP 1	HOP 2	HOP 3	HOP 4	HOP 5
Data Payload Format										
1	0	Data Symbol								
Frame Payload Format										
1	1	Frame Symbol								
Tail-Data Format										
2	0	Data Symbol Acting as a Packet Tail								
Tail-Frame Format										
2	1	Frame Symbol Acting as a Packet Tail								
Voucher Field Format										
Type	F	Acc	Conn	Src	Trgt	HOP				
3	0	1	Conn	Src	Trgt	HOP 1	HOP 2	HOP 3	HOP 4	HOP 5
Ticket Field Format										
Type	F	Acc	Conn	Src	Trgt	HOP				
3	0	2	Conn	Src	Trgt	HOP 1	HOP 2	HOP 3	HOP 4	HOP 5
Null Field Format										
Type	F	Acc	29:0							
3	1	3	XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX							
Abort Field Format										
Type	F	Acc	29:0							
3	0	0	XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX							

## 5.0 Clock Signals

There are four clock domains in QuickRing, one for each port. The transmit and receive ports are clocked by TxCLK and RxCLK, respectively. The QR0001 core logic is clocked either from RGCLK when CKSRC is asserted or from UpCLK when CKSRC is negated. The upstream port is always clocked by UpCLK. Each controller derives the DnCLK from the clock that drives the downstream port.

TABLE 5.1. Clock Signal

QR0001 Interface	CKSRC	Clock Source
DnCLK,	H	RGCLK
CLKOUT	L	UpCLK

The client ports are asynchronous from each other. The Upstream and Downstream ports are synchronous with each other when CKSRC is negated, and frequency locked, not phase locked, when CKSRC is asserted.

For all clocks, the minimum period is 20 ns having maximum frequency of 50 MHz.

### TIMING SYNCHRONIZATION

On QR0001, the RGCLK, TxCLK and RxCLK must be synchronized. Two methods for synchronization are shown below.

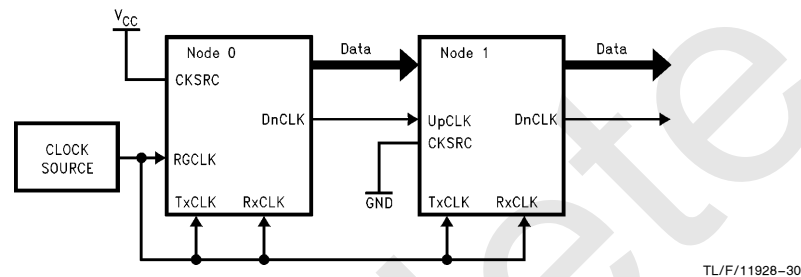


FIGURE 5.1. Recommended for Card-to-Card Connections Over QuickRing

- RGCLK on the CKSRC node is driven by the local host clock that drives RxCLK and TxCLK.

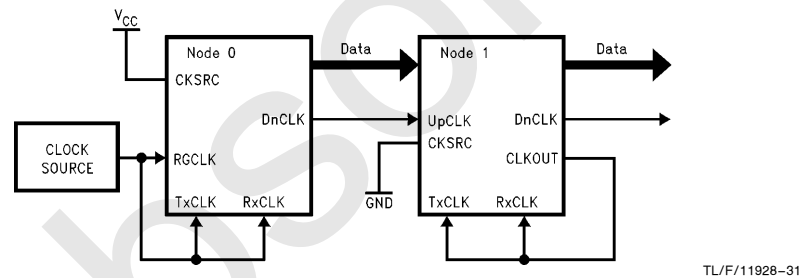


FIGURE 5.2. Recommended for Box-to-Box or Card-to-Card Connectors Over QuickRing

- CLKOUT is used on all other nodes to drive RxCLK, TxCLK, and therefore the HOST SYSTEM CLOCK.
- Note that CLKOUT is not intended to drive large loads and can only sink a few mA. If the application requires the ability to drive other system clocks then add a buffer.

### QR0001 Resynchronizer Issue

The core of QR0001 operates in the timing domain of the ring in which it is connected. The intent of the QR0001 design is to allow the timing domain of the client interface to be independent of the ring clock domain. Unfortunately, there is a bug in the first release of QR0001 that affects both the transmit and receive resynchronizers whose task is to decouple the clock domains from each other. These circuits fail in such a way that data may be erroneously replicated or deleted as it crosses between the ring clock domain and the client clock domains. The failure occurs because of metastable states in the logic that controls these resynchronizer blocks.

The transmit resynchronizer is susceptible to metastability whenever the delay between CKOUT and TxCLK falls within a range which we can call the window of metastability or the danger window.

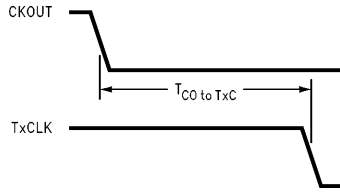
Likewise, the receive resynchronizer may experience metastability and data stream corruption if the delay of RxCLK from CKOUT falls within its window of metastability.

The following two inequalities identify the window of metastability, within which metastability and data stream corruption is possible.



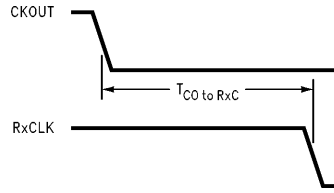
## 5.0 Clock Signals (Continued)

$$T_{COtoTxCmin} < T_{TxMETA} < T_{COtoTxCmax}$$



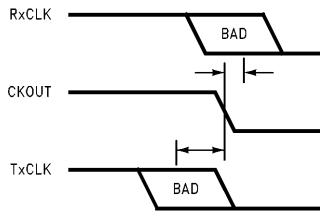
TL/F/11928-33

$$T_{COtoRxCmin} < T_{RxMETA} < T_{COtoRxCmax}$$



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In general, the only way to guarantee that TxCLK and RxCLK never violate the metastability window is to (1) derive TxCLK and RxCLK from CKOUT or from the same source from which CKOUT is derived, and (2) fix the delay of TxCLK and RxCLK safely outside the window.



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Design your circuit so as to avoid the danger window. The size and position of this window is as specified in the following table:

	$T_{META}$ (ns)		
	Min	Max	Width
$T_{COtoTxC}$	-11	-7	4
$T_{COtoRxC}$	-1	3	4

**Why Falling Edges?** Blocks within the QR0001 device operate using two-phase logic. In general, half of the internal latches are transparent during the clock-high time, and the other half are transparent during clock-low time. It just so happens that all of the latches involved in this bug are transparent during clock-high time. The bug represents a failure to decisively resolve a logic value to be true or false as those latches close—on the falling edges of their respective clocks.

**What about frequency and duty cycle?** The window of metastability is fixed by chip-internal combinatorial delay paths, whose values are independent of the clock frequency and duty cycle.

**What are the symptoms?** It would be extremely rare for any single symbol to be corrupted. However the symbol *stream* will be corrupted, as individual symbols or groups of symbols may be randomly dropped or duplicated.

**What circuits do I need?** If you are deriving RxCLK and TxCLK from a buffered version of CKOUT, you are probably already safe. Just analyze your own circuit to make sure that TxCLK and RxCLK fall *outside* the danger window.

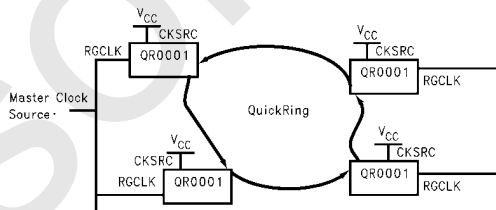
### Multiple Clock Sources to Reduce Ring Jitter on QR0001

Testing shows rings with more than 4 nodes accumulate excessive jitter on the ring clock, which inhibits maximum

frequency operation. One method to stop jitter accumulation, and improve frequency performance, on large rings is to provide multiple clocks sources. Using several nodes on all nodes as clock sources reduces accumulated ring jitter. Using multiple clock sources, however, does increase ring latency; the next QuickRing device (QR1001) is being designed so that only one clock source will be required.

A 10 node ring was tested using 3 clock sources. It allowed the ring to operate at full speed (33 MHz). To make a node a clock source, the “CKSRC” input pin should be asserted, and the clock should be connected to the “RGCLK” pin. Note that all “RGCLK” pins in the Ring (Clock Source Nodes) MUST be exactly the same frequency, however, phase relationship is not an issue. This necessitates one master clock source distributed to each QuickRing Clock Source node, figure below. “CKSRC” asserted activates the elasticity buffer at the Upstream port. This buffer adds 3 clock cycles delay to every symbol that arrives at the port, including vouchers and tickets.

### Multiple Clock Source Nodes



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## 6.0 ABORT Signal

The  $\overline{ABORT}$  signal is an output of the QR0001. Any one of the following events can cause the  $\overline{ABORT}$  signal to be asserted:

- EDC error. Although  $\overline{ABORT}$  signal pin is asserted, ring abort symbol may not propagate around entire QuickRing.
- Illegal sequence detected on the QuickRing (Refer to following ring interface sections.) Ring abort symbol propagates around QuickRing.
- Node ID detected greater than maximum number of nodes in the ring. Ring abort symbol propagates around QuickRing.
- Received an Abort symbol from the upstream port.

## 7.0 Bridges

In a single QuickRing ring, the maximum number of nodes is sixteen. Within a ring, the PIPE signal will most probably be asserted for ease of interfacing to the QR0001. In a multiple QuickRing topology, the individual rings may be connected together through bridges. The system may implement a very basic bridge or an intelligent bridge.

For a basic bridge implementation, two QR0001 controllers can be directly connected through their client ports, providing a bridge between two rings. The PIPE signal should be negated in bridge operation so that the Rx and Tx port timing will be identical. Also, the TxOK signal is connected to the RxSTALL signal. QR0001 timing characteristics will support bridging. However, an external flip-flop may be used to achieve additional setup and hold time margins. For more sophisticated bridges, external logic can implement an added layer of protocol.

The HOP fields are used, with respect to bridges, when implementing multi-ring topologies. The HOP fields may be used as desired in a single ring topology. (i.e., To distinguish various data streams.) Refer to Client Interface Field Definitions sections for more information.

## 8.0 Little/Big Endian Issues

This QR0001 datasheet uses strict little-endian labeling conventions to indicate bit positions. The device itself is neither big-endian nor little-endian. No assumption is made in QR0001 about the relative significance of bytes within any payload symbol.

For reference:

Big Endian: MSB(byte) of the information (data/address) is stored at the least significant address location.

Little Endian: LSB(byte) of the information (data/address) is stored at the least significant address location.

Table 8.0 contains Big/Little Endian formats.

TABLE 8.0. Big/Little Endian

Big Endian			
MSB(it)			LSB(it)
Bit 0			Bit 31
[0:7]	[8:15]	[16:23]	[24:31]
MSB(yte)			LSB(yte)
Byte 0	Byte 1	Byte 2	Byte 3
Address: (n)	Address: (n + 1)	Address: (n + 2)	Address: (n + 3)
Little Endian			
MSB(it)			LSB(it)
Bit 31			Bit 0
[31:24]	[23:16]	[15:8]	[7:0]
MSB(yte)			LSB(yte)
Byte 3	Byte 2	Byte 1	Byte 0
Address: (n + 3)	Address: (n + 2)	Address: (n + 1)	Address: (n)

## 9.0 Reset and Initialization

### 9.1 Reset

The controller must be reset after power up. RESET can be released from each node in any order but only after all

nodes are simultaneously in the reset state (for the time period of the reset pulse width: tRSPW timing parameter #82). External logic should assert RESET to all nodes on the ring during system power up or when ABORT is asserted. The release of RESET to node 0 will begin the initialization process. The ring initialization proceeds to completion only after RESET has been released to all nodes.

The first 2 non-null symbols that appear at the receive port are the node ID number and the largest ID on the ring. The type associated with this information will indicate a non-null type also. These values will be present for one clock cycle. The information can be later retrieved by reading the Diagnostics Register through the RxNBL and RxSEL at any time later.

TABLE 9.1. RxS[31:0]

31	28	27	0
Node ID	1	1	1
Max ID	1	1	1

### 9.2 Node 0 Selection and Initialization

Only one QuickRing controller in a ring can be designated as Node 0 (NODE0 asserted). For all other controllers on the ring, NODE0 must be negated. Once the QuickRing has completed the initialization process, the ring is ready for normal operation. During normal operation, there are no differences between node 0 and all other nodes.

### 9.3 Node ID Assignment

As RESET is released to each QuickRing controller, each node receives the node ID of its upstream neighbor on RxS[31:28], assumes that its own address is node ID + 1, and passes its new node ID to its downstream neighbor.

After initialization, the first two non-null symbols that appear at the receive port indicate to the client interface the node ID number of the controller, and the largest ID number on the ring. This information can be used to configure the client interface.

The node ID (Node ID) and largest node ID in the system (MaxID) can be read later from the internal diagnostics register in the controller.

### 9.4 Sequence for Node 0

1. On release of RESET by all nodes, the controller with the NODE0 signal asserted assigns itself to be node 0.
2. Node 0 then begins to transmit a stream of identical symbols at the down stream port whose high order four bits are [0,0,0,0], whose frame bit is 1 and whose type field is [0,1].
3. The first downstream node to receive this symbol increments the value to [0,0,0,1], becomes node 1,
4. then the node forwards the symbol containing a value of 1. The type field and frame bit are not changed.
5. Each node in turn increments the value and takes on its own unique node ID.
6. When the node 0 receives the symbol at its up stream port, the value of the symbol is the largest ID number in the ring.
7. Node 0 stores this value and forwards it around the ring, but with the type field changed to [1,0]. This notifies all other nodes the total number of nodes in the ring.
8. All nodes forward this symbol stream unmodified.

## 9.0 Reset and Initialization (Continued)

9. Once this symbol stream completes its route around the ring, node 0 begins to transmit null symbols whose frame bits are reset to 0.
10. As soon as each node, including node 0, detects an up stream symbol with the frame bit equal to zero, its initialization sequence is completed, and it may begin to transmit vouchers, tickets and packets.
11. During this sequence, the controller forwards the node ID and eventually the MaxID on the ring to the receive port.

### 9.5 Sequence for All Other Nodes on the Ring

1. While **RESET** remains asserted all other nodes (other than node 0) transmit all ones at the down stream port.
2. Release of **RESET** from a node causes that node to begin monitoring its up stream port. While the up stream type field is [1,1], the node transmits all 1's at the down stream port.
3. When the upstream type field changes to [0,1], the accompanying symbol field is interpreted as the node ID of the upstream neighbor.
4. The node increments the symbol field value, stores the new value internally, and then forwards the incremental value including the new [0,1] type code at its down stream port. The stored value becomes the local node ID. This node ID number is propagated to the node's receive port so the client interface can learn its ID number.
5. Some time later, a new stream of symbols arrives at the up stream port accompanied by the type code [1,0]. The value of this symbol is stored internally and represents the numerically greatest node ID residing on the ring. The node forwards this symbol stream to its down stream port. This value is also forwarded to the receive port, so the client can learn the number of nodes on the ring.
6. Throughout this sequence, the node transmits symbols with the frame bit set to 1. Eventually, a stream of null symbols is received at the up stream port with the frame bit reset to 0. As soon as this symbol is forwarded to the down stream port, the node may commence normal ring operation. If at any point there is a node ID detected whose value is greater than the greatest ID residing on the ring, an abort symbol is sent and it is considered as a failure. For the client interface, the first 2 non-null symbols that appear at the receive port are the node ID number and the largest ID on the ring.

## 10.0 QR0001 Operation Flow

### 10.1 Ring Traffic Flow Priorities for DnSS Port Transmission

After the initialization process is complete, all nodes on the QuickRing are ready to transfer packets on the ring. Data streams can be queued/de-queued into/from the QR0001 through the Client Interface on all nodes. As traffic builds on the ring, the QR0001 prioritizes the information flow through the node that goes onto the ring. Following is the list, in descending order, of the paths inside the QR0001 that process information to be sent out onto the ring through the downstream (DnSS) port. Refer to the QR0001 block diagram.

1. The highest priority is given to tickets/vouchers to/from other nodes. This QR0001 is simply forwarding the access symbols on the ring that are destined for other nodes.
2. LB Target Handler: Sends out low bandwidth tickets generated by this node. (Includes voucher rejects when exceeding storage capacity.)
3. Target Handler: Sends out normal tickets generated by this node. (Includes voucher rejects when exceeding storage capacity.)
4. Local sourced vouchers launched by this node.

LB FIFO: Generates a voucher when the LBW symbol gets to the head of the FIFO.

X or Y FIFO: Generates a voucher as soon as the first symbol is loaded into the FIFO. Also, generates another voucher as soon as the 21st symbol (associated with the same head) is loaded into the FIFO. Further, continues to generate a voucher for each packet (maximum bundle of 20 symbols).

5. Ring FIFO: This QR0001 is forwarding data destined to other nodes.
6. Sends out locally generated packets from this node's X, Y, or LB FIFO. At the beginning of each packet, the traffic flow priorities are checked. (The source (X, Y, or LB) FIFO can transmit when the Ring FIFO has at least 28 empty positions. Locally sourced packets will be held until the Ring FIFO has no more than 12 data symbols.)

### 10.2 Inside the Source Node (Device Transmitting Data)

At the source node, as soon as QR0001 latches a head and a payload symbol, in the X or Y FIFO, it sends a voucher to the target node. The source node waits until the target node sends a ticket back before transmitting a packet. During this time the client interface can write payloads into the controller.

When QR0001 detects that a single packet will not be enough to transmit all data in FIFO X or Y, another voucher is sent to the target node. Additional vouchers are sent as soon as the controller deems it necessary to complete the transmission. This action is intended to hide the latency between the transmission of vouchers and the receipt of tickets. A maximum of 7 (3X, 3Y and 1 LB) vouchers can be outstanding from the source node. Vouchers have higher priority than payloads, and they can be launched interleaved in current outgoing packets.

At the source node, only when a ticket is received is a packet sent. A packet is formed by 1 head and anywhere from 1 to 20 payload symbols. The largest packet is 21 symbols, 1 head symbol and 20 payload symbols. The last payload symbol of a packet is always identified as a tail. This is encoded in the type field.

The QuickRing controller does not wait for any specific number of data symbols to send a packet. If the client interface is slow in writing data at the transmit port, QR0001 could send packets with less than 21 symbols. The same will occur in transmissions where the total number of payloads is not a multiple of 20. The QuickRing controller is designed to transmit the data in the transmit pipeline as soon as possible.

### 10.3 Summary of Source Node Actions

QR0001 sends a voucher from the source node to the target node as soon as it has at least one payload to transmit. (In the X or Y FIFOs.)

## 10.0 QR0001 Operation Flow (Continued)

QR0001 sends an additional voucher as soon as it identifies that one packet is not going to be enough to transmit all the data in the transmit pipeline.

No packet is sent until a ticket is received. This includes low bandwidth packets.

QR0001 does not wait for data; therefore, packets could vary in size.

The largest and most efficient packet is one formed by 1 head symbol and 20 payload symbols, 21 symbols in all.

Low Bandwidth packets are 1 head and 1 payload symbol.

The client interface must stop writing data at the transmit port within 20 non-null symbols after TxOK negates. The count is reset if TxOK asserts again.

### 10.4 Inside the Target Node

At the *target node*, if the receiving controller has space for one packet in the Target FIFO, it will send a ticket immediately to the source node in response to a voucher. A QR0001 Target FIFO has space for 3 normal packets and 6 low bandwidth packets; therefore, the controller can have only 3 outstanding normal tickets and 6 outstanding low bandwidth tickets. If all tickets have been given, the receiving QR0001 will queue incoming vouchers in one of two special buffers, called Target Handler and LB Target Handler. The Target Handler can store 30 vouchers and the LB Target Handler can store 10 vouchers for low bandwidth transmission.

At the *target node*, a new ticket is released as soon as a packet has exited the Target FIFO to the Rx Resynchronizer. This is determined internally by matching the tickets given and the tails exiting the target FIFO.

If the target node cannot return a ticket or store the voucher to be handled later, it will return a voucher rejected to the source node. (The Source will sink the voucher and the node will then re-send the voucher after 100 clock cycles.)

### 10.5 Summary of Target Node Actions

The target FIFO can handle 3 normal packets and 6 low bandwidth packets. Therefore, only 3 normal tickets and 6 LB tickets can be outstanding at one time.

QR0001 can store 30 normal vouchers and 10 LB vouchers before returning a voucher\_reject to the source node.

The Head Stripper will remove the head of all packets before entering the Target FIFO, unless there is a change in stream (new head).

Data may arrive at the Rx Port on every tick of the clock unless the client stops the flow through the  $\overline{\text{RxSTALL}}$  input.

RxET can be used to monitor the kind of data entering the receive pipeline up to 20 symbols before it appears at the receive port. When the Rx pipeline is free flowing in the unblocked pipe ( $\overline{\text{RxSTALL}}$  is negated), RxET will indicate the Type:

1. Three clock cycles early the symbols (RxS) in the pipelined timing and
2. Two clock cycles early the symbols (RxS) in the non-pipelined timing.

## 11.0 Board Considerations

### 11.1 Upstream Port Signal Termination

The ring interface upstream port signals: UpSS[5:0], and UpCLK need external termination. The termination should be a  $100\Omega$  resistor between the differential signal pair. The resistor should be placed as close to the upstream port pins as possible. Minimum parasitic inductance and capacitance is desirable. Surface mount chip resistors with  $\pm 1\%$  tolerance are recommended. See *Figure 11.1*.

### 11.2 QuickRing Physical Layer Details

The QuickRing 180 MHz data signals dictate special care for the physical layer design and layout. The use of LVDS (Low Voltage Differential Signals) enables the very high frequency operation. The LVDS also eases design because the differential signals are forgiving to certain impedance discontinuities in the signal path. If the discontinuities are at the same electrical distance and have the same magnitude, they will not distort the differential signal. Each single ended signal may appear to have reflections, but if the differential pair has the same minor reflections, then the differential signal will not be affected. The skew between the pairs and inside the pairs is a critical design criteria. These are the basic guidelines for transporting the ring signals.

The skew between pairs and between single ended signals inside a pair is critical. First, the skew between signal pairs. The 350 MBaud signals only provide a bit width of about

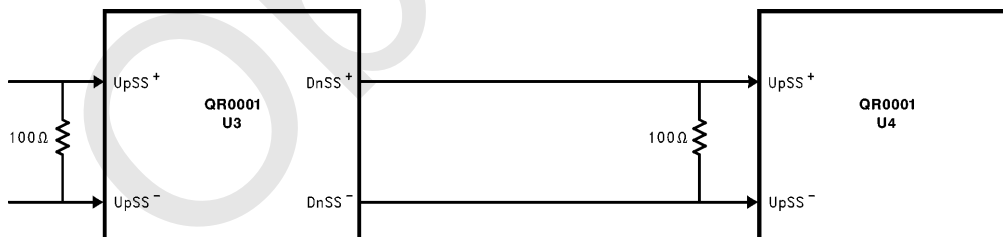


FIGURE 11.1. Termination between the Differential Signal pair

TL/F/11928-26

## 11.0 Board Considerations (Continued)

2.86 ns. The QuickRing UpPort needs 2.36 ns of this bit width (including transitions) to successfully sample the value for each sub-symbol. This allows for a total skew budget of 0.5 ns. The interconnect between DnPort and UpPort should be limited to 350 ps. This provides 150 ps skew margin. The 350 ps can be divided between PCB traces, connectors, headers, cables and all other media used in the signal path.

The skew within a pair needs to be controlled because of the EMI considerations. The simultaneous and opposite transitions on paths within a pair create equal and opposing electromagnetic fields. These EMF, the source of EMI, serve to cancel each other thereby reducing EMI. The skew within a pair should be controlled so that the single ended EMF remain temporally and spatially relevant for the canceling affect.

The length of node interconnects is not critical to the operation of QuickRing until it degrades signal integrity. Nodes in a ring can have different length interconnects. The maximum length of the interconnect depends on two qualities of the interconnect; transition time degradation and amplitude attenuation. Any extension in transition time due to the high frequency filter affect of the interconnect, takes away from the skew budget. The trade offs between the skew and transition time degradation must be balanced to allow for the correct amount of sample time for the UpPort.

The signal attenuation affects the differential signal amplitude at the receiver input. The receiver requires a differential voltage of at least 100 mV to guarantee a state. The receiver actually is more sensitive than that under typical operating conditions, but due to power supply and temperature variations, and test limitations, this is the data sheet specification. As long as the differential voltage is guaranteed to be at least 150 mV and all the skew budget specifications are met, the receiver will operate correctly with adequate noise margin.

## 12.0 Power and Decoupling Issues

### 12.1 Power Issues

The QR0001 device internally has Four distinct Power regions. These regions are labeled (Refer to *Figure 12.3*):

1. Logic Power Pins  
(V<sub>CC</sub> 4,5,12,13; GND 3,15,18,19,28,29);
2. Client Receive Port Output Power Pins  
(V<sub>CC</sub> 6,7,8,9,10,11; GND 20,21,22,23,24,25,26,27);
3. LVDS Power Pins  
(V<sub>CC</sub> 1,3; GND 1,2,4,5,6,7,8,10,11,12,13,14,16,17);
4. PLL and Delay Element Power Pins  
(V<sub>CC</sub> 2; GND 9);

It is currently recommended that the PC Board have separate GND and V<sub>CC</sub> planes. Also, Power Region 2 should have some additional isolation from the power plane. Complete isolation is not required. The isolation aids in limiting the Receive Port current spikes to the remaining plane. Refer to *Figure 12.1*.

### 12.2 Decoupling Issues

It is currently recommended that capacitors be placed locally on all four corners of the device to provide an even filtering. Capacitors should also be placed close to power region 2 to provide additional noise filtering. Refer to *Figure 12.1*.

Two capacitors should be placed in parallel to get high and low frequency filtering along each side. However, each capacitor should have a via directly to the V<sub>CC</sub> and Ground planes.

For power region 4 (PLL and Delay Element Power Pin), two decoupling capacitors should be placed as close to the pins as possible (between V<sub>CC2</sub> and GND9). A trace from the pin directly to the capacitors is recommended and separate vias to ground plane for each capacitor. Refer to *Figure 12.1*.

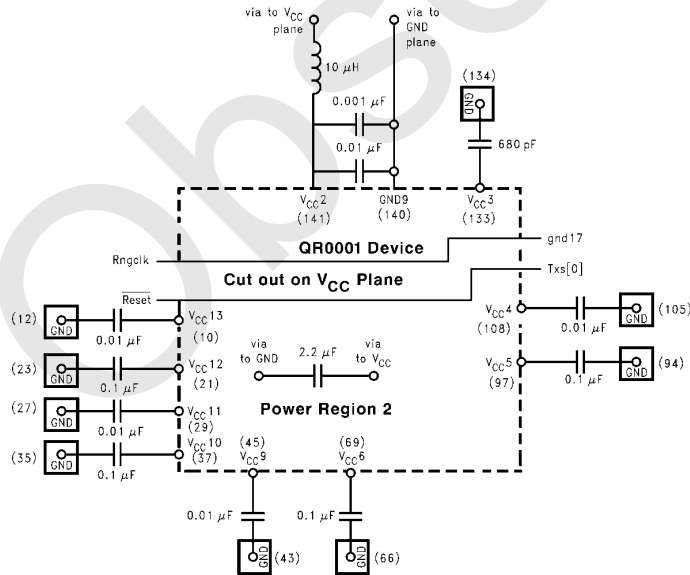


FIGURE 12.1. QR0001 Power Region Isolation

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## 12.0 Power and Decoupling Issues (Continued)

Following is a List of PCB Recommendations:

1. Use one ground plane and at least one  $V_{CC}$  plane.
2. Use a range of decoupling capacitor values. These decoupling caps should be high Q factor chip capacitors (chip caps have little parasitic inductance). The differing QR port frequencies require decoupling over a range of frequencies. The decoupling caps should not share vias to the ground plane, as this would defeat the noise suppression across the desired frequency range.
3. Decoupling caps should be placed as close to the device power pins as possible. Extreme care should be taken placing the Power Region 4 de-couple caps directly on the power pins. These decoupling caps are recommended as  $0.001 \mu\text{F}$  and  $0.01 \mu\text{F}$ . The caps at the RxPort (region 2) are recommended to be  $2.2 \mu\text{F}$ ,  $1-1.0 \mu\text{F}$ ,  $1-0.1 \mu\text{F}$ ,  $2-0.01 \mu\text{F}$ . These caps should be used as noise barriers between this region and the high frequency ring port region. Power region (3 and 1 combined) should have  $2-0.1 \mu\text{F}$ ,  $2-0.01 \mu\text{F}$ , and  $680 \text{ pF}$  close to the power pins.
4. Care should be taken for ensuring RGCLK, TxCLK, and RxCLK have clean transitions and no reflections or ringing. Transmission line design techniques must be used. As a rule of thumb, if the signal path electrical length (propagation delay time) is greater than 0.125 times the clock transition time, the line should be terminated.

Obsolete

## 12.0 Power and Decoupling Issues (Continued)

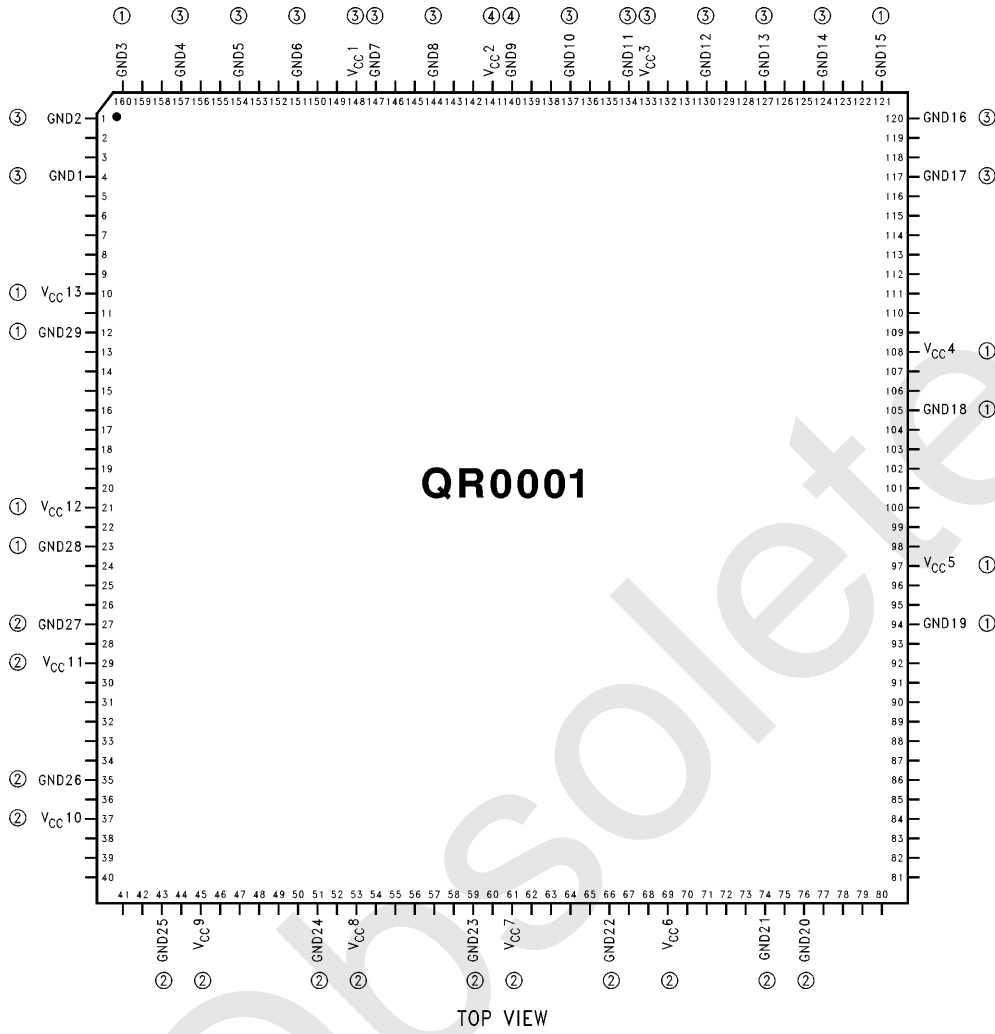


FIGURE 12.3. Power and Ground Regions

TL/F/11928-29

## 13.0 DC Electrical Characteristics

### PARAMETRICS DISCLAIMER

The current AC and DC specifications contained in this document are a combination of target design specifications, limited sampled electrical data, and some characterization data. Currently, this information does not represent all actual guaranteed test timing parameters. Guaranteed specifications will be provided after full device characterization. For more specific information regards DC and AC parameters, contact National Semiconductor.

## Absolute Maximum Ratings

DC Supply Voltage ( $V_{CC}$ )	-0.5V to +7.0V
DC Input Voltage ( $V_{IN}$ )	-0.5V to $V_{CC} + 0.5V$
Storage Temperature Range ( $T_{STG}$ )	-55°C to +150°C
Power Dissipation (PD)	2.2W
ESD Rating	2000V

## Recommended Operating Conditions

Supply Voltage, $V_{CC}$	4.5V to 5.5V
Operating Free Air Temperature	0°C to 70°C

## DC TTL Specifications, Client Ports $T_A = 0^\circ\text{C}$ to $+70^\circ\text{C}$ , $V_{CC} = 5V \pm 10\%$ , unless otherwise specified

Symbol	Parameter	Conditions	Min	Max	Units
$V_{IH}$	Minimum High Level Input Voltage	(Note A)	2.0		V
$V_{IL}$	Maximum Low Level Input Voltage	(Note A)		0.8	V
$V_{OH}$	Minimum High Level Output Voltage	$I_{OH} = -400 \mu\text{A}$ (Note A)	2.4		V
$V_{OL}$	Maximum Low Level Output Voltage	$I_{OL} = 1.6 \text{ mA}$ (Note A) $I_{OL} = 8 \text{ mA}$ (Note B)		0.4 0.4	V
$I_I$	Input Leakage Current	$V_{IN} = V_{CC}$ (Note A)	-1.0	1.0	$\mu\text{A}$
$I_{IN}$	Input High Current	$V_{IN} = 2.0V$ (Note A)		1.0	$\mu\text{A}$
$I_{IL}$	Input Low Current	$V_{IN} = 0.8V$ (Note A)	-1.0		$\mu\text{A}$
$I_{DD}$	Supply Current	(Note A)		450	mA
$I_{CC}$	Average Operating Supply Current	RESET, RxSTALL, RxOE = 3.5V Other CLIENT INPUTS = 0.4V (Note A)		200	mA
$I_{OZ}$	Maximum TRI-STATE Output Leakage Current	RxOE = 2V (Note A)	-10	10	$\mu\text{A}$

## DC Electrical Characteristics, Ring Ports

DC Differential Generator Specifications,  $T_A = 0^\circ\text{C}$  to  $+70^\circ\text{C}$ ,  $V_{CC} = 5V \pm 10\%$ , unless otherwise specified

Symbol	Parameter	Conditions	Min	Typ	Max	Units
$V_{OH}$	Output Voltage High, $V_{OA}$ and $V_{OB}$	$R_{LOAD} = 100\Omega$ (Note B)	$V_{OL} + 0.3$	1.4	1.5	V
$V_{OL}$	Output Voltage Low, $V_{OA}$ and $V_{OB}$	(Note B)	0.9	1.0	$V_{OH} - 0.3$	V
$V_{OD}$	Differential Output Voltage	(Note B)	$\pm 300$	$\pm 400$	$\pm 500$	mV
$\Delta V_{OD}$	Differential Voltage Change between Complimentary Output Stages	(Note B)		0	50	mV
$\Delta V_{OS}$	Output Offset Voltage Change between Complimentary Output States	(Note B)		0	50	mV

## DC Receiver Specifications $T_A = 0^\circ\text{C}$ to $+70^\circ\text{C}$ , $V_{CC} = 5V \pm 10\%$ , unless otherwise specified

Symbol	Parameter	Conditions	Min	Typ	Max	Units
$V_I$	Input Voltage, $V_{IA}$ and $V_{IB}$	$V_{gpd} = \pm 900 \text{ mV}$ (Note B)	0		3	V
$V_{TH}$	Differential High Input Threshold	(Note B)			+100	mV
$V_{TL}$	Differential Low Input Threshold	(Note B)	-100			mV

Note 1:  $V_{gpd}$  = ground potential difference voltage between the generator and receiver.

Note A: Limit guaranteed by test program.

Note B: Limit based on simulation results.

Note C: Limit based on bench characterization.



### 13.0 DC Electrical Characteristics (Continued)

#### AC Receiver Specifications $T_A = 0^\circ\text{C}$ to $+70^\circ\text{C}$ , $V_{CC} = 5\text{V} \pm 10\%$ , unless otherwise specified

Symbol	Parameter	Conditions	Min	Typ	Max	Units
$t_{pSKEW}$	Receiver Propagation Delay Skew	Any Two Channels on IC (Notes 2, 3, B)	0		250	ps
$t_{pwd}$	Pulse Width Distortion ( $t_{plh} - t_{phl}$ )	One channel at receiver output. (Notes 2, 3, B)	-250		+250	ps
$t_{SKEWIN}$	Single ended skew that can be tolerated at receiver inputs	Measured at 50% of transition. (Notes 2, 3, B)			500	ps

**Note 2:** These specifications are not tested but verified by design.

**Note 3:** A 300 mV differential signal is used to stimulate the receiver input circuitry.

**Note B:** Limit based on simulation results.

#### AC Differential Generator Specifications

$T_A = 0^\circ\text{C}$  to  $+70^\circ\text{C}$ ,  $V_{CC} = 5\text{V} \pm 10\%$ , unless otherwise specified

Symbol	Parameter	Conditions	Min	Typ	Max	Units
$t_r$	$V_{OA}$ and $V_{OB}$ Rise Time. 20%–80%	$Z_{LOAD} = 100\Omega$ (Note B)	150	300	450	ps
$t_f$	$V_{OA}$ and $V_{OB}$ Fall Time. 80%–20%		150	300	450	ps
$t_{SKEW}$	t Generator Propagation Delay	Any Two Channels on IC (Note B)			200	ps
$t_{pwd}$	Pulse Width Distortion ( $t_{plh} - t_{phl}$ )	One Channel, Difference between Differential Prop Delays (Note B)	-200		+200	ps

**Note A:** Limit guaranteed by test program.

**Note B:** Limit based on simulation results.

**Note C:** Limit based on bench characterization.

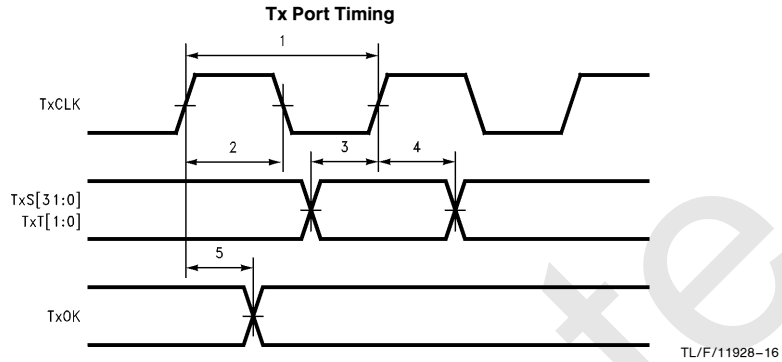
## 14.0 AC Timing Parameters

### Parameters Disclaimer

The current AC and DC specifications contained in this document are a combination of target design specifications, limited sampled empirical data, and some characterization data. Currently, this information does not represent all actu-

al guaranteed tested timing parameters. Guaranteed specifications will be provided after full device characterization. For more specific information regards DC and AC parameters, contact National Semiconductor.

### AC TTL PARAMETERS



#	Symbol	Description	Min	TYP	Max	Units
1	$t_{TCKP}$ (Note 1)	Transmit Clock Period ( $1/f = T$ : @50 MHz, $T = 20$ ns, @33 MHz, $T = 30$ ns (Note C))		$1/f$		ns
2	$t_{TCKPW}$ (Note 1)	Transmit Clock Pulse Width ( $f_{max} = 50$ MHz) (Note C)	$1/2f - 20\%$	$1/2f$	$1/2f + 20\%$	ns
3	$t_{TDS}$	Symbol and Type Set up to Clock High  (Note A) (Note B)	5 4	3.6		ns
4	$t_{TDH}$	Symbol and Type Hold Time (Note C)	3	0.7		ns
5	$t_{TOK}$	Clock High to TxOK Valid (Note A)		8.7	12	ns

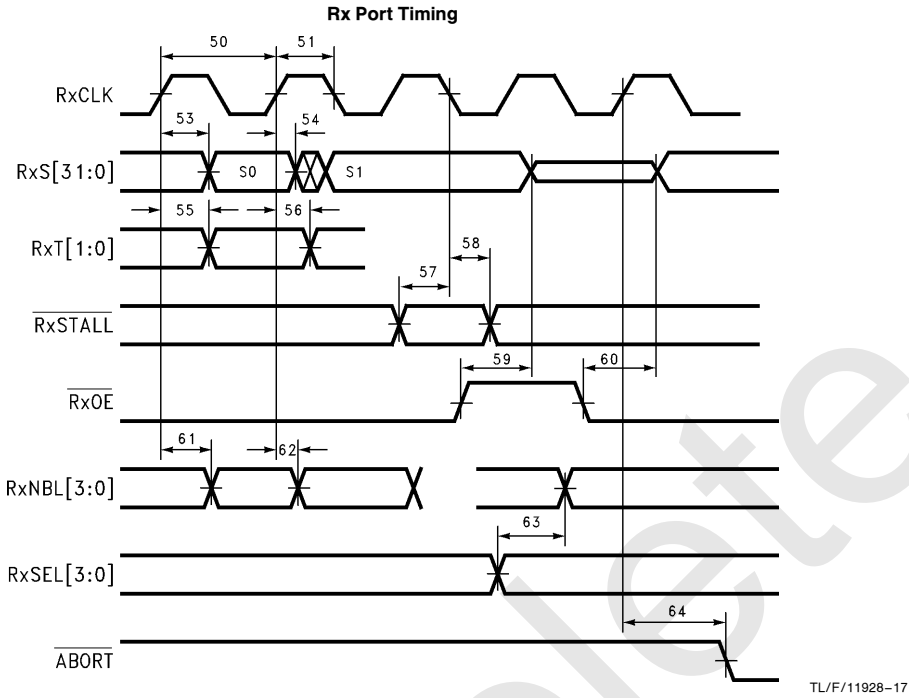
**Note 1:** This parameter is dependent on clock frequency.

**Note A:** Limit guaranteed by test program.

**Note B:** Limit based on simulation results.

**Note C:** Limit based on bench characterization.

## 14.0 AC Timing Parameters (Continued)



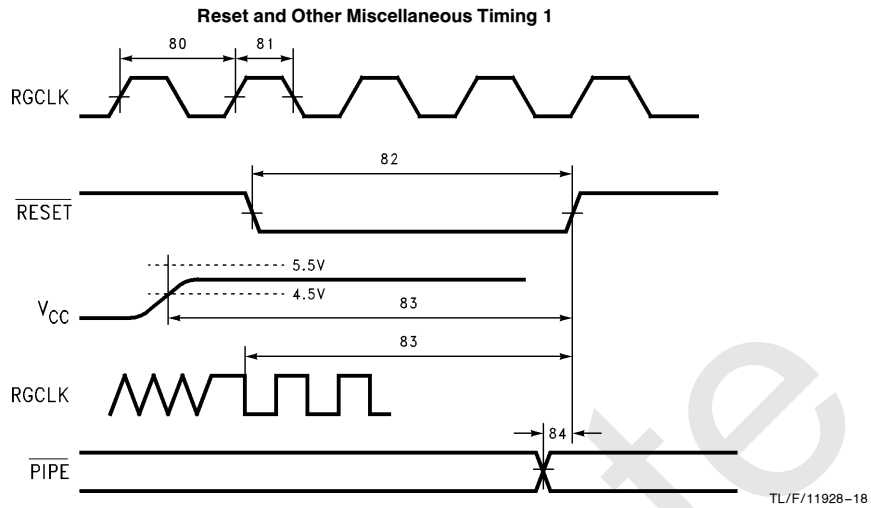
#	Symbol	Description	Min	Typ	Max	Units
50	$t_{RCKP}$ (Note 1)	Receive Clock Period (Note C)		$1/f$		ns
51	$t_{TRCKPW}$ (Note 1)	Receive Clock Pulse Width (Note C)	$1/2f-20\%$	$1/2f$	$1/2f + 20\%$	ns
53	$t_{RSACC}$	<b>Clock High to Symbol Access Time (Note A)</b>		13	16	ns
54	$t_{RSVAL}$	Symbol Valid after Clock High (Note C)	3	9.4		ns
55	$t_{RTACC}$	<b>Clock High to Type Access Time (Note A)</b>		14.2	15	ns
56	$t_{RTVAL}$	<b>Type Valid after Clock High (Note A)</b>	3	8.8		ns
57	$t_{RSTLS}$	$\overline{RxSTALL}$ Set up to Clock Low (Note C)	-2	-4		ns
58	$t_{RSTLH}$	$\overline{RxSTALL}$ Hold from Clock Low (Note C)	5	2.9		ns
59	$t_{RSHZ}$	$\overline{RxOE}$ Negated to Symbol TRI-STATE (Note C)		4.5	8	ns
60	$t_{RSLZ}$	$\overline{RxOE}$ Asserted to Symbol Low Z (Note C)		5	9	ns
61	$t_{RNBACC}$	<b>Clock High to NIBBLE Access Time (Note A)</b>		8.6	19	ns
62	$t_{RNBVAL}$	<b>NIBBLE Valid after Clock High (Note A)</b>	4	3		ns
63	$t_{RSELNB}$	<b>SELECT to NIBBLE Valid Access Time (Note A)</b>		14.6	18	ns
64	$t_{RABT}$	<b>Clock High to ABORT Valid (Note C)</b>		12.5	15	ns

**Note A:** Limit guaranteed by test program.

**Note B:** Limit based on simulation results.

**Note C:** Limit based on bench characterization.

## 14.0 AC Timing Parameters (Continued)



#	Symbol	Description	Min	Typ	Max	Units
80	$t_{RGCKP}$ (Note 1)	RGCLK Clock Period (Note C)		$1/f$		ns
81	$t_{RGCKPW}$ (Note 1)	RGCLK Clock pulse Width (Note C)	$1/2f - 20\%$	$1/2f$	$1/2f + 20\%$	ns
82	$t_{RSPW}$ (Note 1)	RESET Pulse Width (Note C) @50 MHz @33 MHz	230* 320*	100 150		ns ns
83	$t_{PLLS}$	Phase Lock Loop Set (Note B)	3**			ms
84	$t_{PIPES}$	PIPE Set Up Time to RESET (Note C)	0			ns

**Note 1:** This parameter is dependent on clock frequency.

\*At 50 MHz, i.e.,  $t_{RCKP} = t_{RGCKP} = t_{TCKP} = 20$  ns. Otherwise,  $t_{RSPW} = t_{RCKP} + 7(t_{RGCKP}) + t_{TCKP} + 50$  ns.

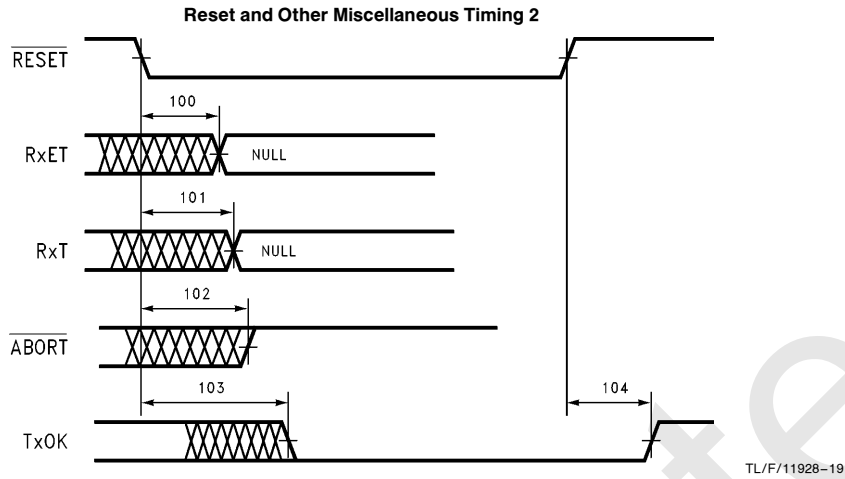
\*\*At one node, otherwise,  $t_{PLLS} = 1.5$  (node number + 1) ms.

**Note A:** Limit guaranteed by test program.

**Note B:** Limit based on simulation results.

**Note C:** Limit based on bench characterization.

## 14.0 AC Timing Parameters (Continued)



#	Symbol	Description	Min	Typ	Max	Units
100	$t_{RSET}$	$\overline{RESET}$ Asserted to RxET Valid (Note C)		25	55*	ns
101	$t_{RST}$	$\overline{RESET}$ Asserted to RxT Valid (Note C)		22	55*	ns
102	$t_{RSABT}$	$\overline{RESET}$ Asserted to $\overline{ABORT}$ Valid (Note C)		10.2	35	ns
103	$t_{RSTXOKN}$	$\overline{RESET}$ Asserted to TxOK Low (Note C)		14.6	35	ns
104	$t_{RSTXOK}$ (Note 1)	$\overline{RESET}$ Negated to TxOK High @50 MHz (Note C) @33 MHz (Note A)		150 220	191** 282**	ns ns

**Note 1:** This parameter is dependent on clock frequency.

\*At  $t_{RCKP} = 20$  ns. Otherwise  $t_{RSET} = t_{RST} = 2t_{RCKP} + 15$  ns.

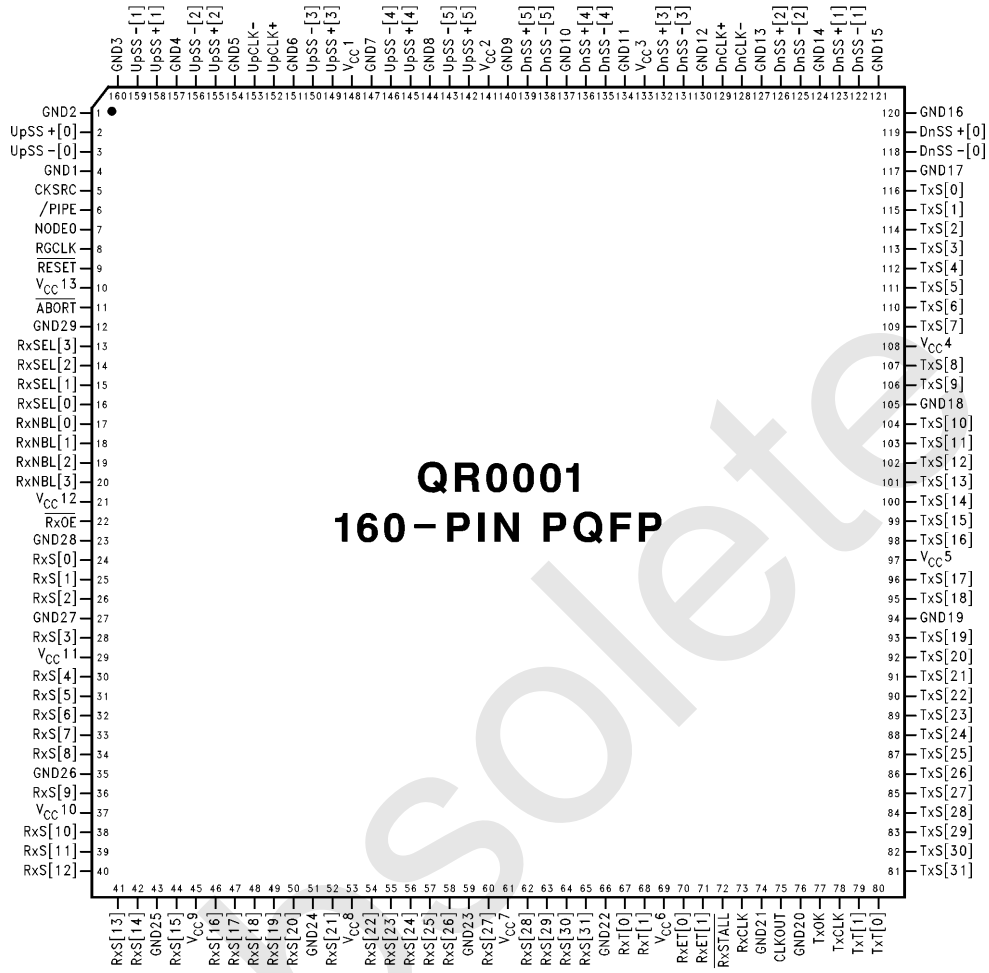
\*\*At 50 MHz i.e.,  $t_{RCKP} = t_{RGCKP} = t_{TCKP} = 20$  ns. Otherwise,  $t_{RSTXOKmax} = t_{RCKP} + 7t_{RGCKP} + t_{TCKP} + t_{TOK}$ .

**Note A:** Limit guaranteed by test program.

**Note B:** Limit based on simulation results.

**Note C:** Limit based on bench characterization.

# 15.0 Connection Diagram



TOP VIEW

Order Number: QR001-33VUL

TL/F/11928-20

## 16.0 Glossary

**bridge mode**—The ability to directly connect one QuickRing client port to another QuickRing client port. This will provide a hop path from one ring structure to another. (PIPE signal is negated.)

**hop fields**—The ring packet header has 5 fields allocated to address to different rings. If the fields are not used to hop rings, they can be used to identify separate data streams. This allows up to  $2^{20}$  individually identified data streams.

**hop path**—The means of moving from one QuickRing to another through a bridge connection. Hop fields in the header symbol provide the addressing to achieve the routing.

**initialization**—A user transparent process that begins upon reset release by all nodes. During initialization, nodes are assigned node ID numbers, then the total number of nodes on the ring is distributed to each node. The node address and total number of nodes is made available to the client. Reservation and packet transmissions may begin immediately following.

**Node0**—Node 0 is determined by the **Node0** pin being asserted. Node 0 governs the initialization process.

**ring of rings**—The result of connecting multiple rings together. Up to 5 QuickRings can be traversed by a packet because there are 5 hop fields in the header.

**symbol**—The ring transmission basic unit, on the ring. Each symbol consists of 42 bits; 2 type bits, 1 frame bit, 32 data bits, and 7 bits of error detection code. At the client ports, a symbol is a 32-bit value on RxS[31:0] or TxS[31:0].

**voucher**—On the ring, vouchers are sent by source nodes to obtain permission to launch packets of client generated payload symbols.

**ticket**—On the ring, tickets are returned by target nodes in response to vouchers. They indicate that the target has reserved FIFO space for one packet.

**packets**—On the ring, packets are limited to a size of 21. Each packet at least consists of 1 head symbol and 1 tail symbol/last symbol.

**Null**—Null is the encoding on the Type fields which indicates to ignore the associated symbol.

## 17.0 Revision Notes

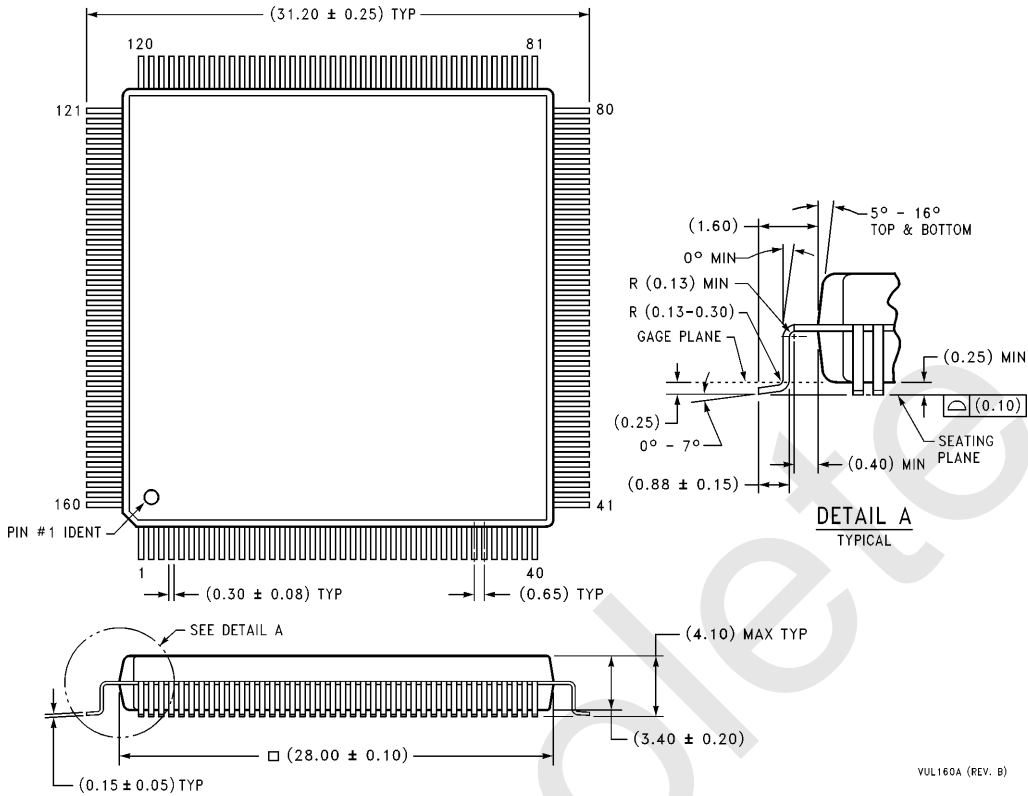
Following is a list of some of the changes that have been made between this version of the datasheet and the December 1993 version. This is not a complete list of the changes.

Change	Section
Maximum Data Transfer Rate	Front page
Client receive port operation	3.5.1
EDC error and client "abort" pin functionality	3.16
Resynchronizer issue	5.0
Multiple clock sources and ring with many nodes	5.0
Power and decoupling recommendations	12.0

Obsolete



**Physical Dimensions** inches (millimeters)



**160-Lead (28mm x 28mm) Molded Plastic Quad Flatpak, JEDEC NS Package Number VUL160A**

VUL160A (REV. B)

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2. A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.



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