### INTEGRATED CIRCUITS

# DATA SHEET



# **PCA9559**

5-bit multiplexed/1-bit latched 6-bit I<sup>2</sup>C EEPROM

Product data Supersedes data of 2000 Jan 31





### 5-bit multiplexed/1-bit latched 6-bit I<sup>2</sup>C EEPROM

PCA9559



#### **FEATURES**

- 5-bit 2-to-1 multiplexer, 1-bit latch
- 6-bit internal non-volatile register
- Internal non-volatile register programmable and readable via I<sup>2</sup>C bus
- Override input forces all outputs to logic 0
- 5 open drain multiplexed outputs
- 1 open drain non-multiplexed (latched) output
- 5V and 2.5V tolerant inputs
- Useful for 'jumperless' configuration of PC motherboards
- 2 address pins, allowing up to 4 devices on the I<sup>2</sup>C bus
- ESD protection exceeds 2000 V HBM per JESD22-A114,
   200 V MM per JESD22-A115 and 1000 V CDM per JESD22-C101
- Latch-up testing is done to JESDEC Standard JESD78 which exceeds 100 mA

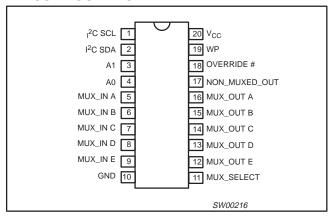
#### **DESCRIPTION**

The PCA9559 is a 20-pin CMOS device consisting of one 6-bit non-volatile EEPROM registers, 5 hardware pin inputs and a 5-bit multiplexed output with one latched EEPROM bit. It is used for DIP switch-free or jumper-less system configuration and supports Mobile and Desktop VID Configuration, where 2 preset values (1 set of internal non-volatile registers and 1 set of external hardware pins) set processor voltage for operation in either performance or deep sleep modes. The PCA9559 is also useful in server and telecom/networking applications when used to replace DIP switches or jumpers, since the settings can be easily changed via I<sup>2</sup>C/SMBus without having to power down the equipment to open the cabinet. The non-volatile memory retains the most current setting selected before the power is turned off.

The PCA9559 typically resides between the CPU and Voltage Regulator Module (VRM) when used for CPU VID (Voltage IDentification code) configuration. It is used to bypass the CPU-defined VID values and provide a different set of VID values to the VRM, if an increase in the CPU voltage is desired. An increase in CPU voltage combined with an increase in CPU frequency leads to a performance boost of up to 7.5%. Lower CPU voltage reduces power consumption.

The PCA9559 has 2 address pins allowing up to 4 devices to be placed on the same  $I^2C$  bus or SMBus.

#### **PIN CONFIGURATION**



#### **PIN DESCRIPTION**

PIN NUM- BER	SYMBOL	FUNCTION
1	I <sup>2</sup> C SCL	Serial I <sup>2</sup> C bus clock
2	I <sup>2</sup> C SDA	Serial bi-directional I <sup>2</sup> C bus data
3	A1 Address	A1
4	A0 Address	A0
5–9	MUX_IN A-E	External inputs to multiplexer
10	GND	Ground
11	MUX_SELECT	Selects MUX_IN inputs or register contents for MUX_OUT outputs
12–16	MUX_OUT E-A	Open drain multiplexed outputs
17	NON_MUXED_ OUT	Open drain outputs from non-volatile memory
18	OVERRIDE#	Forces all outputs to logic 0
19	WP	Non-volatile register write-protect
20	V <sub>CC</sub>	Power supply: +3.0 to +3.6 V

#### ORDERING INFORMATION

PACKAGES	TEMPERATURE RANGE	ORDER CODE	DRAWING NUMBER		
20-Pin Plastic TSSOP	0 to +70 °C	PCA9559PW	SOT360-1		

Standard packing quantities and other packaging data is available at www.philipslogic.com/packaging.

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#### **FUNCTIONAL DESCRIPTION**

When the MUX\_SELECT signal is logic 0, the multiplexer will select the data from the non-volatile register to drive on the MUX\_OUT pins. When the MUX\_SELECT signal is logic 1, the multiplexer will select the MUX\_IN lines to drive on the MUX\_OUT pins. The MUX\_SELECT signal is also used to latch the NON\_MUXED\_OUT signal which outputs data from the non-volatile register. The NON\_MUXED\_OUT signal latch is transparent when MUX\_SELECT is in a logic 0 state, and will latch data when MUX\_SELECT is in a logic 1 state. When the active-LOW OVERRIDE# signal is set to logic 0 and the MUX\_SELECT signal is at a logic 0, all outputs will be driven to logic 0. This information is summarized in Table 1.

The Write Protect (WP) input is used to control the ability to write the contents of the 6-bit non-volatile register. If the WP signal is logic 0, the I<sup>2</sup>C bus will be able to write the contents of the non-volatile register. If the WP signal is logic 1, data will not be allowed to be written into the non-volatile register.

The factory default for the contents of the non-volatile register are all logic 0. These stored values can be read or written using the I<sup>2</sup>C bus (described in the next section).

The OVERRIDE#, WP, MUX\_IN, and MUX\_SELECT signals have internal pullup resistors. See the DC and AC Characteristics for hysteresis and signal spike suppression figures.

#### **FUNCTION TABLE**

OVERRIDE#	MUX_SELECT	MUX_OUT OUTPUTS	NON_MUXED_OUT OUTPUT		
0	0	All 0's	All 0's		
0	1	MUX_IN inputs	Latched NON_MUXED_OUT <sup>1</sup>		
1	0	From non- volatile register	From non-volatile register		
1	1	MUX_IN inputs	From non-volatile register		

#### NOTE:

 NON\_MUXED\_OUT state will be the value present on the output at the time of the MUX\_SELECT input transitioned from a logic 0 to a logic 1 state.

#### **POWER-ON RESET**

When power is applied to  $V_{CC}$ , an internal power-on reset holds the PCA9559 in a reset state until  $V_{CC}$  has reached  $V_{POR}$ . At that point, the reset condition is released and the PCA9559 registers and  $I^2C/SMBus$  state machine will initialize to their default states.

#### I<sup>2</sup>C INTERFACE

Communicating with this device is initiated by sending a valid address on the I<sup>2</sup>C bus. The address format (see Flgure 1) has 5 fixed bits and two user-programmable bits followed by a 1-bit read/write value which determines the direction of the data transfer.

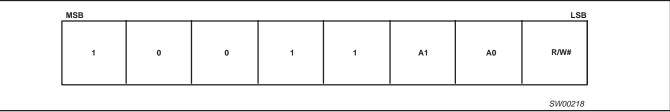


Figure 1. I<sup>2</sup>C Address Byte

Following the address and acknowledge bit are 8 data bits which, depending on the read/write bit in the address, will read data from or write data to the non-volatile register. Data will be written to the register if the read/write bit is logic 0 and the WP input is logic 0. Data will be read from the register if the bit is logic 1. The four high-order bits are latched outputs, while the four low order bits are multiplexed outputs (Figure 2).

#### NOTE:

To ensure data integrity, the non-volatile register must be internally write protected when V<sub>CC</sub> to the I<sup>2</sup>C bus is powered down or V<sub>CC</sub> to the component is dropped below normal operating levels.

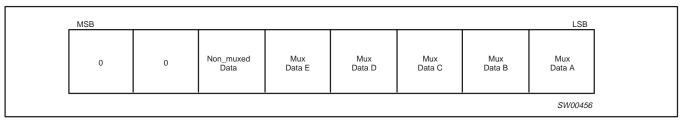
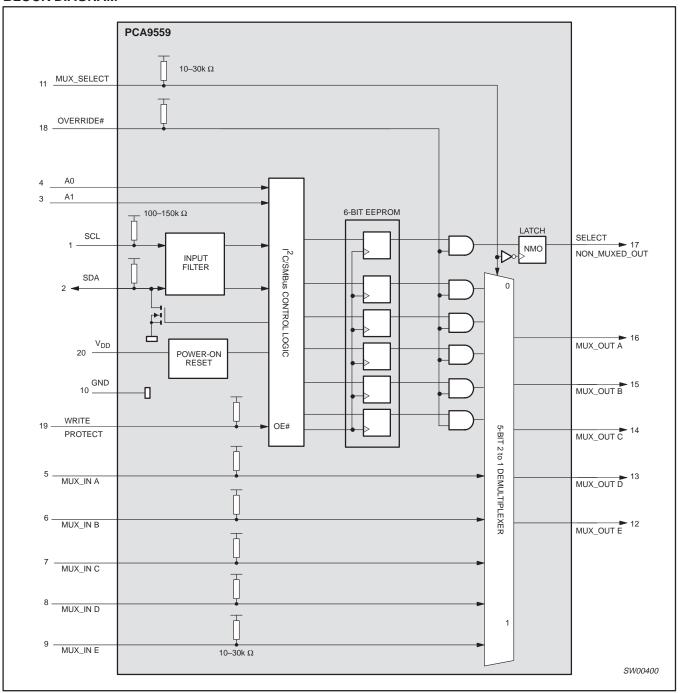


Figure 2. I<sup>2</sup>C Data Byte

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#### **BLOCK DIAGRAM**



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#### ABSOLUTE MAXIMUM RATINGS1, 2

In accordance with the Absolute Maximum Rating System (IEC 134)

Voltages are referenced to GND (ground = 0 V)

SYMBOL	PARAMETER	PARAMETER CONDITIONS			
V <sub>CC</sub>	DC supply voltage		-0.5 to +4.6	V	
VI	DC input voltage	Note 3	–1.5 to V <sub>CC</sub> +1.5	V	
V <sub>OUT</sub>	DC output voltage	Note 3	–0.5 to V <sub>CC</sub> +0.5	V	
T <sub>stg</sub>	Storage temperature range		-60 to +150	°C	

#### NOTES

1. Stresses beyond those listed may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

2. The performance capability of a high-performance integrated circuit in conjunction with its thermal environment can create junction temperatures which are detrimental to reliability. The maximum junction temperature of this integrated circuit should not exceed 150°C.

3. The input and output voltage ratings may be exceeded if the input and output current ratings are observed.

#### RECOMMENDED OPERATING CONDITIONS

SYMBOL	PARAMETER	CONDITIONS	LIM	UNIT	
STMBOL	PARAMETER	CONDITIONS	MIN	MAX	UNII
V <sub>CC</sub>	DC supply voltage		3.0	3.6	V
	V <sub>IL</sub>	I <sub>OL</sub> = 3 mA	-0.5	0.9	V
SCL, SDA	$V_{IH}$	I <sub>OL</sub> = 3 mA	2.7	4.0	V
SCL, SDA	V <sub>OL</sub>	I <sub>OL</sub> = 3 mA	_	0.4	V
	V <sub>OL</sub>	I <sub>OL</sub> = 6 mA	_	0.6	V
OVERRIDE#, MUX_IN,	$V_{IL}$		-0.5	0.8	V
MUX_SELECT	$V_{IH}$		2.0	4.0	V
MUX_OUT, NON_MUXED_OUT	I <sub>OL</sub>		_	8	mA
MOX_OO1, NON_MOXED_OO1	I <sub>OH</sub>		_	100	μΑ
dt/dv	Input transition rise or fall time		0	10	ns/V
T <sub>amb</sub>	Operating temperature		0	70	°C

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#### **DC CHARACTERISTICS**

SYMBOL	PARAMETER	TEST COMPITION		LIMITS		LINIT	
- AKAMETEK		TEST CONDITION	MIN.	TYP.	MAX.	UNIT	
Supply							
V <sub>CC</sub>	Supply Voltage		3	_	3.8	V	
I <sub>CCL</sub>	Supply Current	Operating mode ALL inputs = 0 V	T -	_	10	mA	
Іссн	Supply Current	Operating mode ALL inputs = V <sub>CC</sub>	_	_	600	μΑ	
V <sub>POR</sub>	Power-on Rest Voltage	no load; V <sub>I</sub> = V <sub>CC</sub> or GND	T -	1.9	2.6	V	
Input SCL:	Input/Output SDA						
V <sub>IL</sub>	Low Level Input Voltage		-0.5	_	0.8	V	
V <sub>IH</sub>	High Level Input Voltage		2	_	V <sub>CC</sub> + 0.5	V	
I <sub>OL</sub>	Low Level Output Current	V <sub>OL</sub> = 0.4	3	_		mA	
I <sub>OL</sub>	Low Level Output Current	V <sub>OL</sub> = 0.6	6	_		mA	
I <sub>IH</sub>	Leakage Current High	$V_I = V_{CC}$	-1.5	_	-12	μА	
I <sub>IL</sub>	Leakage Current Low	V <sub>I</sub> = GND	-7	_	-32	μА	
Cı	Input Capacitance		_	_	10	pF	
Override #,	WP, Mux_Select		•				
I <sub>IH</sub>	Leakage Current High	$V_I = V_{CC}$	-20	l –	-100	μΑ	
I <sub>IL</sub>	Leakage Current Low	V <sub>I</sub> = GND	-86	_	-267	μА	
C <sub>I</sub>	Input Capacitance		_	_	10	pF	
Mux A $\rightarrow$ E							
I <sub>IH</sub>	Leakage Current High	$V_I = V_{CC}$	-0.166	_	-0.75	mA	
I <sub>IL</sub>	Leakage Current Low	V <sub>I</sub> = GND	-0.72	_	-2	mA	
Cı	Input Capacitance		_	_	10	pF	
A0, A1 Inpu	its		•				
I <sub>IH</sub>	Leakage Current High	$V_I = V_{CC}$	-1	_	1	μА	
I <sub>IL</sub>	Leakage Current Low	V <sub>I</sub> = GND	-1	_	1	μА	
C <sub>I</sub>	Input Capacitance		_	_	10	pF	
Mux_Outpu	its						
V <sub>OL</sub>	Low Level Output Current	(I <sub>OL</sub> = 100 μA)	_	_	0.4	V	
V <sub>OL</sub>	Low Level Output Current	(I <sub>OL</sub> = 2 mA)	_	_	0.7	V	
Non_Mux_0	Output				•		
V <sub>OL</sub>		(I <sub>OL</sub> = 100 μA)	<u> </u>	_	0.4	V	
V <sub>OL</sub>		(I <sub>OL</sub> = 2 mA)	<u> </u>		0.7	V	

#### NOTES:

#### NON-VOLATILE STORAGE SPECIFICATIONS

PARAMETER	SPECIFICATION		
Memory cell data retention	10 years min		
Number of memory cell write cycles	3,000 cycles min		

<sup>1.</sup>  $V_{\mbox{\scriptsize HYS}}$  is the hysteresis of Schmitt-Trigger inputs

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#### **AC CHARACTERISTICS**

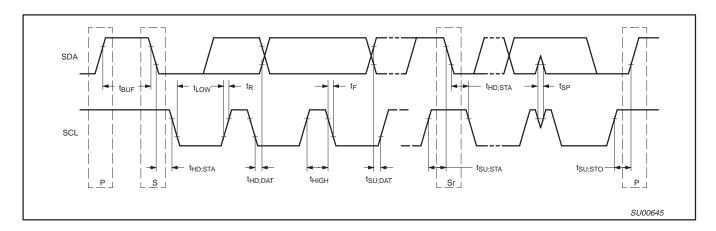
SYMBOL	PARAMETER		UNIT		
STWIBOL	PARAMETER	MIN.	TYP.	MAX.	] UNII
/IUX_in ⇒ MUX	_out				
T <sub>plh</sub>		_	28	37	nS
T <sub>phl</sub>		_	16	21	nS
Select ⇒ MUX_c	out				
T <sub>plh</sub>		_	30	39	nS
T <sub>phl</sub>		_	17	22	nS
Override ⇒ Nor	I-MUX_out				
T <sub>plh</sub>		_	34	43	nS
T <sub>phl</sub>		_	19	25	nS
Override ⇒ MU	X_out	•	•	•	•
T <sub>plh</sub>		_	31	41	nS
T <sub>phl</sub>		_	21	27	nS
T <sub>R</sub>	Output rise time	1.0	_	3	ns/V
T <sub>F</sub>	Output fall time	1.0	_	3	ns/V
P <sub>F</sub>	Pull-up resistor for outputs	1.0	_	<u> </u>	ns/V
CL	Test load capacitance on outputs	_	_	_	pF
<sup>2</sup> C Bus					
tscl	SCL clock frequency	10	T -	400	kHz
t <sub>BUF</sub>	Bus free time between a STOP and a START condition	1.3	_	_	μs
t <sub>HD:STA</sub>	Hold time (repeated) START condition. After this period, the first clock pulse is generated	600	_	_	ns
t <sub>LOW</sub>	LOW period of SCL clock	1.3	<u> </u>	<u> </u>	μs
t <sub>HIGH</sub>	HIGH period of SCL clock	600	<u> </u>	-12	ns
t <sub>SU:STA</sub>	Set-up time for a repeated START condition	600	_	-32	ns
t <sub>HD:DAT</sub>	Data hold time	0	_	10	ns
t <sub>SU:DAT</sub>	Data set-up time	100	<u> </u>	-100	ns
t <sub>SP</sub>	Data spike time	0	<u> </u>	50	ns
t <sub>SU:STO</sub>	Set-up time for STOP condition	600	<del>                                     </del>	10	ns
t <sub>R</sub>	Rise time for both SDA and SCL signals (10 – 400 pF bus)	20	<u> </u>	300	ns
t <sub>l</sub>	Fall time for both SDA and SCL signals (10 – 400 pF bus)	20	<u> </u>	300	ns
C <sub>L</sub>	Capacitive load for each bus line	_	<u> </u>	400	pF
T <sub>W</sub>	Write cycle time <sup>1</sup>		15	<del> </del>	mS

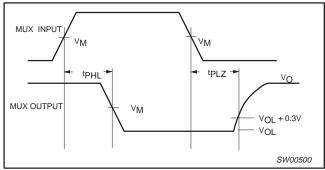
NOTE:

<sup>1.</sup> WRITE CYCLE time can only be measured indirectly during the write cycle. During this time, the device will not acknowledge its I<sup>2</sup>C Address.

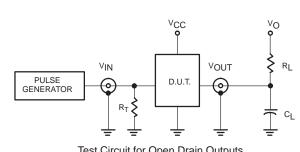
### 5-bit multiplexed/1-bit latched 6-bit I<sup>2</sup>C EEPROM

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Waveform 1. Open drain output enable and disable times



#### Test Circuit for Open Drain Outputs

#### **DEFINITIONS**

 $R_L$  = Load resistor; 1 k $\Omega$ 

Load capacitance includes jig and probe capacitance;

 $R_T = \begin{array}{ll} \text{Termination resistance should be equal to $Z_{OUT}$ of pulse generators.} \end{array}$ 

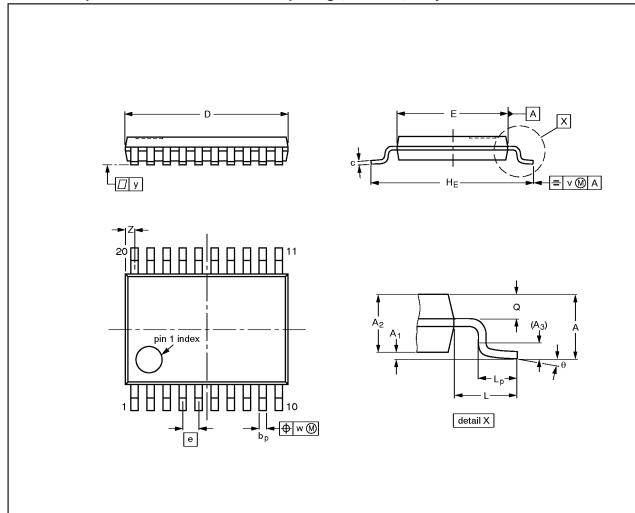
SW00510

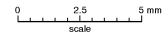
## 5-bit multiplexed/1-bit latched 6-bit I<sup>2</sup>C EEPROM

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TSSOP20: plastic thin shrink small outline package; 20 leads; body width 4.4 mm

SOT360-1





#### DIMENSIONS (mm are the original dimensions)

UNIT	A max.	A <sub>1</sub>	A <sub>2</sub>	Аз	рb	С	D <sup>(1)</sup>	E <sup>(2)</sup>	е	HE	L	Lp	Q	v	w	у	Z <sup>(1)</sup>	θ
mm	1.10	0.15 0.05	0.95 0.80	0.25	0.30 0.19	0.2 0.1	6.6 6.4	4.5 4.3	0.65	6.6 6.2	1.0	0.75 0.50	0.4 0.3	0.2	0.13	0.1	0.5 0.2	8° 0°

#### Notes

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

OUTLINE		REFER	EUROPEAN	ISSUE DATE		
VERSION	IEC	JEDEC	EIAJ		PROJECTION	ISSUE DATE
SOT360-1		MO-153AC				<del>-93-06-16</del> 95-02-04

2002 May 24 9

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Purchase of Philips I<sup>2</sup>C components conveys a license under the Philips' I<sup>2</sup>C patent to use the components in the I<sup>2</sup>C system provided the system conforms to the I<sup>2</sup>C specifications defined by Philips. This specification can be ordered using the code 9398 393 40011.

#### Data sheet status

Data sheet status <sup>[1]</sup>	Product status <sup>[2]</sup>	Definitions
Objective data	Development	This data sheet contains data from the objective specification for product development.  Philips Semiconductors reserves the right to change the specification in any manner without notice.
Preliminary data	Qualification	This data sheet contains data from the preliminary specification. Supplementary data will be published at a later date. Philips Semiconductors reserves the right to change the specification without notice, in order to improve the design and supply the best possible product.
Product data	Production	This data sheet contains data from the product specification. Philips Semiconductors reserves the right to make changes at any time in order to improve the design, manufacturing and supply. Changes will be communicated according to the Customer Product/Process Change Notification (CPCN) procedure SNW-SQ-650A.

<sup>[1]</sup> Please consult the most recently issued data sheet before initiating or completing a design.

#### **Definitions**

**Short-form specification** — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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<sup>[2]</sup> The product status of the device(s) described in this data sheet may have changed since this data sheet was published. The latest information is available on the Internet at URL http://www.semiconductors.philips.com.