



PRELIMINARY

PROCESSED TO MIL-STD-883, METHOD 5004,
CLASS B, 16,384 x 1 BIT-DYNAMIC RAM
MKB4516(P/J/E) - 80/81/82

FEATURES

- Military temperature range: $-55^{\circ}\text{C} \leq T_C \leq +110^{\circ}\text{C}$
- Recognized industry standard 16-pin configuration from Mostek
- Single +5 V ($\pm 10\%$) supply operation
- On chip substrate bias generator for optimum performance
- 100 ns access time, 235 ns cycle time (MKB4516-80)
120 ns access time, 270 ns cycle time (MKB4516-81)
150 ns access time, 320 ns cycle time (MKB4516-82)
- Common I/O capability using "early write"
- Interchangeable with M2118
- Read, Write, Read-Write, Read-Modify-Write and Page-Mode capability
- All inputs TTL compatible, low capacitance, and are protected against static charge
- Scaled POLY 5 technology
- Pin compatible with the MKB4564 (64K RAM)
- 128 refresh cycles (2 msec)
- Available to the DESC part number 8101501EX
- Indefinite D_{OUT} hold using \overline{CAS} control

DESCRIPTION

The MKB4516 is a single +5 V power supply version of the industry standard MKB4116, 16,384 x 1 bit dynamic RAM.

The high performance features of the MKB4516 are achieved by state-of-the-art circuit device techniques as well as utilization of Mostek's "Scaled POLY 5" process technology. Features include access times starting where the current generation 16K RAMs leave off, TTL compatibility, and +5 V operation.

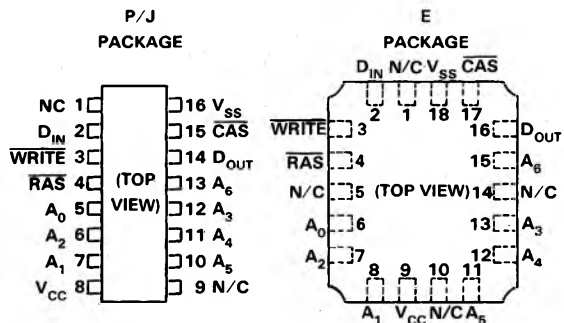
The MKB4516 is capable of a variety of operations including READ, WRITE, READ-WRITE, READ-MODIFY-WRITE, PAGE MODE, and REFRESH. The output of the MKB4516 can be held valid indefinitely by holding \overline{CAS} active low. This is quite useful since a refresh cycle can be performed while holding data valid from a previous cycle.

The MKB4516 is designed to be compatible with JEDEC standards for the 64K x 1 dynamic RAM. It is intended to extend the life cycle of the 16K RAM, as well as create new applications due to its superior performance. Compatibility with the MKB4564 will also permit a common board design to service both the MKB4516 and the MKB4564 (64K RAM) designs. The MKB4516 will therefore permit a smoother transition to the 64K RAM as the industry standard MKB4027 did for the MKB4116.

The small memory user need no longer pay a three power supply penalty for achieving the economics of using dynamic RAM over static RAM with this new generation device.

PIN OUT

Figure 1



PIN FUNCTIONS

| | | | |
|------------------|---------------------|--------------------|--------------------|
| $A_0 - A_6$ | Address Inputs | \overline{RAS} | Row Address Strobe |
| \overline{CAS} | Col. Address Strobe | \overline{WRITE} | Read/Write Input |
| D_{IN} | Data In | \overline{RFSH} | Refresh |
| D_{OUT} | Data Out | V_{CC} | Power (+5 V) |
| NC | Not Connected | V_{SS} | GND |

ABSOLUTE MAXIMUM RATINGS*

Voltage on V_{CC} Supply Relative to V_{SS} -2.0 V to +7.0 V
 Operating Temperature, T_C (Case) -55°C to +110°C
 Storage Temperature -65°C to +150°C
 Power Dissipation 1 Watt
 Short Circuit Output Current 50 mA

*Stresses greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

RECOMMENDED DC OPERATING CONDITIONS

(-55°C ≤ T_C ≤ 110°C)

| SYM | PARAMETER | MIN | TYP | MAX | UNITS | NOTES |
|----------|---|------|-----|---------------|-------|-------|
| V_{CC} | Supply Voltage | 4.5 | 5.0 | 5.5 | V | 2 |
| V_{IH} | Input High (Logic 1) Voltage, All Inputs | 2.4 | — | V_{CC}^{+1} | V | 2 |
| V_{IL} | Input Low (Logic 0) Voltage, All Inputs | -2.0 | — | .8 | V | 2,17 |

DC ELECTRICAL CHARACTERISTICS

(-55°C ≤ T_C ≤ 110°C)

| SYM | PARAMETER | MIN | MAX | UNITS | NOTES |
|----------------------|--|-----|-----|---------------|-------|
| I_{CC1} | OPERATING CURRENT Average power supply operating current (\overline{RAS} , \overline{CAS} cycling, $t_{RC} = t_{RC \text{ min.}}$) | | 38 | mA | 3 |
| I_{CC1} | Operating Current ($T_C = 110^\circ\text{C}$) | | 30 | mA | 3,18 |
| I_{CC2} | STANDBY CURRENT Power supply standby current ($\overline{RAS} = \overline{CAS} = V_{IH}$ $D_{OUT} = \text{High Impedance}$) | | 4 | mA | |
| I_{CC3} | \overline{RAS} ONLY REFRESH CURRENT Average Power Supply current, refresh mode (\overline{RAS} cycling, $\overline{CAS} = V_{IH}$; $t_{RC} = \text{min.}$) | | 32 | mA | 3 |
| I_{CC4} | PAGE MODE CURRENT Average power supply current, page mode operation ($\overline{RAS} = V_{IL}$, $t_{RAS} = t_{RAS \text{ max.}}$, \overline{CAS} cycling; $t_{PC} = t_{PC \text{ min.}}$) | | 35 | mA | 3 |
| $I_{IL(L)}$ | INPUT LEAKAGE Input leakage current, any input ($0 \text{ V} \leq V_{IN} \leq +5.5 \text{ V}$, all other pins not under test = 0 volts) | -10 | 10 | μA | |
| $I_{OL(L)}$ | OUTPUT LEAKAGE Output leakage current (D_{OUT} is disabled, $0 \text{ V} \leq V_{OUT} \leq +5.5 \text{ V}$) | -10 | 10 | μA | |
| V_{OH} V_{OL} | OUTPUT LEVELS Output High (Logic 1) voltage ($I_{OUT} = -5 \text{ mA}$) Output Low (Logic 0) voltage ($I_{OUT} = 4.2 \text{ mA}$) | 2.4 | 0.4 | V V | |

AC ELECTRICAL CHARACTERISTICS AND RECOMMENDED OPERATION CONDITIONS (4, 5, 9)

(-55°C ≤ T_C ≤ 110°C), V_{CC} = 5.0 V ± 10%

| SYMBOL | | PARAMETER | MK4516-80 | | MK4516-81 | | MK4516-82 | | UNITS | NOTES |
|------------------------------|------------------|--|-----------|-----------------|-----------|-----------------|-----------|-----------------|-------|-------|
| STD | ALT | | MIN | MAX | MIN | MAX | MIN | MAX | | |
| t _{RELREL} | t _{RC} | Random read or write cycle time | 235 | | 270 | | 320 | | ns | 6 |
| t _{RELREL} (RMW) | t _{RMW} | Read-modify-write cycle time | 285 | | 320 | | 410 | | ns | 6 |
| t _{RELREL} (PC) | t _{PC} | Page mode cycle time | 125 | | 145 | | 190 | | ns | 6 |
| t _{RELOV} | t _{RAC} | Access time from $\overline{\text{RAS}}$ | | 100 | | 120 | | 150 | ns | 7 |
| t _{CELOV} | t _{CAC} | Access time from $\overline{\text{CAS}}$ | | 55 | | 65 | | 80 | ns | 8 |
| t _{CEHOZ} | t _{OFF} | Output buffer turn-off delay | 0 | 45 | 0 | 50 | 0 | 60 | ns | 9 |
| t _T | t _T | Transition time (rise and fall) | 3 | 50 | 3 | 50 | 3 | 50 | ns | 5 |
| t _{REHREL} | t _{RP} | RAS precharge time | 110 | | 120 | | 135 | | ns | |
| t _{RELREH} | t _{RAS} | RAS pulse width | 115 | 10 ⁴ | 140 | 10 ⁴ | 175 | 10 ⁴ | ns | |
| t _{CELREH} | t _{RSH} | $\overline{\text{RAS}}$ hold time | 70 | | 85 | | 105 | | ns | |
| t _{RELCEH} | t _{CSH} | CAS hold time | 100 | | 120 | | 165 | | ns | |
| t _{CELCEH} | t _{CAS} | $\overline{\text{CAS}}$ pulse width | 55 | 10 ⁴ | 65 | 10 ⁴ | 95 | 10 ⁴ | ns | |
| t _{RELCEL} | t _{RCD} | RAS to $\overline{\text{CAS}}$ delay time | 25 | 45 | 25 | 55 | 25 | 70 | ns | 10 |
| t _{REHWX} | t _{RRH} | Read command hold time referenced to RAS | 0 | | 0 | | 0 | | ns | 11 |
| t _{AVREL} | t _{ASR} | Row Address set-up time | 0 | | 0 | | 0 | | ns | |
| t _{RELAX} | t _{RAH} | Row Address hold time | 15 | | 15 | | 15 | | ns | |
| t _{AVCEL} | t _{ASC} | Column Address set-up time | 0 | | 0 | | 0 | | ns | |
| t _{CELAX} | t _{CAH} | Column Address hold time | 15 | | 15 | | 20 | | ns | |
| t _{RELA(C)X} | t _{AR} | Column Address hold time referenced to RAS | 60 | | 70 | | 90 | | ns | |
| t _{WHCEL} | t _{RCS} | Read command set-up time | 0 | | 0 | | 0 | | ns | |
| t _{CEHWX} | t _{RCH} | Read command hold time referenced to $\overline{\text{CAS}}$ | 0 | | 0 | | 0 | | ns | 11 |
| t _{CELWX} | t _{WCH} | Write command hold time | 25 | | 30 | | 45 | | ns | |
| t _{RELWX} | t _{WCR} | Write command hold time referenced to RAS | 70 | | 85 | | 115 | | ns | |
| t _H | t _{WP} | Write command pulse width | 25 | | 30 | | 50 | | ns | |
| t _{WLREH} | t _{RWL} | Write command to $\overline{\text{RAS}}$ lead time | 60 | | 65 | | 110 | | ns | |
| t _{WLCEH} | t _{CWL} | Write command to $\overline{\text{CAS}}$ lead time | 45 | | 50 | | 100 | | ns | |

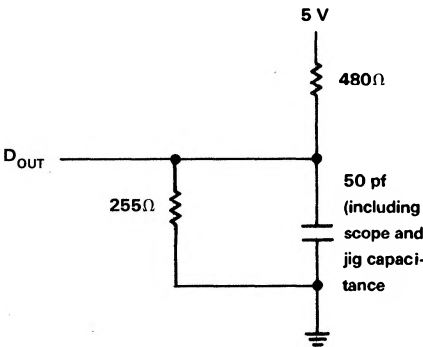
AC ELECTRICAL CHARACTERISTICS AND RECOMMENDED OPERATING CONDITIONS (Continued)

| SYMBOL | | PARAMETER | MK4516-10 | | MK4516-12 | | MK4516-15 | | UNITS | NOTES |
|-----------------------------|------------------|--|-----------|-----|-----------|-----|-----------|-----|-------|-------|
| STD | ALT | | MIN | MAX | MIN | MAX | MIN | MAX | | |
| t _{DVCEL} | t _{DS} | Data-in set-up time | 0 | | 0 | | 0 | | ns | 12 |
| t _{CELDX} | t _{DH} | Data-in hold time | 25 | | 30 | | 45 | | ns | 12 |
| t _{RELDX} | t _{DHR} | Data-in hold time referenced to RAS | 70 | | 85 | | 115 | | ns | |
| t _{CEHCEL} (PC) | t _{CP} | CAS precharge time (for page mode cycle only) | 60 | | 70 | | 85 | | ns | |
| t _{RVRV} | t _{REF} | Refresh period | | 2 | | 2 | | 2 | ms | |
| t _{WLCEL} | t _{WCS} | WRITE command set-up time | 0 | | 0 | | 0 | | ns | 13 |
| t _{CELWL} | t _{CWD} | CAS to WRITE delay | 55 | | 65 | | 80 | | ns | 13 |
| t _{RELWL} | t _{RWD} | RAS to WRITE delay | 100 | | 120 | | 150 | | ns | 13 |
| t _{CEHREL} | t _{CRP} | CAS to RAS precharge time | 0 | | 0 | | 0 | | ns | |

AC TEST CONDITIONS

Input Levels0 V to 3.0 V
Transition times 5 ns
Input timing reference level1.5 V
Output timing reference levels0.8 V - 2.0 V
Output loadSee figure

OUTPUT LOAD



CAPACITANCE

($-55^{\circ}\text{C} \leq T_C \leq 110^{\circ}\text{C}$) ($V_{CC} = 5.0\text{ V} \pm 10\%$)

| SYMBOL | PARAMETER | TYP | MAX | UNITS | NOTES |
|----------|---|-----|-----|-------|-------|
| C_{11} | Input ($A_0 - A_5$, D_{IN}) | 4 | 5 | pF | 15 |
| C_{12} | Input $\overline{\text{RAS}}$, $\overline{\text{CAS}}$, $\overline{\text{WRITE}}$ | 8 | 10 | pF | 15 |
| C_0 | Output (D_{OUT}) | 5 | 7 | pF | 15,16 |

NOTES:

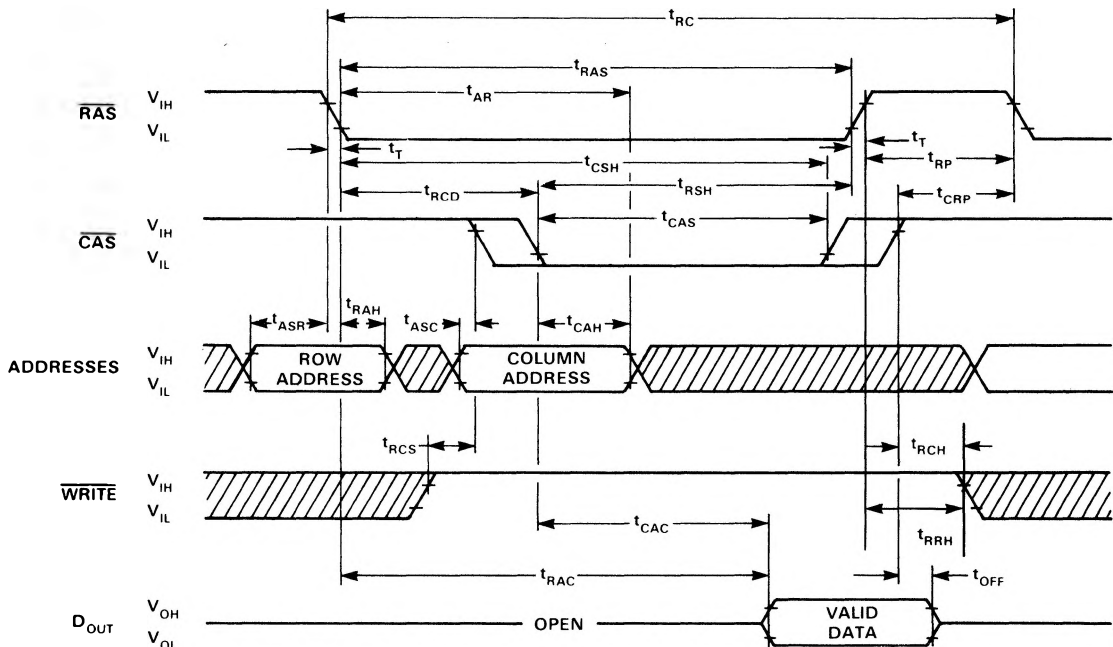
1. No user connection to Pin 1 (Leadless Chip Carrier only). This pin must be left floating.
2. All voltages referenced to V_{SS} .
3. I_{CC} is dependent on output loading and cycle rates. Specified values are obtained with the output open.
4. An initial pause of 500 μs is required after power-up followed by any 8 $\overline{\text{RAS}}$ cycles before proper device operation is achieved. $\overline{\text{RAS}}$ may be cycled during the initial pause.
5. V_{IH} min. and V_{IL} max are reference levels for measuring timing of input signals. Transition times are measured between V_{IH} and V_{IL} .
6. The minimum specifications are used only to indicate cycle time at which proper operation over the full temperature range ($-55^{\circ}\text{C} \leq T_C \leq +110^{\circ}\text{C}$) is assigned.
7. Assumes that $t_{RCD} \leq t_{RCD}(\text{max})$. If t_{RCD} is greater than the maximum recommended value shown in this table, t_{RAC} will increase by the amount that t_{RCD} exceeds the value shown.
8. Assumes that $t_{RCD} \geq t_{RCD}(\text{max})$.
9. t_{OFF} max defines the time at which the output achieves the open circuit condition and is not referenced to V_{OH} or V_{OL} .
10. Operation within the $t_{RCD}(\text{max})$ limit insures that $t_{RAC}(\text{max})$ can be met. $t_{RCD}(\text{max})$ is specified as a reference point only; if t_{RCD} is greater than the

specified $t_{RCD}(\text{max})$ limit, then access time is controlled exclusively by t_{CAC} .

11. Either t_{RRH} or t_{RCH} must be satisfied for a read cycle.
12. These parameters are referenced to $\overline{\text{CAS}}$ leading edge in early write cycles and to $\overline{\text{WRITE}}$ leading edge in delayed write or read-modify-write.
13. t_{WCS} , t_{CWD} , and t_{RWD} are restrictive operating parameters in READ/WRITE and READ/MODIFY/WRITE cycles only. If $t_{WCS} \geq t_{WCS}(\text{min})$ the cycle is an EARLY WRITE cycle and the data output will remain open circuit throughout the entire cycle. If $t_{CWD} \geq t_{CWD}(\text{min})$ and $t_{RWD} \geq t_{RWD}(\text{min})$ the cycle is a READ/WRITE and the data output will contain data read from the selected cell. If neither of the above conditions are met the condition of the data out (at access time and until $\overline{\text{CAS}}$ goes back to V_{IH}) is indeterminate.
14. The transition time specification applies for all input signals. In addition to meeting the transition rate specification, all input signals must transmit between V_{IH} and V_{IL} (or between V_{IL} and V_{IH}) in a monotonic manner.
15. Effective capacitance calculated from the equation $c = \frac{I \Delta T}{\Delta V}$ with $\Delta V = 3\text{ volts}$ and power supply at nominal level. This parameter is sample tested only.
16. $\overline{\text{CAS}} = V_{IH}$ D_{OUT} .
17. Includes the dc level and all instantaneous signal excursions.
18. Power consumption decreases with increasing temperature.

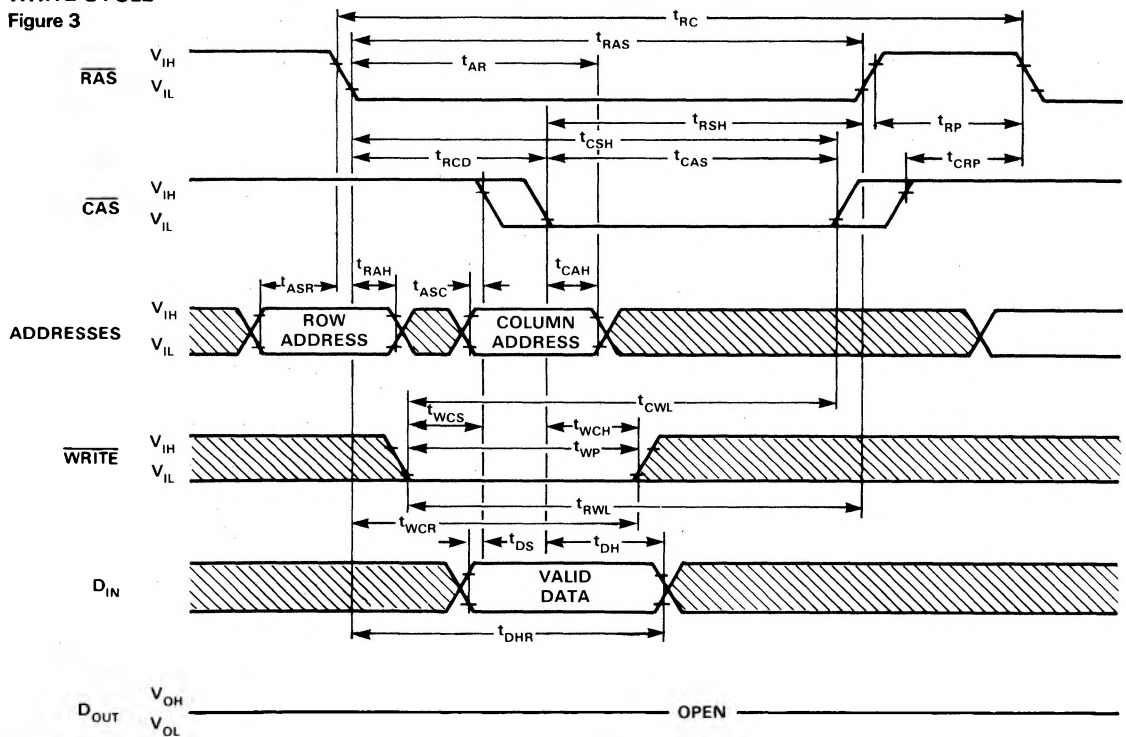
READ CYCLE

Figure 2



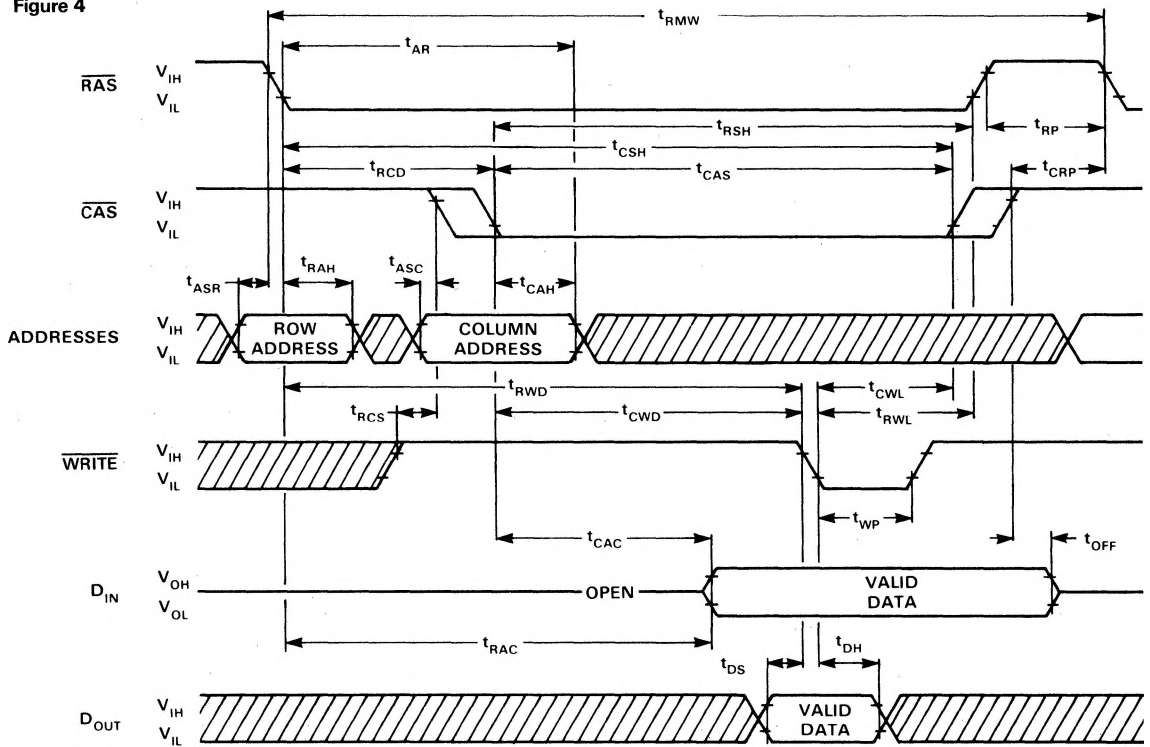
WRITE CYCLE

Figure 3



READ-WRITE/READ-MODIFY-WRITE CYCLE

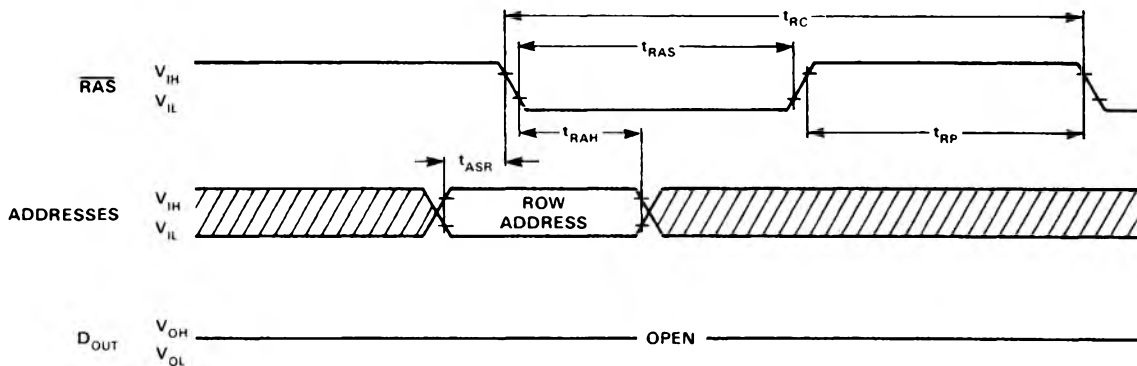
Figure 4



"RAS-ONLY" REFRESH CYCLE

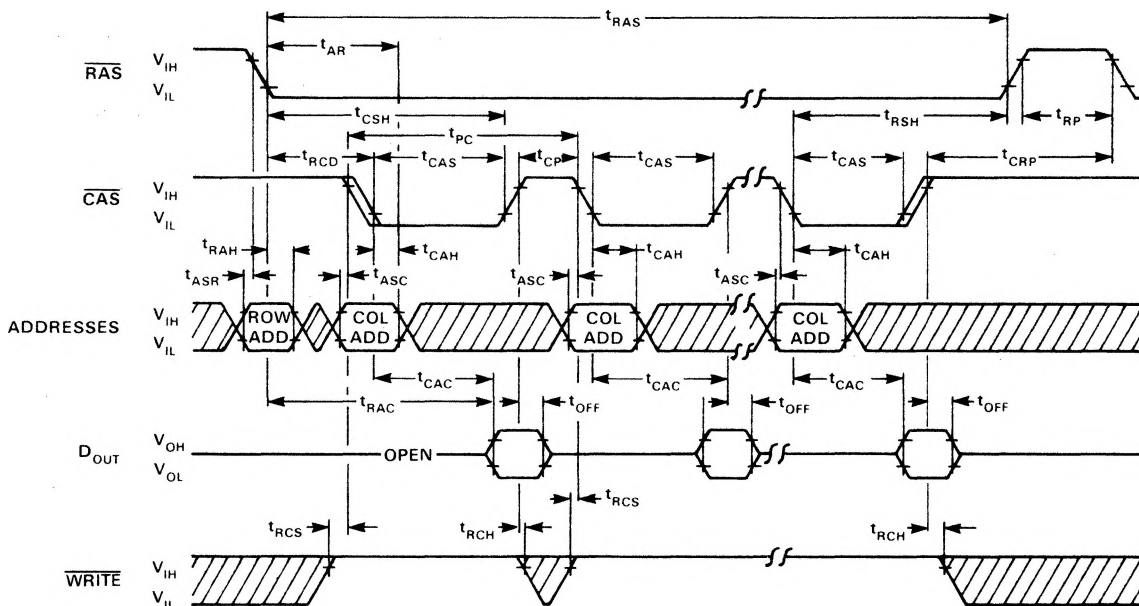
NOTE: CAS = V_{IH} WRITE = DON'T CARE

Figure 5



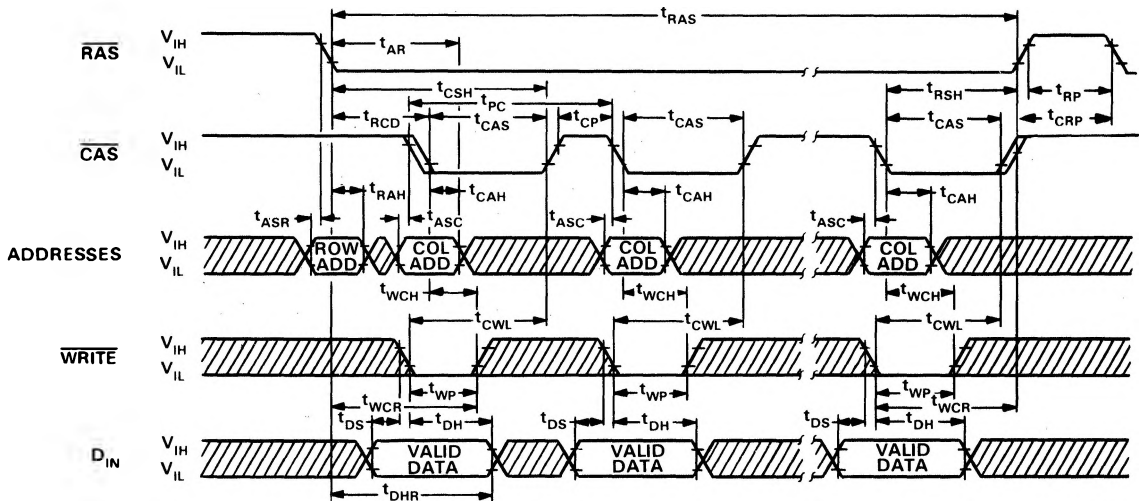
PAGE MODE READ CYCLE

Figure 6



PAGE MODE WRITE CYCLE

Figure 7



OPERATION

The 14 address bits required to decode 1 of the 16,384 cell locations within the MKB4516 are multiplexed onto the 7 address inputs and latched into the on-chip address latches by externally applying two negative going TTL-level clocks. The first clock, Row Address Strobe (\overline{RAS}), latches the 7 row addresses into the chip. The high-to-low transition of the second clock, Column Address Strobe (\overline{CAS}), subsequently latches the 7 column addresses into the chip. Each of these signals, \overline{RAS} and \overline{CAS} , triggers a sequence of events which are controlled by different delayed internal clocks. The two clock chains are linked together logically in such a way that the address multiplexing operation is done outside of the critical timing path for read data access. The later events in the \overline{CAS} clock sequence are inhibited until the occurrence of a delayed signal derived from the \overline{RAS} clock chain. This "gated \overline{CAS} " feature allows the \overline{CAS} clock to be externally activated as soon as the Row Address Hold specification (t_{RAH}) has been satisfied and the address inputs have been changed from Row address to Column address information.

The "gated \overline{CAS} " feature permits \overline{CAS} to be activated at any time after t_{RAH} and it will have no effect on the worst case data access time (t_{RAC}) up to the point in time when the delayed row clock no longer inhibits the remaining sequence of column clocks. Two timing endpoints result from the internal gating of \overline{CAS} which are called t_{RCD} (min) and t_{RCD} (max). No data storage or reading errors will result if \overline{CAS} is applied to the MKB4516 at a point in time beyond the t_{RCD} (max) limit. However, access time will then be determined exclusively by the access time from \overline{CAS} (t_{CAC}) rather than from \overline{RAS} (t_{RAC}), and \overline{RAS} access time will be

lengthened by the amount that t_{RCD} exceeds the t_{RCD} (max) limit.

Data Input/Output

Data to be written into a selected cell is latched into an on-chip register by a combination of \overline{WRITE} and \overline{CAS} while \overline{RAS} is active. The latter of \overline{WRITE} or \overline{CAS} to make its negative transition is the strobe for the Data In (D_{IN}) register. This permits several options in the write cycle timing. In a write cycle, if the \overline{WRITE} input is brought low (active) prior to \overline{CAS} being brought low (active), the D_{IN} is strobed by \overline{CAS} , and the Input Data set-up and hold times are referenced to \overline{CAS} . If the input data is not available at \overline{CAS} time (late write), or if it is desired that the cycle be a read-write or read-modify-write cycle the \overline{WRITE} signal should be delayed until after \overline{CAS} has made its negative transition. In this "delayed write cycle" the data input is set-up and hold times are referenced to the negative edge of \overline{WRITE} rather than \overline{CAS} .

Data is retrieved from the memory in a read cycle by maintaining \overline{WRITE} in the inactive or high state throughout the portion of the memory cycle in which both the \overline{RAS} and \overline{CAS} are low (active). Data read from the selected cell is available at the output port within the specified access time. The output data is the same polarity (not inverted) as the input data.

Data Output Control

The normal condition of the Data Output (D_{OUT}) of the MK4516 is the high impedance (open circuit) state; anytime \overline{CAS} is high (inactive) the D_{OUT} pin will be floating.

Once the output data port has gone active, it will remain valid until $\overline{\text{CAS}}$ is taken to the precharge (inactive high) state.

Page Mode Operation

The Page Mode feature of the MKB4516 allows for successive memory operations at multiple column locations within the same row address. This is done by strobing the row address into the chip and maintaining the $\overline{\text{RAS}}$ signal low (active) throughout all successive memory cycles in which the row address is common. The first success within a page mode operation will be available at t_{RAC} or t_{CAC} time, whichever is the limiting parameter. However, all successive accesses within the page mode operation will be available at t_{CAC} time (referenced to $\overline{\text{CAS}}$). With the MKB4516, this results in as much as a 45% improvement in access times! Effective memory cycle times are also reduced when using page mode.

The page mode boundary of a single MKB4516 is limited to the 128 column locations determined by all combinations of the seven column address bits. Operations within the page mode boundary need not be sequentially addressed and any combination of read-write and read-modify-write cycle are permitted within the page mode operation.

Refresh

Refresh of the dynamic cell matrix is accomplished by performing a memory cycle at all 128 combinations of the seven row address bits within each 2 ms interval. Although any normal memory cycle will perform the required refreshing, this function is most easily accomplished with " $\overline{\text{RAS}}$ -only" cycles.