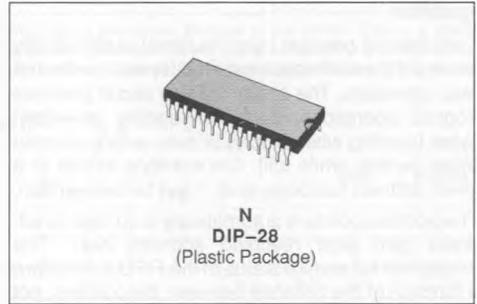


**2048 x 9 CMOS BiPORT FIFO**
**ADVANCE DATA**

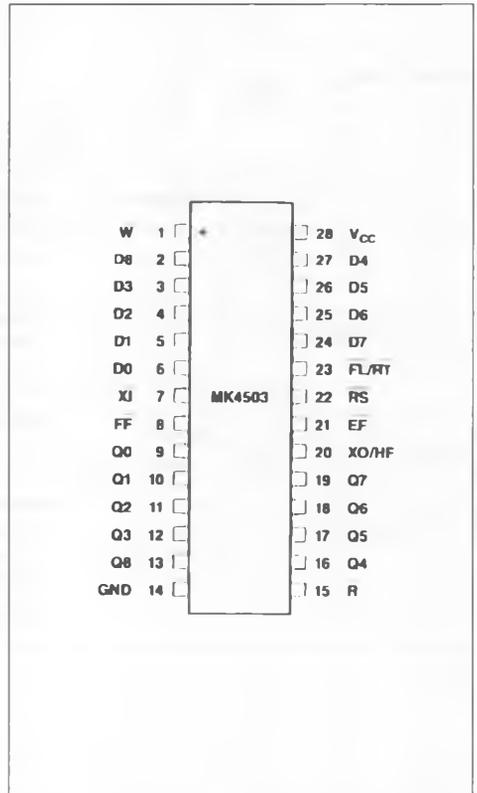
- FIRST-IN, FIRST-OUT MEMORY BASED ARCHITECTURE
- FLEXIBLE 2048 x 9 ORGANIZATION
- LOW POWER HCMOS TECHNOLOGY
- ASYNCHRONOUS AND SIMULTANEOUS READ/WRITE
- BIDIRECTIONAL APPLICATIONS
- FULLY EXPANDABLE BY WORD WIDTH OR DEPTH
- EMPTY AND FULL WARNING FLAGS
- RETRANSMIT CAPABILITY
- HIGH PERFORMANCE
- HALF FULL FLAG IN SINGLE DEVICE MODE


**Figure 1 : Pin Connections.**
**DESCRIPTION**

The MK4503 is a member of the BiPORT™ Memory Series, which utilizes special two-port cell techniques. Specifically, this device implements a First-In, First-Out algorithm, featuring asynchronous read/write operations, full, half full and empty flags, and unlimited expansion capability in both word size and depth. The main application of the MK4503 is as a rate buffer, sourcing and absorbing data at different rates, (e.g., interfacing fast processors and slow peripherals). The full, half full and empty flags are provided to prevent data overflow and underflow. The data is loaded and emptied on a First-In, First-Out (FIFO) basis, and the latency for the retrieval of data is approximately one load cycle (write). Since the writes and reads are internally sequential, thereby requiring no address information, the pinout definition will serve this and future high-density devices. The ninth bit is provided to support control or parity functions.

**PIN NAMES**

W = Write	XI = Expansion in
R = Read	XO/HF = Expansion out Half Full Flag
RS = Reset	FF = Full Flag
FL/RT = First Load/ Retransmit	EF = Empty Flag V <sub>CC</sub> = 5V
D = Data in	GND = Ground
Q = Data out	NC = No Connection



**FUNCTIONAL DESCRIPTION**

Unlike conventional shift register based FIFOs, the MK4503 employs a memory-based architecture wherein a byte written into the device does not "ripple-through". Instead, a byte written into the MK4503 is stored at a specific location, where it remains until over-written. The byte can be read and re-read as often as desired in the single device configuration.

Twin internal pointers (ring counters) automatically generate the addresses required for each write and read operation. The empty/full flag circuit prevents illogical operations, such as reading un-written bytes (reading while empty) or over-writing un-read bytes (writing while full). Once a byte stored at a given address has been read, it can be over-written.

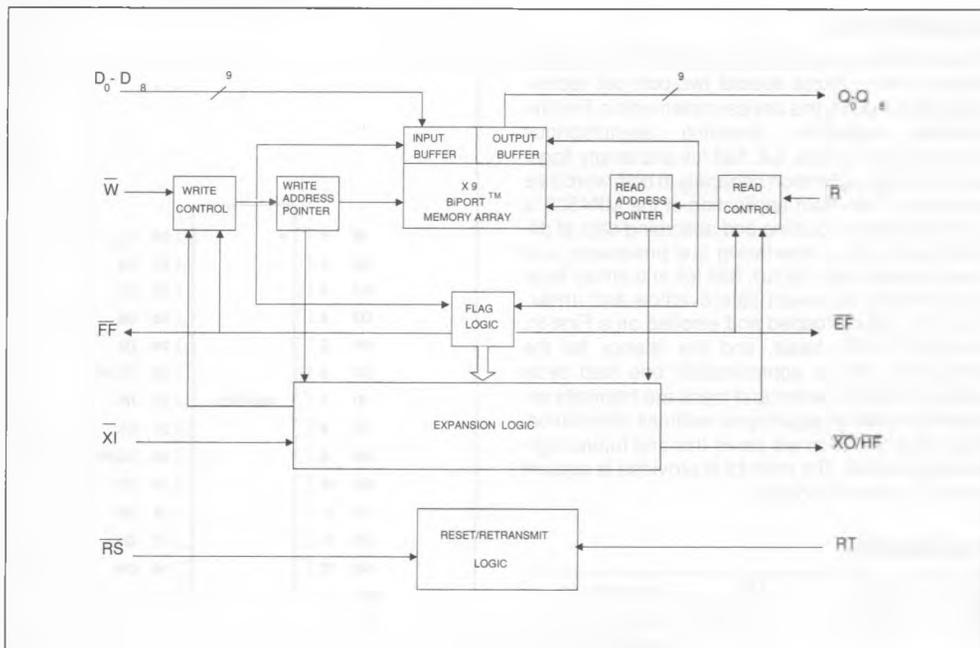
The address pointers automatically loop back to address zero after reaching address 2047. The empty/half full and full status of the FIFO is therefore a function of the distance between the pointers, not

of their absolute location. As long as the pointers do not catch one another, the FIFO can be written and read continuously without ever becoming full or empty.

Resetting the FIFO simply resets the write and read pointers to location zero. Pulsing retransmit resets the read address pointer without affecting the write address pointer.

With conventional FIFOs, implementation of a larger FIFO is accomplished by cascading the individual FIFOs. The penalty of cascading is often unacceptable ripple-through delays. The 4503 allows implementation of very large FIFOs with no timing penalties. The memory-based architecture of the MK4503 allows connecting the read, write, data in, and data out lines of the MK4503s in parallel. The write and read control circuits of the individual FIFOs are then automatically enabled and disabled through the expansion-in and expansion-out pins.

Figure 2 : MK4503 Block Diagram.



## ABSOLUTE MAXIMUM RATINGS\*

Parameter	Value	Unit
Voltage on any Pin Relative to GND	- 0.5 to + 7.0	V
Operating Temperature $T_A$ (ambient)	0 to + 70	°C
Storage Temperature	- 55 to + 125	°C
Total Device Power Dissipation	1	Watt
Output Current per Pin	20	mA

\* Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at these, or any other conditions above those indicated in the operational sections of this specification, is not implied. Exposure to absolute maximum ratings for extended periods may affect device

RECOMMENDED DC OPERATING CONDITIONS ( $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$ )

Symbol	Parameter	Value			Unit	Notes
		Min.	Typ.	Max.		
$V_{CC}$	Supply Voltage	4.5	5.0	5.5	V	3
GND	Ground	0	0	0	V	
$V_{IH}$	Logic "1" Voltage all Inputs	2.0		$V_{CC} + .3$	V	3, 9
$V_{IL}$	Logic "0" Voltage all Inputs	- 0.3		0.8	V	3, 4, 9

DC ELECTRICAL CHARACTERISTICS ( $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$ ) ( $V_{CC} = 5.0\text{V} \pm 10\%$ )

Symbol	Parameter	Value			Unit	Notes
		Min.	Typ.	Max.		
$I_{IL}$	Input Leakage Current (any input)	- 1		1	$\mu\text{A}$	5
$I_{OL}$	Output Leakage Current	- 10		10	$\mu\text{A}$	6
$V_{OH}$	Output Logic "1" Voltage $I_{OUT} = -1\text{mA}$	2.4			V	3
$V_{OL}$	Output Logic "0" Voltage $I_{OUT} = 4\text{mA}$			0.4	V	3
$I_{CC1}$	Average $V_{CC}$ Power Supply Current			120	mA	7
$I_{CC2}$	Average Standby Current ( $R = W = RS = FL/RT = V_{IH}$ )			12	mA	7
$I_{CC3}$	Power Down Current (all inputs $\geq V_{CC} - 0.2\text{V}$ )			4	$\mu\text{A}$	7

AC ELECTRICAL CHARACTERISTICS ( $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$ ) ( $V_{CC} = +5.0\text{V} \pm 10\%$ )

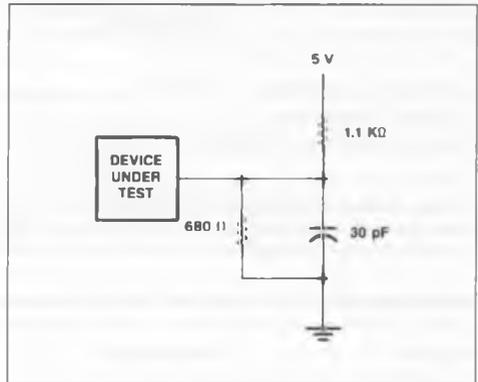
Symbol	Parameter	Value			Unit	Notes
		Min.	Typ.	Max.		
$C_I$	Capacitance on Input Pins			7	pF	
$C_O$	Capacitance on Output Pins			12	pF	8

- Notes :
1. Pulse widths less than minimum values are not allowed.
  2. Measured using output load shown in Output Load Circuit.
  3. All voltages are referenced to ground.
  4. - 1.5 volt undershoots are allowed for 10ns once per cycle.
  5. Measured with  $0.0 \leq V_{IH} \leq V_{CC}$ .
  6.  $R \geq V_{IH}$ ,  $0.0 \geq V_{OUT} \leq V_{CC}$ .
  7.  $I_{CC}$  measurements are made with outputs open.
  8. With output buffer deselected.
  9. Input levels tested at 500ns cycle time.

**AC TEST CONDITIONS :**

Input Levels..... GND to 3.0V  
Transition Times..... 5ns  
Input Signal Timing  
Reference Level ..... .5  
Output Signal Timing  
Reference Level ..... 0.8V and 2.2V  
Ambient Temperature..... 0°C to 70°C  
Vcc ..... 5.0V ± 10%

**Figure 3 : Output Load Circuit.**



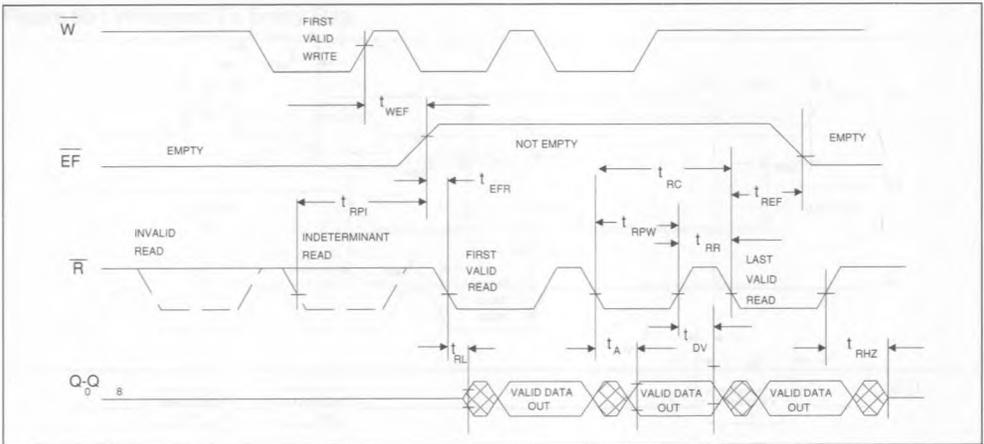
## READ MODE

The MK4503 initiates a Read Cycle (see figure 4) on the falling edge of Read Enable control input ( $\overline{R}$ ), provided that the Empty Flag ( $\overline{EF}$ ) is not asserted. In the Read mode of operation, the MK4503 provides a fast access to data from 9 of 18432 locations in the static storage array. The data is accessed on a FIFO basis independent of any on-going WRITE operations. After  $\overline{R}$  goes high, data outputs will return to a high impedance condition until the next Read operation.

In the event that all data has been read from the FIFO, the  $\overline{EF}$  will go low, and further Read opera-

tions will be inhibited (the data outputs will remain in high impedance).  $\overline{EF}$  will go high  $t_{WEF}$  after completion of a valid Write operation.  $\overline{EF}$  will again go low  $t_{REF}$  from the beginning of a subsequent READ operation, provided that a second WRITE has not been completed (see figure 6B). Reads beginning  $t_{EFR}$  after  $\overline{EF}$  goes high are valid. Reads begun after  $\overline{EF}$  goes low and more than  $t_{RPI}$  before  $\overline{EF}$  goes high are invalid (ignored). Reads beginning less than  $t_{RPI}$  before  $\overline{EF}$  goes high and less than  $t_{EFR}$  later may or may not occur (be valid) depending on internal flag status.

Figure 4 : Read And Empty Flag Timing.



## AC ELECTRICAL CHARACTERISTICS ( $0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$ ) ( $V_{CC} = +5.0\text{volts} \pm 10\%$ )

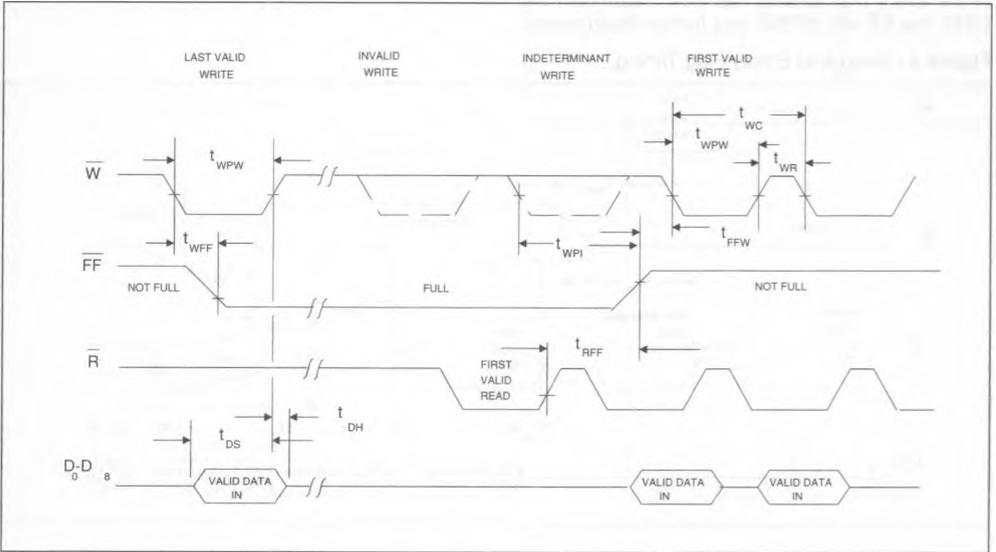
Sym	Parameter	4503-65		4503-80		4503-10		4503-12		4503-15		4503-20		Unit	Notes
		Min.	Max.												
$t_{RC}$	Read Cycle Time	80		100		120		140		175		235		ns	
$t_A$	Access Time		65		80		100		120		150		200	ns	2
$t_{RR}$	Read Recovery Time	15		20		20		20		25		35		ns	
$t_{RPW}$	Read Pulse Width	65		80		100		120		150		200		ns	1
$t_{RL}$	$\overline{R}$ Low to Low Z	0		0		0		0		0		0		ns	2
$t_{DV}$	Data Valid from $\overline{R}$ High	5		5		5		5		5		5		ns	2
$t_{RHZ}$	$\overline{R}$ High to High Z		25		25		25		35		50		60	ns	2
$t_{REF}$	$\overline{R}$ Low to $\overline{EF}$ Low		60		75		95		115		145		195	ns	2
$t_{EFR}$	$\overline{EF}$ High to Valid Read	10		10		10		10		10		10		ns	2
$t_{WEF}$	$\overline{W}$ High to $\overline{EF}$ High		60		75		95		110		140		190	ns	2
$t_{RPI}$	Read Protect Indeterminant		35		35		35		35		35		35	ns	2

**WRITE MODE**

The MK4503 initiates a Write Cycle (see figure 5) on the falling edge of the Write Enable control input ( $\overline{W}$ ), provided that the Full Flag ( $\overline{FF}$ ) is not asserted. Data set-up and hold-time requirements must be satisfied with respect to the rising edge of  $\overline{W}$ . The data is stored sequentially and independent of any ongoing Read operations.  $\overline{FF}$  is asserted during the last valid write as the MK4503 becomes full. Write operations begun with  $\overline{FF}$  low are inhibited.  $\overline{FF}$  will go high  $t_{RFF}$

after completion of a valid READ operation.  $\overline{FF}$  will again go low  $t_{WFF}$  from the beginning of a subsequent WRITE operation, provided that a second READ has not been completed (see figure 6A). Writes beginning  $t_{FFW}$  after  $\overline{FF}$  goes high are valid. Writes beginning after  $\overline{FF}$  goes low and more than  $t_{WPI}$  before  $\overline{FF}$  goes high are invalid (ignored). Writes beginning less than  $t_{WPI}$  before  $\overline{FF}$  goes high and less than  $t_{FFW}$  later may or may not occur (be valid), depending on internal flag status.

**Figure 5 : Write And Full Flag Timing.**



**AC ELECTRICAL CHARACTERISTICS (0°C ≤ T<sub>A</sub> ≤ + 70°C) (V<sub>CC</sub> = + 5.0volts ± 10%)**

Sym.	Parameter	4503-65		4503-80		4503-10		4503-12		4503-15		4503-20		Unit	Notes
		Min.	Max.												
t <sub>WC</sub>	Write Cycle Time	80		100		120		140		175		235		ns	
t <sub>WPW</sub>	Write Pulse Width	65		80		100		120		150		200		ns	1
t <sub>WR</sub>	Write Recovery Time	15		20		20		20		25		35		ns	
t <sub>DS</sub>	Data Set Up Time	30		40		40		40		50		65		ns	
t <sub>DH</sub>	Data Hold Time	10		10		10		10		10		10		ns	
t <sub>WFF</sub>	W Low to FF Low		60		70		95		115		145		195	ns	2
t <sub>FFW</sub>	FF High to Valid Write		10		10		10		10		10		10	ns	2
t <sub>RFF</sub>	R High to FF High		60		70		95		110		140		190	ns	2
t <sub>WPI</sub>	Write Protect Indeterminant		35		35		35		35		35		35	ns	2

Figure 6a : Read/write To Full Flag.

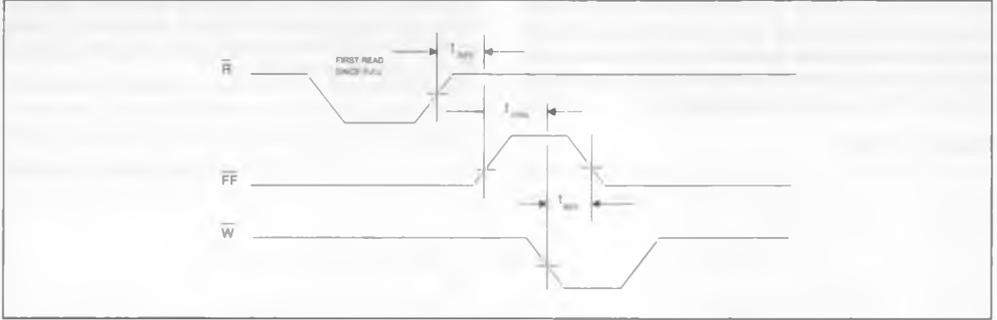
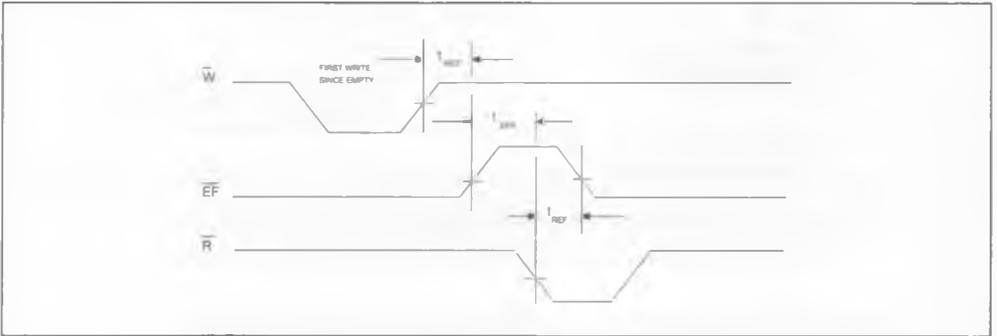


Figure 6b : Write/read To Empty Flag.

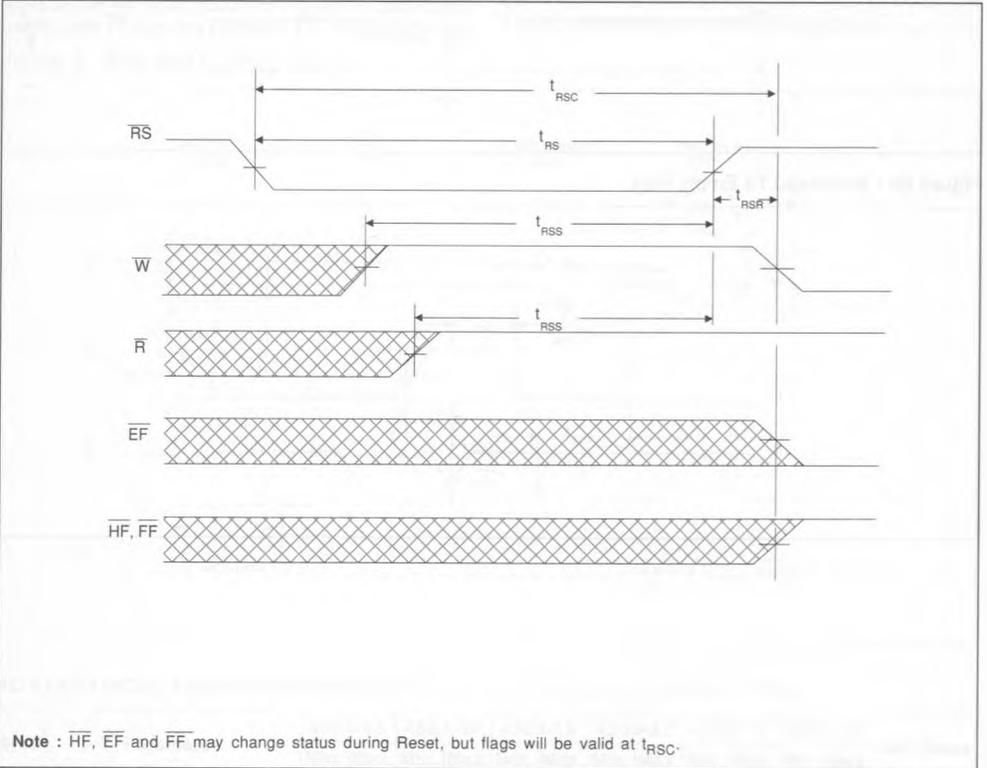


**RESET**

The MK4503 is reset (see figure 7) whenever the Reset pin ( $\overline{RS}$ ) is in the low state. During a Reset, both the internal read and write pointers are set to the first location. Reset is required after power up, before a Write operation can begin.

Although neither  $\overline{W}$  or  $\overline{R}$  need be high when  $\overline{RS}$  goes low, both  $\overline{W}$  and  $\overline{R}$  must be high  $t_{RSS}$  before  $\overline{RS}$  goes high, and must remain high  $t_{RSR}$  afterwards. Refer to the following discussion for the required state of  $\overline{FL/RT}$  and  $\overline{XI}$  during Reset.

**Figure 7 : Reset.**



**AC ELECTRICAL CHARACTERISTICS** ( $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$ ) ( $V_{CC} = +5.0\text{volts} \pm 10\%$ )

Sym.	Parameter	4503-65		4503-80		4503-10		4503-12		4503-15		4503-20		Unit	Notes
		Min.	Max.												
$t_{RSC}$	Reset Cycle Time	80		100		120		140		175		235		ns	
$t_{RS}$	Reset Pulse Width	65		80		100		120		150		200		ns	1
$t_{RSR}$	Reset Recovery Time	15		20		20		20		25		35		ns	
$t_{RSS}$	Reset Set Up Time	45		60		80		100		130		180		ns	

## RETRANSMIT

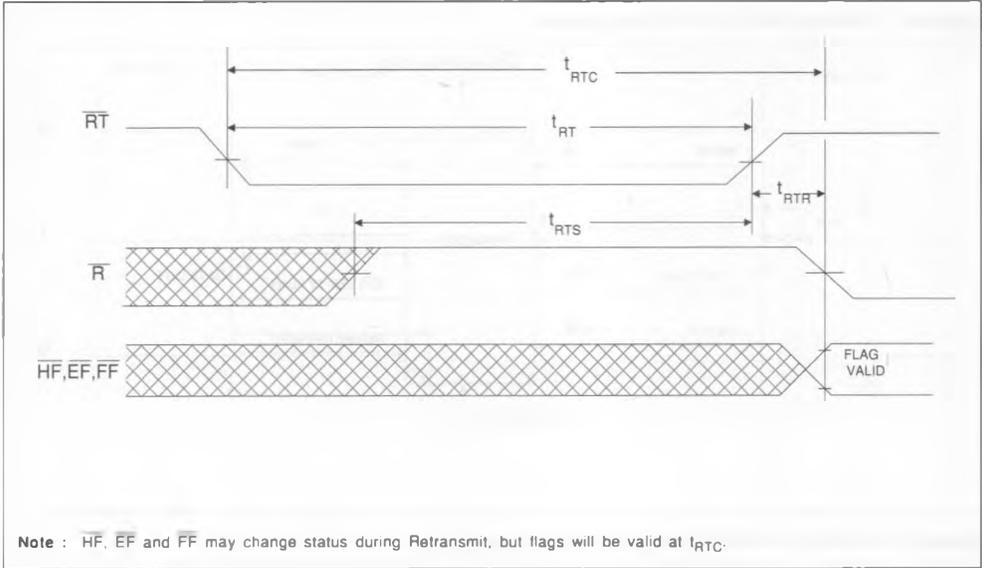
The MK4503 can be made to retransmit (re-read previously read data) after the Retransmit pin ( $\overline{RT}$ ) is pulsed low. (See figure 8).

A Retransmit operation sets the internal read pointer to the first physical location in the array, but will not affect the position of the write pointer.  $\overline{R}$  must be in-

active  $t_{RTS}$  before  $\overline{RT}$  goes high, and must remain high for  $t_{RTR}$  afterwards.

The Retransmit function is particularly useful when blocks of less than 2048 Writes are performed between Resets. The Retransmit feature is not compatible with Depth Expansion.

Figure 8 : Retransmit.



## AC ELECTRICAL CHARACTERISTICS ( $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$ ) ( $V_{CC} = +5.0\text{volts} \pm 10\%$ )

Sym.	Parameter	4503-65		4503-80		4503-10		4503-12		4503-15		4503-20		Unit	Notes
		Min.	Max.												
$t_{RTC}$	Retransmit Cycle Time	80		100		120		140		175		235		ns	
$t_{RT}$	Retransmit Pulse Width	65		80		100		120		150		200		ns	1
$t_{RTR}$	Retransmit Recovery Time	15		20		20		20		25		35		ns	
$t_{RTS}$	Retransmit Setup Time	45		60		80		100		130		180		ns	

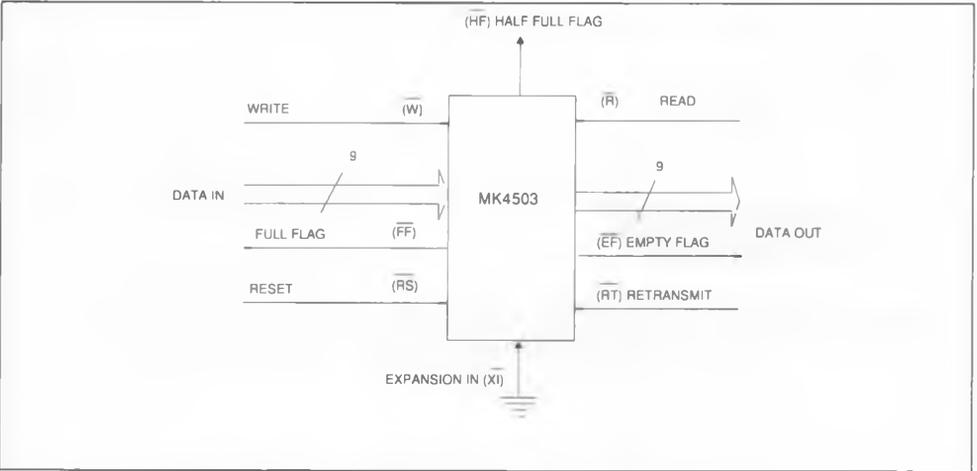
**SINGLE DEVICE CONFIGURATION**

A single MK4503 may be used when application requirements are for 2048 words or less. The MK4503 is placed in Single Device Configuration mode when the chip is Reset with the Expansion In pin (XI) grounded (see figure 9).

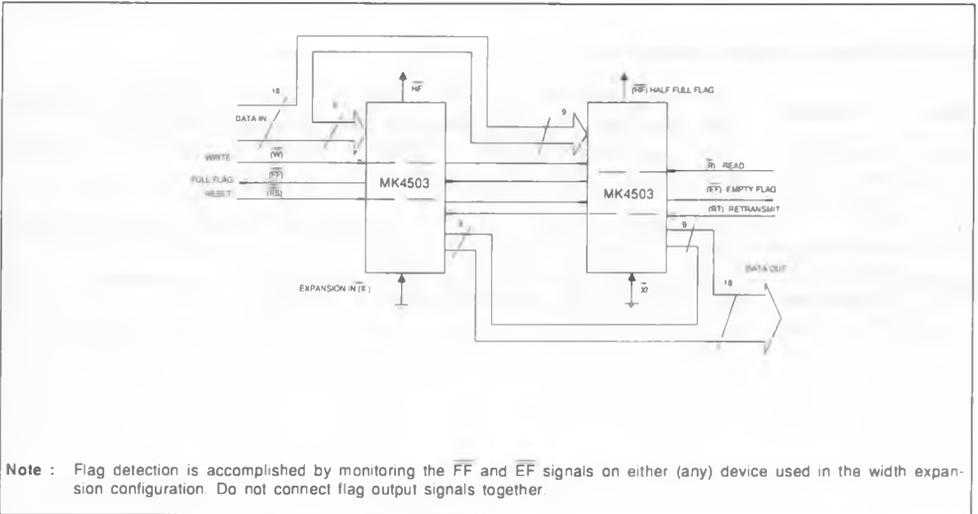
**WIDTH EXPANSION**

Word width may be increased simply by connecting the corresponding input control signals of multiple devices. Status Flags ( $\overline{EF}$  and  $\overline{FF}$ ) can be detected from any one device. Figure 10 demonstrates an 18-bit word width by using two MK4503s. Any word width can be attained by adding additional MK4503s. The half full flag ( $\overline{HF}$ ) operates the same as in the single device configuration.

**Figure 9 :** A Single 2047 x 9 FIFO Configuration.



**Figure 10 :** A 2048 x 18 FIFO Configuration (width expansion).



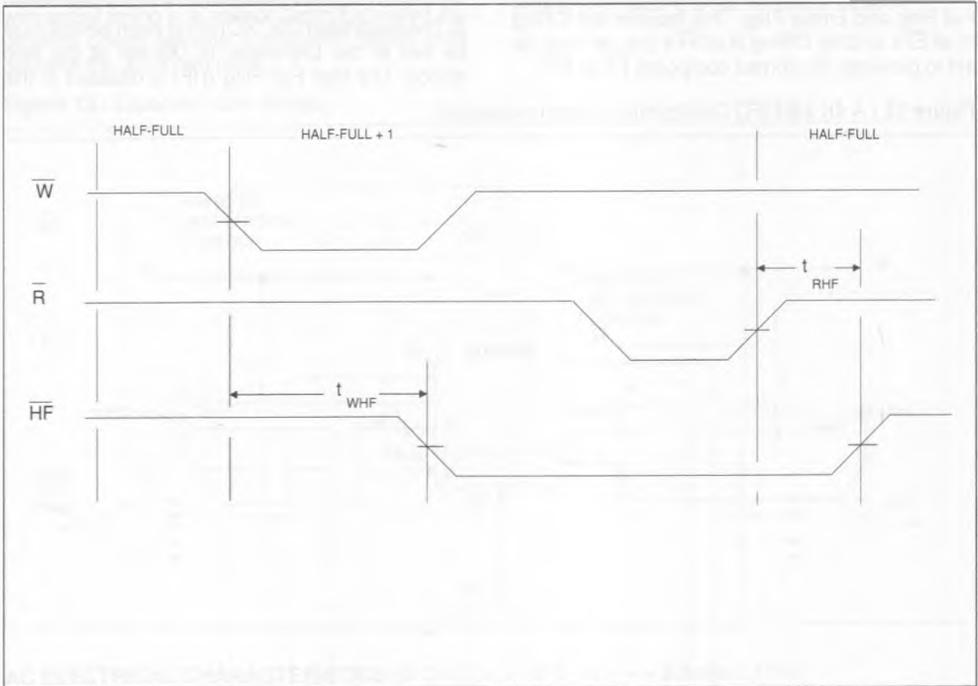
**Note :** Flag detection is accomplished by monitoring the  $\overline{FF}$  and  $\overline{EF}$  signals on either (any) device used in the width expansion configuration. Do not connect flag output signals together.

## HALF FULL FLAG LOGIC

When in single device configuration, the ( $\overline{\text{HF}}$ ) output acts as an indication of a half full memory. After half of the memory is filled, and at the falling edge of the next write operation, the half full flag ( $\overline{\text{HF}}$ ) will be set

low and remain low until the difference between the write pointer and read pointer is less than or equal to one half the total memory. The half full flag ( $\overline{\text{HF}}$ ) is then reset by the rising edge of the read operation (see figure 11).

Figure 11 : Half Full Flag Timing.



## AC CHARACTERISTICS ( $0^{\circ}\text{C} \leq T_{\text{A}} \leq +70^{\circ}\text{C}$ ) ( $V_{\text{CC}} = +5\text{volts} \pm 10\%$ )

Sym.	Parameter	4503-65		4503-80		4503-10		4503-12		4503-15		4503-20		Unit	Notes
		Min.	Max.												
$t_{\text{WHF}}$	Write Low to Half Full Flag Low		80		100		120		140		175		235	ns	
$t_{\text{RHF}}$	Read High to Half Full Flag High		80		100		120		140		175		235	ns	

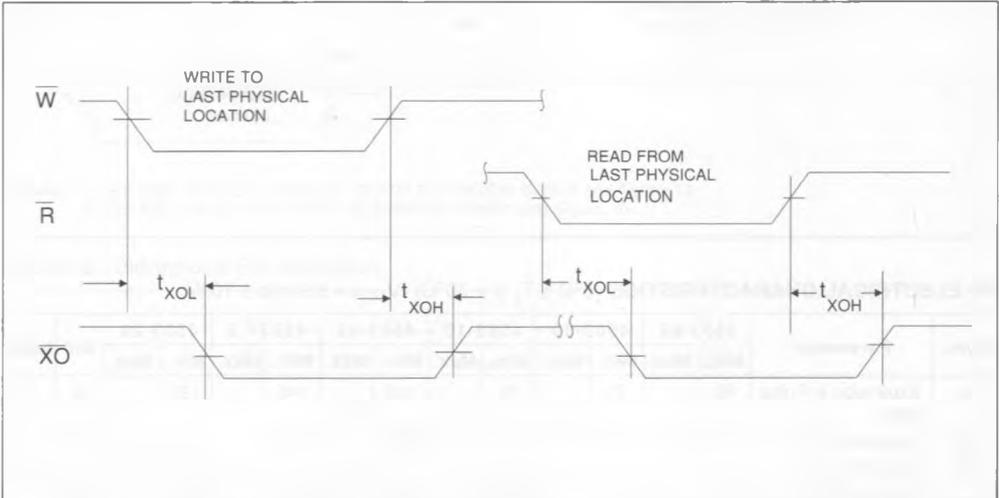


## EXPANSION TIMING

Figures 13 and 14 illustrate the timing of the Expansion Out and Expansion In signals. Discussion of Expansion Out/Expansion In timing is provided to clarify how Depth Expansion works. Inasmuch as Expansion Out pins are generally connected only to Expansion In pins, the user need not be concerned with actual timing in a normal Depth Expanded application unless extreme propagation delays exist between the  $\overline{XO}/\overline{XI}$  pin pairs.

Expansion Out pulses are the image of the WRITE and READ signals that cause them; delayed in time by  $t_{XOL}$  and  $t_{XOH}$ . The Expansion Out signal is propagated when the last physical location in the memory array is written and again when it is read (Last Read). This is in contrast to when the Full and Empty Flags are activated, which is in response to writing and reading a last available location.

Figure 13 : Expansion Out timing.



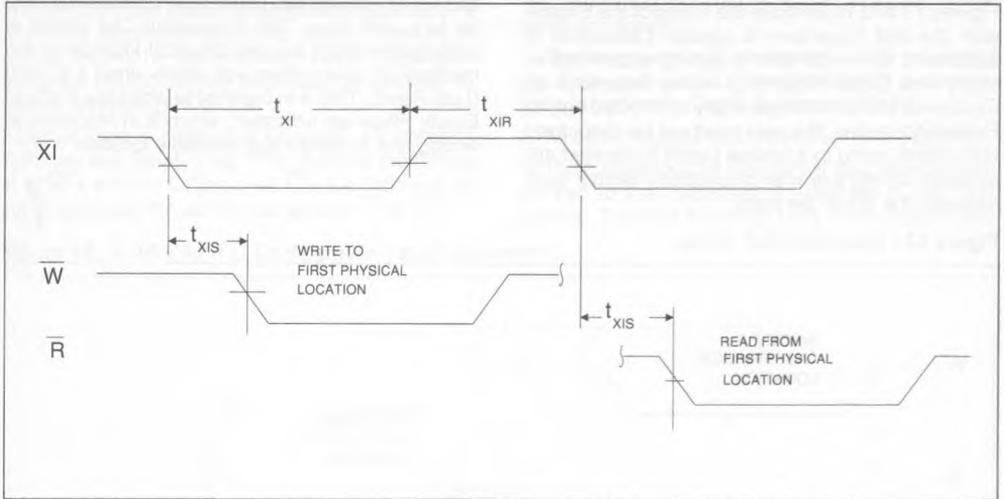
## AC ELECTRICAL CHARACTERISTICS ( $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$ ) ( $V_{CC} = +5.0\text{volts} \pm 10\%$ )

Sym.	Parameter	4503-65		4503-80		4503-10		4503-12		4503-15		4503-20		Unit	Notes
		Min.	Max.												
$t_{XOL}$	Expansion Out Low		55		70		75		90		115		150	ns	
$t_{XOH}$	Expansion Out High		60		80		90		100		125		155	ns	

When in Depth Expansion mode, a given MK4503 will begin writing and reading as soon as valid WRITE and READ signals begin, provided  $\overline{FL}$  was grounded at RESET time. A MK4503 in Depth Expansion mode with  $\overline{FL}$  high at RESET will not begin writing until after an Expansion In pulse occurs.

It will not begin reading until a second Expansion In pulse occurs and the Empty Flag has gone high. Expansion In pulses must occur  $t_{XIS}$  before the WRITE and READ signals they are intended to enable. Minimum Expansion In pulse width,  $t_{XI}$ , and recovery time,  $t_{XIR}$ , must be observed.

Figure 14 : Expansion In Timing.



AC ELECTRICAL CHARACTERISTICS ( $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$ ) ( $V_{CC} = +5.0\text{volts} \pm 10\%$ )

Sym.	Parameter	4503-65		4503-80		4503-10		4503-12		4503-15		4503-20		Unit	Notes
		Min.	Max.												
$t_{xi}$	Expansion in Pulse Width	60		75		95		115		145		195		ns	1
$t_{xir}$	Expansion in Recovery Time	15		20		20		20		25		35		ns	
$t_{xis}$	Expansion in Setup Time	25		30		45		50		60		85		ns	

COMPOUND EXPANSION

The two expansion techniques described above can be applied together in a straight forward manner to achieve large FIFO arrays (see figure 15).

BIDIRECTIONAL APPLICATIONS

Applications, which require data buffering between two systems (each system capable of READ and

WRITE operations), can be achieved by pairing MK4503s, as shown in figure 16. Care must be taken to assure that the appropriate flag is monitored by each system. (i.e.,  $\overline{FF}$  is monitored on the device where  $\overline{W}$  is used ;  $\overline{EF}$  is monitored on the device where  $\overline{R}$  is used). Both Depth Expansion and Width Expansion may be used in this mode.

Figure 15 : Compound Fifo Expansion.

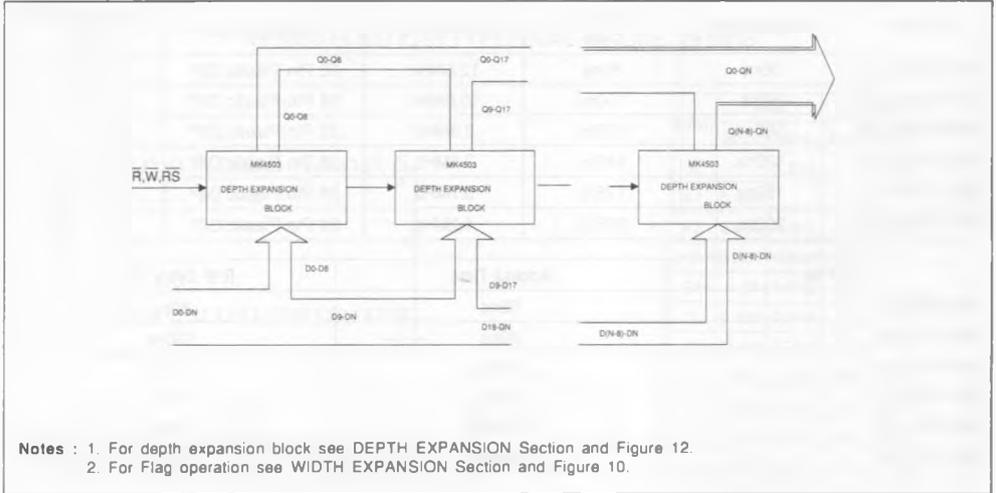
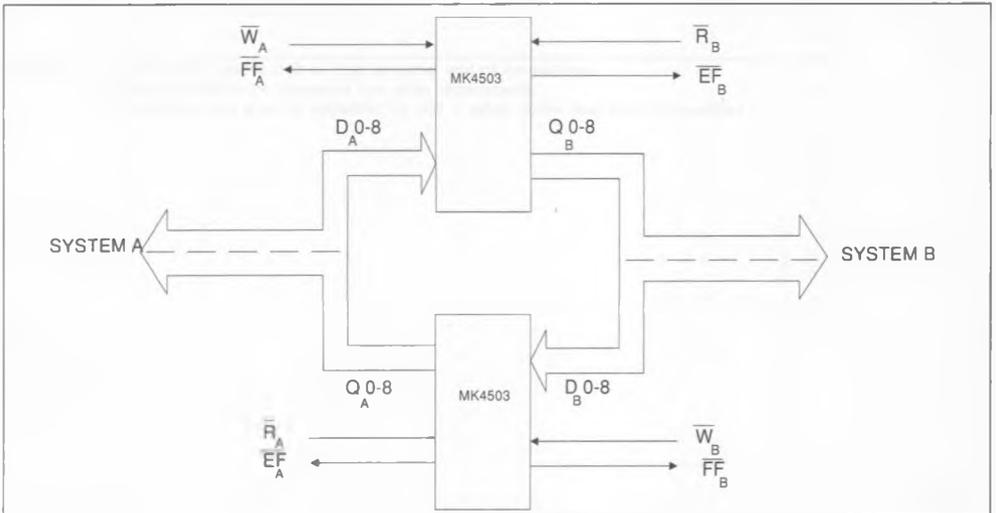


Figure 16 : Bidirectional Fifo Application.



**ORDER CODES**

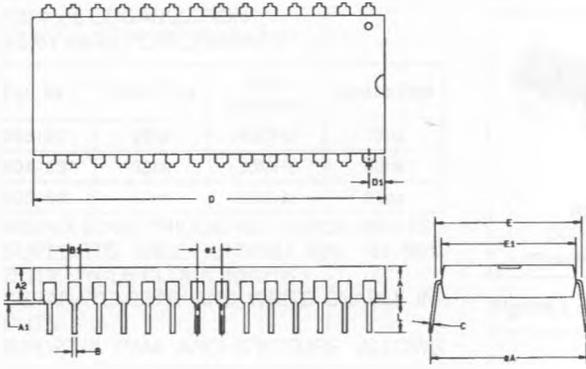
Part No	Access Time	R/W Cycle Time	Clock Freq.	Package Type	Temperature Range
<b>MK4503N-65</b>	65ns	80ns	12.5MHz	28 Pin Plastic DIP	0° to 70°C
<b>MK4503N-80</b>	80ns	100ns	10.0MHz	28 Pin Plastic DIP	0° to 70°C
<b>MK4503N-10</b>	100ns	120ns	8.3MHz	28 Pin Plastic DIP	0° to 70°C
<b>MK4503N-12</b>	120ns	140ns	7.1MHz	28 Pin Plastic DIP	0° to 70°C
<b>MK4503N-15</b>	150ns	175ns	5.7MHz	28 Pin Plastic DIP	0° to 70°C
<b>MK4503N-20</b>	200ns	235ns	4.2MHz	28 Pin Plastic DIP	0° to 70°C

Part No	Access Time	R/W Cycle Time
<b>MK4503-65</b>	65ns	80ns
<b>MK4503-80</b>	80ns	100ns
<b>MK4503-10</b>	100ns	120ns
<b>MK4503-12</b>	120ns	140ns
<b>MK4503-15</b>	150ns	175ns
<b>MK4503-20</b>	200ns	235ns

## PACKAGE DESCRIPTION

## MK4503 PLASTIC (N TYPE) DUAL-IN-LINE. 28 PINS

Dim.	mm		Inches		Notes
	Min.	Max.	Min.	Max.	
A		5.334		.210	2
A1	0.381		.015		2
A2	3.556	4.064	.140	.160	
B	0.381	0.534	.015	.021	3
B1	1.27	1.778	.050	.070	
C	0.203	0.304	.008	.012	3
D	36.576	37.338	1.440	1.470	1
D1	1.651	2.159	.065	.085	
E	15.24	15.875	.600	.625	
E1	13.462	14.224	.530	.560	
e1	2.286	2.794	.090	.110	
eA	15.24	17.78	.600	.700	
L	3.048		.120		



- Notes :
1. Overall length includes 010 in flash on either end of the package
  2. Package standoff to be measured per jedec requirements.
  3. The maximum limit shall be increased by 003 in when solder lead finish is specified