HD6801V0, HD6801V5 MCU (Microcomputer Unit)

The HD6801V MCU is an 8-bit microcomputer system which is compatible with the HD6801S except the ROM size. The HD6801V MCU is object code compatible with the HD6800 with improved execution times of key instructions plus several new 16-bit and 8-bit instructions including an 8×8 unsigned multiply with 16-bit result. The HD6801V MCU can operate as a single chip microcomputer or be expanded to 65k words. The HD6801V MCU is TTL compatible and requires one +5.0 volt power supply. The HD6801V MCU has 4k bytes of ROM and 128 bytes of RAM on chip. Serial Communications interface (SCI), and parallel I/O as well as a three function 16-bit timer. Features and Block diagram of the HD6801V include the following:

- FEATURES
- Expanded HMCS6800 Instruction Set
- 8 × 8 Multiply
- On-Chip Serial Communications Interface (SCI)
- Object Code Compatible With The HD6800 MPU
- 16-Bit Timer
- Single Chip Or Expandable To 65k Words
- 4k Bytes Of ROM
- 128 Bytes Of RAM (64 Bytes Retainable On Power Down)
- 29 Parallel I/O Lines And 2 Handshake Control Lines
- Internal Clock/Divided-By-Four Circuitry
- TTL Compatible Inputs And Outputs
- Interrupt Capability
- Compatible with MC6801 (except ROM size)
- BLOCK DIAGRAM





PRELIMINARY-

PIN ARRANGEMENT



TYPE OF PRODUCTS

MCU	Bus Timing
HD6801V0	1 MHz
HD6801V5	1.25 MHz

ABSOLUTE MAXIMUM RATINGS

Item	Symbol	Value	Unit
Supply Voltage	V _{cc} *	-0.3~+7.0	V
Input Voltage	V _{in} *	-0.3 ~ +7.0	v
Operating Temperature	Topr	0 ~+70	°C
Storage Temperature	T _{stg}	- 55 ~+150	°C

* With respect to VSS (SYSTEM GND)

[NOTE] Permanent LSI damage may occur if maximum ratings are exceeded. Normal operation should be under recommended operating conditions. If these conditions are exceeded, it could affect reliability of LSI.

ELECTRICAL CHARACTERISTICS

• DC CHARACTERISTICS (V_{CC} =5.0V \pm 5%, V_{SS} = 0V, Ta = 0 ~ +70°C, unless otherwise noted.)

Iter	n	Symbol	Test Condition	min	typ	max	Unit	
Input "High" Voltage				4.0	-	V _{cc}		
input High voltage	Other Inputs*	VIH		2.0	_	V _{cc}	v	
Input "Low" Voltage	All Inputs*	VIL		-0.3	-	0.8	v	
	$P_{40} \sim P_{47}$		V 0 - 2 AV	-	-	0.5		
Input Load Current	SC ₁	Itin	$Vin = 0 \sim 2.4V$	_	-	0.8	mA	
	EXTAL		$V_{in} = 0 \sim V_{CC}$	-	-	0.8		
Input Leakage Current	NMI, IRQ, , RES	llinl	$V_{in} = 0 \sim 5.25 V$	-	-	2.5	μA	
Three State (Offset)	$P_{10} \sim P_{17}, P_{30} \sim P_{37}$	1. 1	N - 05 - 0 AV	_	-	10		
Leakage Current	$P_{20} \sim P_{24}$	TSIL	$v_{in} = 0.5 \sim 2.4 v$	-	-	100	μΑ	
	$P_{30} \sim P_{37}$		$I_{LOAD} = -205 \mu A$	2.4	-	-		
Output "High" Voltage	$P_{40} \sim P_{47}$, E, SC ₁ , SC ₂	V _{он}	Ι _{LOAD} = -145 μΑ	2.4	-	—	v	
	Other Outputs		$I_{LOAD} = -100 \mu A$	2.4	-	-		
Output "Low" Voltage	All Outputs	Vol	I _{LOAD} = 1.6 mA	-	_	0.5	v	
Darlington Drive Current	$P_{10} \sim P_{17}$	-1он	V _{out} = 1.5V	1.0	-	10.0	mA	
Power Dissipation		PD		-	-	1200	mW	
Input Consoltance	$P_{30} \sim P_{37}, P_{40} \sim P_{47}, SC_1$	C.	$V_{in} = 0V, Ta = 25^{\circ}C,$	-	1	12.5	-5	
Input Capacitance	Other Inputs	Uin	f = 1.0 MHz	_	-	10.0	pr	
Vee Standby	Powerdown	V _{SBB}		4.0	_	5.25	V	
ACC Standok	Operating	V _{SB}		4.75	_	5.25	v	
Standby Current	Powerdown	ISBB	V _{SBB} = 4.0 V	-	-	8.0	mA	

*Except Mode Programming Levels.

• AC CHARACTERISTICS

BUS TIMING (V_{CC} = 5.0V \pm 5%, V_{SS} = 0V, Ta = 0 ~ +70°C, unless otherwise noted.)

		Cumbral	Tant Condition	н	HD6801V0			HD6801V5		
	Item	Symbol	Test Condition	min	typ	max	min	typ	max	Unit
Cycle Time		t _{cyc}		1	-	10	0.8	-	10	μs
Address Strobe Pu	Ise Width "High"	PWASH		200	-	-	150	-	-	ns
Address Strobe Ri	se Time	t _{ASr}		5	-	50	5	-	50	ns
Address Strobe Fa	II Time	tASF]	5	-	50	5	-	50	ns
Address Strobe De	lay Time	tASD		60	-	-	30	-	-	ns
Enable Rise Time		ter		5	-	50	5	-	50	ns
Enable Fall Time		t _{Ef}]	5	-	50	5	-	50	ns
Enable Pulse Width	n "High" Time	PWEH]	450	-	-	340		-	ns
Enable Pulse Width	n "Low" Time	PWEL		450	-	-	350	-	-	ns
Address Strobe to	Enable Delay Time	tASED	-	60	-	-	30	-		ns
Address Delay Tim	le	t _{AD}	Fig. 1	-	-	260	-	-	260	ns
Address Delay Tim	e for Latch	tADL	Fig. 2	-	-	270	-	-	260	ns
Data Set-up Write	Time	t _{DSW}		225	-	-	115	-	-	ns
Data Set-up Read	Time	t _{DSR}]	80	-	-	70	-		ns
Data Hold Time	Read	t _{HR}		10	-	-	10	-	-	
Data Hold Time	Write	t _{HW}		20			20	-		
Address Set-up Tir	ne for Latch	tASL		60	-	-	50	-	-	ns
Address Hold Time	e for Latch	tAHL		20	-		20		-	ns
Address Hold Time	2	t _{AH}		20	_	-	20	-	-	_ns
Peripheral Read	Non-Multiplexed Bus	(tACCN)		-	-	(610)	-	-	(410)	
Access Time	Multiplexed Bus	(tACCM)		-	-	(600)	_	-	(400)	
Oscillator stabiliza	tion Time	t _{RC}	Fig. 10	100	-		100	-	-	ms
Processor Control	Set-up Time	tPCS	Fig. 11	200		-	200	-	-	ns

PERIPHERAL PORT TIMING (V_{CC} = 5.0V \pm 5%, V_{SS} = 0V, Ta = 0 ~ +70°C, unless otherwise noted.)

ltem		Symbol	Test Condition	min	typ	max	Unit
Peripheral Data Setup Time	Port 1, 2, 3, 4	tPDSU	Fig. 3	200	-	-	ns
Peripheral Data Hold Time	Port 1, 2, 3, 4	t _{PDH}	Fig. 3	200	-		ns
Delay Time, Enable Positive T to OS3 Negative Transition	Fransition	t _{OSD1}	Fig. 5	-	-	350	ns
Delay Time, Enable Positive 1 to OS3 Positive Transition	Fransition	t _{OSD2}	Fig. 5	_	-	350	ns
Delay Time, Enable Negative Transition to Peripheral Data Valid	Port 1, 2*, 3, 4	tpwD	Fig. 4	-	-	400	ns
Delay Time, Enable Negative Transition to Peripheral CMOS Data Valid	Port 2**, 4	t _{cmos}	Fig. 4	_	-	2.0	μs
Input Strobe Pulse Width		tewis	Fig. 6	200	-	-	ns
Input Data Hold Time	port 3	t _{IH}	Fig. 6	50	-	-	ns
Input Data Set-up Time	Port 3	t _{is}	Fig. 6	20	-	-	ns

*Except P₂₁ **10kΩ pull up register required for Port 2

.

TIMER, SCI TIMING (V_{CC} = 5.0V ±5%, V_{SS} = 0V, Ta = 0 \sim +70 $^{\circ}$ C, unless otherwise noted.)

ltem	Symbol	Test Condition	min	typ	max	Unit
Timer Input Pulse Width	t _{PWT}		2t _{cyc} +200	-	-	ns
Delay Time, Enable Positive Transition to Timer Out	t _{TOD}	Fig. 7	-	-	600	ns
SCI Input Clock Cycle	t _{Scyc}		1	-	-	t _{cyc}
SCI Input Clock Pulse Width	t _{PWSCK}		0.4	-	0.6	tScyc

MODE PROGRAMMING (V_{CC} = 5.0V \pm 5%, V_{SS} = 0V, Ta = 0 ~ +70°C, unless otherwise noted.)

Item	Symbol	Test Condition	min	typ	max	Unit
Mode Programming Input "Low" Voltage	VMPL		-	-	1.7	V
Mode Programming Input "High" Voltage	V _{MPH}		4.0	-	-	V
RES "Low" Pulse Width	PWRSTL	Fig. 8	3.0	-		t _{cyc}
Mode Programming Set-up Time	t _{MPS}]	2.0	-	-	t _{cyc}
Mode Programming Hold Time	tмрн		150	-	-	ns



Figure 1 Expanded Multiplexed Bus Timing







*Port 3 Non-Latched Operation (LATCH ENABLE = 0)

Figure 3 Data Set-up and Hold Times (MPU Read)



*Access matches Output Strobe Select (OSS = 0, a read; OSS = 1, a write)

Figure 5 Port 3 Output Strobe Timing (Single Chip Mode)



(Note)

- 1. IO k Pullup resistor required for Port 2 to reach 0.7 V_{CC} 2. Not applicable to P $_{11}$ 3. Port 4 cannot be pulled above V_{CC}





Figure 6 Port 3 Latch Timing (Single Chip Mode)



Figure 11 Reset Timing

SIGNAL DESCRIPTIONS

VCC and VSS

These two pins are used to supply power and ground to the chip. The voltage supplied will be +5 volts $\pm 5\%$.

XTAL and EXTAL

These connections are for a parallel resonant fundamental crystal, AT cut. Divide by 4 circuitry is included with the internal clock, so a 4 MHz crystal may be used to run the system at 1 MHz. The divide by 4 circuitry allows for use of the inexpensive 3.58 MHz Color TV crystal for non-time critical applications. Two 22pF capacitors are needed from the two crystal pins to ground to insure reliable operation. EXTAL may be driven by an external TTL compatible clock source with a 50% ($\pm 10\%$) duty cycle. It will divide by 4 any frequency less than or equal to 5 MHz. XTAL must be grounded if an external clock is used. The following are the recommended crystal parameters:

Nominal Crystal Parameter

Crystal	4 MHz	5 MHz
Co	7 pF max.	4.7 pF max.
Rs	60Ω max.	30 Ω typ.



Figure 12 Crystal Interface

VCC Standby

This pin will supply +5 volts $\pm 5\%$ to the standby RAM on the chip. The first 64 bytes of RAM will be maintained in the power down mode with 8 mA current max. The circuit of figure 13 can be utilized to assure that V_{CC} Standby does not go below V_{SBB} during power down.

To retain information in the RAM during power down the following procedure is necessary:

- Write "0" into the RAM enable bit, RAM E. RAM E is bit 6 of the RAM Control Register at location \$0014. This disables the standby RAM, thereby protecting it at power down.
- 2) Keep V_{CC} Standby greater than V_{SBB} .



Figure 13 Battery Backup for V_{CC} Standby

Reset (RES)

This input is used to reset and start the MPU from a power down condition, resulting from a power failure or an initial startup of the processor. On power up, the reset must be held "Low" for at least 100 ms. During operation, \overline{RES} , when brought "Low" must be held "Low" at least 3 clock cycles.

When a "High" level is detected, the MPU does the following:

- 1) All the higher order address lines will be forced "High".
- 2) I/O Port 2 bits, 2, 1, and 0 are latched into programmed control bits PC2, PC1 and PC0.
- The last two (\$FFFE, \$FFFF) locations in memory will be used to load the program addressed by the program counter.
- 4) The interrupt mask bit is set, must be cleared before the MPU can recognize maskable interrupts.

• Enable (E)

This supplies the external clock for the rest of the system when the internal oscillator is used. It is a single phase, TTL compatible clock, and will be the divide by 4 result of the crystal frequency. It will drive one TTL load and 90 pF.

Non-Maskable Interrupt (NMI)

A low-going edge on this input requests that a non-maskableinterrupt sequence be generated within the processor. As with interrupt Request signal, the processor will complete the current instruction that is being executed before it recognizes the \overline{NMI} signal. The interrupt mask bit in the Condition Code Register has no effect on \overline{NMI} .

In response to an NMI interrupt, the Index Register, Program Counter, Accumulators, and Condition Code Register are stored on the stack. At the end of the sequence, a 16-bit address will be loaded that points to a vectoring address located in memory locations \$FFFC and \$FFFD. An address loaded at these locations causes the MPU to branch to a non-maskable interrupt service routine in memory.

A 3.3 k Ω external resistor to VCC should be used for wire-OR and optimum control of interrupts.

Inputs IRQ_1 and \overline{NMI} are hardware interrupt lines that are sampled during E and will start the interrupt routine on the E following the completion of an instruction.

Interrupt Request (IRQ₁)

This level sensitive input requests that an interrupt sequence be generated within the machine. The processor will wait until it completes the current instruction that it being executed before it recognizes the request. At that time, if the interrupt mask bit in the Condition Code Register is not set, the machine will begin an interrupt sequence. The Index Register, Program Counter, Accumulators, and Condition Code Register are stored on the stack. Next the MPU will respond to the interrupt request by setting the interrupt mask bit "High" so that no further maskable interrupts may occur. At the end of the cycle, a 16-bit address will be loaded that points to a vectoring address which is located in memory locations SFFF8 and SFFF9. An address loaded at these locations causes the MPU to branch to an interrupt routine in memory.

The $\overline{IRQ_1}$ requires a 3.3 k Ω external resister to V_{CC} which should be used for wire-OR and optimum control of interrupts. Internal Interrupts will use an internal interrupt line ($\overline{IRQ_2}$). This interrupt will operate the same as $\overline{IRQ_1}$ except that it will use the vector address of SFFF0 through SFFF7. $\overline{IRQ_1}$ will have priority over $\overline{IRQ_2}$ if both occur at the same time. The Interrupt Mask Bit in the condition code register masks both interrupts (See Table 1).

	Vec	tor	Interrunt
	MSB	LSB	interrupt
Highest	FFFE	FFFF	RES
Priority	FFFC	FFFD	NMI
	FFFA	FFFB	Software Interrupt (SWI)
	FFF8	FFF9	IRQ, (or IS3)
	FFF6	FFF7	ICF (Input Capture)
	FFF4	FFF5	OCF (Output Compare)
	FFF2	FFF3	TOF (Timer Overflow)
Lowest	FFFO	FFF1	SC1 (RDRF + ORFE + TDRE)
PHORITY			

Table 1 Interrupt Vector Location

The following pins are available in the Single Chip Mode, and are associated with Port 3 only.

• Input Strobe (IS3) (SC₁)

The function of the $\overline{IS3}$ signal depends on the I/O Port 3 Control/Status Register. If $\overline{IS3}$ Enable bit is set, an interrupt will occur by the fall of the $\overline{IS3}$ signal. If the latch enable bit is set, the data in the I/O Port 3 will be latched at the I/O Port 3 Data Register. The timing condition of the $\overline{IS3}$ signal that is necessary to be latched the input data normally is shown in Figure 6.

• Output Strobe (OS3) (SC₂)

This signal is used by the processor to strobe an external device, indicating valid data is on the I/O pins. The timing for the Output Strobe is shown in Figure 5 I/O Port 3 Control/Status Register is discussed in the following section.

The following pins are available in the Expanded Modes.

Read/Write (R/W) (SC₂)

This TTL compatible output signals the peripherals and memory devices whether the MPU is in a Read ("High") or a Write ("Low") state. The normal standby state of this signal is Read ("High"). This output is capable of driving one TTL load and 90 pF.

I/O Strobe (IOS) (SC1)

In the expanded non-multiplexed mode of operation, \overline{IOS} internally decodes A₉ through A₁₅ as zero's and A₈ as a one. This allows external access of the 256 locations from \$0100 to \$01FF. The timing diagrams are shown as figure 2.

• Address Strobe (AS) (SC1)

In the expanded multiplexed mode of operation address strobe is output on this pin. This signal is used to latch the 8 LSB's of address which are multiplexed with data on Port 3. An 8-bit latch is utilized in conjunction with Address Strobe, as shown in figure 19. Expanded Multiplexed Mode. Address Strobe signals the latch when it is time to latch the address lines so the lines can become data bus lines during the E pulse. The timing for this singal is shown in Figure 1 of Bus Timing. This signal is also used to disable the address from the multiplexed bus allowing a deselect time, $t_{\rm ASD}$ before the data is enabled to the bus.

PORTS

There are four I/O ports on the HD6801V MCU; three 8-bit ports and one 5-bit port. There are two control lines associated with one of the 8-bit ports. Each port has an associated write only Data Direction Register which allows each I/O line to be programmed to act as an input or an output*. A "1" in the corresponding Data Direction Register bit will cause that I/O line to be an output. A "0" in the corresponding Data Direction Register bit will cause that I/O line to be an input. There are four ports: Port 1, Port 2, Port 3, and Port 4. Their addresses and the addresses of their Data Direction registers are given in Table 2.

* The only exception is bit 1 of Port 2, which can either be data input or Timer output.

Ports	Port Address	Data Direction Register Address
I/O Port 1	\$0002	\$0000
1/0 Port 2	\$0003	\$0001
I/O Port 3	\$0006	\$0004
I/O Port 4	\$0007	\$0005

Table 2 Port and Data Direction Register Addresses

• I/O Port 1

This is an 8-bit port whose individual bits may be defined as inputs or outputs by the corresponding bit in its data direction register. The 8 output buffers have three-state capability, allowing them to enter a high impedance state when the peripheral data lines are used as inputs. In order to be read properly, the voltage on the input lines must be greater than 2.0 V for a logic "1" and less than 0.8 V for a logic "0". As outputs these lines are TTL compatible and may also be used as a source of up to 1 mA at 1.5 V to directly drive a Darlington base. After Reset, the I/O lines are configured as inputs. In all three modes, Port 1 is always parallel I/O.

• I/O Port 2

This port has five lines that may be defined as inputs or outputs by its data direction register. The 5 output buffers have three-state capability, allowing them to enter a high impedance state when used as an input. In order to be read properly, the voltage on the input lines must be greater than 2.0 V for a logic "1" and less than 0.8 V for a logic "0". As outputs, this port has no internal pullup resistors but will drive TTL inputs directly. For driving CMOS inputs, external pullup resistors are required. After Reset, the I/O lines are configured as inputs. Three pins on Port 2 (pins 10, 9, and 8 of the chip) are used to program the mode of operation during reset. The values of these pins at reset are latched into the three MSB's (bits 7, 6, and 5) of Port 2 which are read only. This is explained in the Mode Selection Section.

In all three modes, Port 2 can be configured as I/O and provides access to the Serial Communications Interface and the Timer. Bit 1 is the only pin restricted to data input or Timer output.

• I/O Port 3

This is an 8-bit port that can be configured as 1/0, a data bus, or an address bus multiplexed with the data bus – depending on the mode of operation hardware programmed by the user at reset. As a data bus, Port 3 is bi-directional. As an input for peripherals, it must be supplied regular TTL levels, that is, greater than 2.0 V for a logic "J" and less than 0.8 V for a logic "0" Its TTL compatible three-state output buffers are capable of driving one TTL load and 90 pF. In the Expanded Modes, after reset, the data direction register is inhibited and data flow depends on the state of the R/W line. The input strobe ($\overline{IS3}$) and the output strobe ($\overline{OS3}$) used for handshaking are explained later.

In the three modes, Port 3 assumes the following characteristics:

Single Chip Mode: Parallel Inputs/Outputs as programmed by its associated Data Direction Register. There are two control lines associated with this port in this mode, an input strobe and an output strobe, that can be used for handshaking. They are controlled by the I/O Port 3 Control/Status Register explained at the end of this section. Three options of Port 3 operations are sumarized as follows: (1) Port 3 input data can be latched using $\overline{IS3}$ (SC₁) as a control signal, (2) $\overline{OS3}$ can be generated by either an MPU read or write to Port 3's Data Register, and (3) and $\overline{IRQ_1}$ interrupt can be enabled by an $\overline{IS3}$ negative edge. Port 3 latch and strobe timing is shown in Fig. 5 and Fig. 6.

Expanded Non-Multiplexed Mode: In this mode, Port 3 becomes the data bus $(D_0 \sim D_7)$.

Expanded Multiplexed Mode: In this mode, Port 3 becomes both the data bus $(D_0 \sim D_7)$ and lower bits of the address bus $(A_0 \sim A_7)$. An address strobe output is true when the address is on the port.

I/O PORT 3 CONTROL/STATUS REGISTER

	7	6	5	4	3	2	1	0
\$000F	IS3 FLAG	IS3 IRQ ₁ ENABLE	x	OSS	LATCH ENABLE	×	×	x

Bit 0; Not used.

Bit 1; Not used.

- Bit 2; Not used.
- Bit 3; LATCH ENABLE. This controls the input latch for I/O Port 3. If this bit is set "High" the input data will be latched with the falling edge of the Input Strobe, IS3. This bit is cleared by reset, and the latch is "re-opened" with MCU read Port 3.
- Bit 4: OSS. (Output Strobe Select) This bit will select if the Output Strobe should be generated at $\overline{OS3}$ (SC₂) by a write to I/O Port 3 or a read of I/O Port 3. When this bit is cleared the strobe is generated by a read Port 3. When this bit is set the strobe is generated by a write Port 3.
- Bit 5; Not used.
- Bit 6; IS3 IRQ1 ENABLE. When set, interrupt will be enabled whenever IS3 FLAG is set; when clear, interrupt is inhibited. This bit is cleared by RES.
- Bit 7; IS3 FLAG. This is a read only status bit that is set by the falling edge of the input strobe, IS3 (SC₁). It is cleared by a read of the Control/Status Register followed by a read or write of I/O Port 3. Reset will clear this bit.

I/O Port 4

This is an 8-bit port that can be configured as I/O or as address lines depending on the mode of operation. In order to be read properly, the voltage on the input lines must be greater than 2.0 V for a logic "1" and less than 0.8 V for a logic "0".

As outputs, each line is TTL compatible and can drive 1 TTL

load and 90 pF. After reset, the lines are configured as inputs. To use the pins as addresses, therefore, they should be programmed as outputs. In the three modes, Port 4 assumes the following characteristics:

Single Chip Mode: Parallel Inputs/Outputs as programmed by its associated Data Direction Register.

Expanded Non-Multiplexed Mode: In this mode, Port 4 is configured as the lower order address lines $(A_0 \sim A_7)$ by writing one's to the data direction register. When all eight address lines are not needed, the remaining lines, starting with the most significant bit, may be used as I/O (inputs only).

Expanded Multiplexed Mode: In this mode, Port 4 is configured as the higher order address lines $(A_8 \sim A_{15})$ by writing one's to the data direction register. When all eight address lines are not needed, the remaining lines, starting with the most significant bit, may be used as I/O (inputs only).

OPERATION MODES

The mode of operation that HD6801V will operate in after Reset is determined by hardware that the user must wire on pins 10, 9, and 8 of the chip. These pins are the three LSB's (I/O 2, I/O 1, and I/O 0 respectively) of Port 2. They are latched into programmed control bits PC2, PC1, and PC0 when reset goes high. I/O Port 2 Register is shown below.

PORT 2 DATA REGIS

	7	6	5	4	3	2	1	0
\$0003	PC2	PC1	PC0	1/0 4	1/0 3	1/0 2	1/0 1	1/0 0

An example of external hardware that could be used for Mode Selection is shown in Fig 14. The HD14053B provides the isolation between the peripheral device and MCU during Reset, which is necessary if data conflict can occur between peripheral device and Mode generation circuit.

As bits 5, 6 and 7 of Port 2 are read only, the mode cannot be changed through software. The mode selections are shown in Table 3.

The HD6801V is capable of operating in three basic modes; (1) Single Chip Mode, (2) Expanded Multiplexed Mode (compatible with HMCS6800 peripheral family) (3) Expanded Non-Multiplexed Mode.

• Single Chip Mode

In the Single Chip Mode the Ports are configured for I/O. This is shown in Figure 16 the single Chip Mode. In this mode, Port 3 will have two associated control lines, an input strobe and an output strobe for handshaking data.

Expanded Non-Multiplexed Mode

In this mode the HD6801V will directly address HMCS6800 peripherals with no external logic. In this mode Port 3 becomes the data bus. Port 4 becomes the $A_0 \sim A_7$ address bus or partial address and I/O (inputs only). Port 2 can be parallel I/O, serial I/O, Timer, or any combination of them. Port 1 is parallel I/O only. In this mode the HD6801V is expandable to 256 locations. The eight address lines associated with Port 4 may be substituted for I/O (inputs only) if a fewer number of address lines will satisfy the application (See Figure 17).



Figure 14 Recommended Circuit for Mode Selection



		Tru	th]	Fable							
Contr	011	npu	ĸ	0.	On Switch						
Inhibit	S	iele	ct	On Switch							
minor	С	в	A	HD14053B							
0	0	0	0	Z.	Y,	X,					
0	0	0	1	Z,	Y,	х,					
0	0	1	0	Z,	۷,	×。					
0	0	1	1	z,	۷,	x,					
0	1	0	0	Ζ,	Y,	×,					
0	1	0	1	Z,	Y,	×,					
0	1	1	0	Z,	۲,	×,					
0	1	1	1	Ζ,	Y,	х,					
1	X	X	X		-						

Figure 15 HD14053B Multiplexers/Demultiplexers





Figure 17 HD6801V MCU Expanded Non-Multiplexed Mode

Figure 16 HD6801V MCU Single-Chip Mode

Expanded Multiplexed Mode •

In this mode Port 4 becomes higher order address lines with an alternative of substituting some of the address lines for I/O (inputs only). Port 3 is the data bus multiplexed with the lower order address lines differentiated by an output called Address Strobe. Port 2 is 5 lines of Parallel I/O, SCI, Timer, or any combination of them. Port 1 is 8 Parallel I/O lines. In this mode it is expandable to 65k words. (See Figure 18).

Lower order Address Bus Latches

Since the data bus is multiplexed with the lower order address bus in Port 3, latches are required to latch those address bits. The 74LS373 Transparent octal D-type latch can be used with the HD6801V to latch the least significant address byte. Figure 19 shows how to connect the latch to the HD6801V. The output control to the 74LS373 may be connected to ground.







Function Table

Output	En	able	Output
Control	G	D	٩
L	н	н	н
L	н	L	L
L	L	х	a,
н	х	×	z

Figure 19 Latch Connection

Mode and Port Summary MCU Signal Description

This section gives a description of the MCU signals for the various modes. SC1 and SC2 are signals which vary with the mode that the chip is in.

MODE	PORT 1 Eight Lines	PORT 2 Five Lines	PORT 3 Eight Lines	PORT 4 Eight Lines	SC1	SC ₂
SINGLE CHIP	1/0	1/0	1/0	1/0	ī s 3 (I)	053 (0)
EXPANDED MUX	1/0	1/0	ADDRESS BUS $(A_0 \sim A_7)$ DATA BUS $(D_0 \sim D_7)$	ADDRESS BUS* (A ₈ ~A ₁₅)	AS(O)	R/₩(O)
EXPANDED NON-MUX	1/0	1/0	DATA BUS (D ₀ ~D ₇)	ADDRESS BUS* $(A_0 \sim A_7)$	IOS(O)	R/₩(0)

*These lines can be substituted for I/O (Input Only) starting with the most significant address line. I = Input SC = Strobe Control 0 = Outout

R/W = Read/Write

IS3 = Input Strobe OS3 = Output Strobe IOS = I/O Select

AS = Address Strobe

Mode	P22 (PC2)	P21 (PC1)	P30 (PC0)	ROM	RAM	Interrupt Vectors	Bus Mode	Operating Mode
7	н	н	н	I	1	I		Single Chip
6	н	н	L	I	1	I	MUX ⁽⁶⁾	Multiplexed/Partial Decode
5	н	L	н	I	1	1	NMUX ⁽⁶⁾	Non-Multiplexed/Partial Decode
4	н	L	L	1(2)	1(1)	1	1	Single Chip Test
3	L	н	н	E	E	E	MUX	Multiplexed/No RAM & ROM
2	L	н	L	E	1	E	MUX	Multiplexed/RAM
1	L	L	н	1	1	E	MUX	Multiplexed/RAM & ROM
ο,	L	L	L	1	1	l(3)	MUX	Multiplexed Test

Table 3 Mode Selection Summary

LEGEND:

I - Internal E - External MUX - Multiplexed NMUX - Non-Multiplexed L - Logic "0" H - Logic "1"

[NOTES]

1) Internal RAM is addressed at \$XX80

2) Internal ROM is disabled

3) RES vector is external for 2 cycles after RES goes "High"

4) Addresses associated with Ports 3 and 4 are considered external in Modes 0, 1, 2, and 3

5) Addresses associated with Port 3 are considered external in Modes 5 and 6

6) Port 4 default is user data input; address output is optional by writing to Port 4 **Data Direction Register**

MEMORY MAPS

The MCU can provide up to 65k byte address space depending on the operating mode. A memory map for each operating mode is shown in Figure 20. The first 32 locations of each map are reserved for the MCU's internal register area, as shown in Table 4. With exceptions as indicated.

INTERRUPT FLOWCHART

The Interrupt flowchart is depicted in Figure 24 and is common to every interrupt excluding reset.

Table 4 Internal Register Area	
Register	Address
Port 1 Data Direction Register ***	00
Port 2 Data Direction Register***	01
Port 1 Data Register	02
Port 2 Data Register	03
Port 3 Data Direction Register***	04•
Port 4 Data Direction Register ***	05**
Port 3 Data Register	06*
Port 4 Data Register	07**
Timer Control and Status Register	08
Counter (High Byte)	09
Counter (Low Byte)	0A
Output Compare Register (High Byte)	OB
Output Compare Register (Low Byte)	oc
Input Capture Register (High Byte)	0D
Input Capture Register (Low Byte)	OE
Port 3 Control and Status Register	0F*
Rate and Mode Control Register	10
Transmit/Receive Control and Status Register	11
Receive Data Register	12
Transmit Data Register	13
RAM Control Register	14
Reserved	15-1F

External address in Modes 0, 1, 2, 3, 5, 6; cannot be accessed in Mode 5 (No. IOS)

** External addresses in Modes 0, 1, 2, 3

*** 1=Output, 0=Input+



Figure 20 HD6801V Memory Maps



Figure 20 HD6801V Memory Maps (Continued)



Figure 20 HD6801V Memory Maps (Continued)



Figure 20 HD6801V Memory Maps (Continued)

PROGRAMMABLE TIMER

The HD6801V contains an on-chip 16-bit programmable timer which may be used to perform measurements on an input waveform while independently generating an output waveform. Pulse widths for both input and output signals may vary from a few microseconds to many seconds. The timer hardware consists of

- an 8-bit control and status register,
- a 16-bit free running counter,
- a 16-bit output compare register, and
- a 16-bit input capture register
- A block diagram of the timer registers is shown in Figure 21.

• Free Running Counter (\$0009:000A)

The key element in the programmable timer is a 16-bit free running counter which is driven to increasing values by E (Enable). The counter value may be read by the MPU software at any time. The counter is cleared to zero on \overline{RES} and may be considered a read-only register with one exception. Any MPU write to the counter's address (\$09) will always result in preset value of \$FFF8 being loaded into the counter regardless of the value involved in the write. This preset figure is intended for testing operation of the part, but may be of value in some applications.

Output Compare Register (\$000B:000C)

The Output Compare Register is a 16-bit read/write register which is used to control an output waveform. The contents of this register are constantly compared with the current value of the free running counter. When a match is found, a flag is set (OCF) in the Timer Control and Status Register (TCSR) and the current value of the Output Level bit (OLVL) in the TCSR is clocked to the Output Level Register. Providing the Data Direction Register for Port 2, Bit 1 contains a "1" (Output), the output level register value will appear on the pin for Port 2 Bit 1. The values in the Output Compare Register and Output level bit may then be changed to control the output level on the next compare value. The Output Compare Register is set to \$FFFF during RES. The Compare function is inhibited for one cycle following a write to the high byte of the Output Compare Register to insure a valid 16-bit value is in the register before a compare is made.

• Input Capture Register (\$000D:000E)

The Input Capture Register is a 16-bit read-only register used to store the current value of the free running counter when the proper transition of an external input signal occurs. The input transition change required to trigger the counter transfer is controlled by the input Edge bit (IEDG) in the TCSR. The Data Direction Register bit for Port 2 Bit 0, should* be clear (zero) in order to gate in the external input signal to the edge detect unit in the timer.

• With Port 2 Bit 0 configured as an output and set to "1", the external input will still be seen by the edge detect unit.

Timer Control and Status Register (TCSR) (\$0008)

The Timer Control and Status Register consists of an 8-bit register of which all 8 bits are readable but only the low order 5 bits may be written. The upper three bits contain read-only timer status information and indicate that:

- a proper transition has taken place on the input pin with a subsequent transfer of the current counter value to the input capture register.
- a match has been found between the value in the free running counter and the output compare register, and
- when \$0000 is in the free running counter.

Each of the flags may be enabled onto the HD6801V internal bus $(\overline{IRQ_2})$ with an individual Enable bit in the TCSR. If the



Figure 21 Block Diagram of Programmable Timer

Timer Control and Status Register



I-bit in the HD6801V Condition Code register has been cleared, a priority vectored interrupt will occur corresponding to the flag bit(s) set. A description for each bit follows:

- Bit 0 OLVL Output Level This value is clocked to the output level register on a successful output compare. If the DDR for Port 2 bit 1 is set, the value will appear on the output pin.
- Bit 1 IEDG Input Edge This bit controls which transition of an input will trigger a transfer of the counter to the input capture register. The DDR for Port 2 Bit 0 must be clear for this function to operate. IEDG = 0 Transfer takes place on a negative edge ("High"-to-"Low" transition).

IEDG = 1 Transfer takes place on a positive edge ("Low"-to-"High" transition).

- Bit 2 ETOI Enable Timer Overflow Interrupt When set, this bit enables IRQ₂ to occur on the internal bus for a TOF interrupt; when clear the interrupt is inhibited.
- Bit 3 EOCI Enable Output Compare Interrupt When set, this bit enables $\overline{IRQ_2}$ to appear on the internal bus for an output compare interrupt; when clear the interrupt is inhibited.
- Bit 4 EICI Enable input Capture Interrupt When set, this bit enables $\overline{IRQ_2}$ to occur on the internal bus for an input capture interrupt; when clear the interrupt is inhibited.
- Bit 5 TOF Timer Overflow Flag This read-only bit is set when the counter contains \$0000. It is cleared by a read of the TCSR (with TOF set) followed by an MPU read of the Counter (\$09).
- Bit 6 OCF Output Compare Flag This read-only bit is set when a match is found between the output compare register and the free running counter. It is cleared by a read of the TCSR (with OCF set) followed by an MPU write to the output compare register (\$0B or \$0C).
- Bit 7 ICF Input Capture Flag This read-only status bit is set by a proper transition on the input; it is cleared by a read of the TCSR (with ICF set) followed by an MPU read of the Input Capture Register (\$0D).

SERIAL COMMUNICATIONS INTERFACE

The HD6801V contains a full-duplex asynchronous serial communications interface (SCI) on chip. The controller comprises a transmitter and a receiver which operate independently or each other but in the same data format and at the same data rate. Both transmitter and receiver communicate with the MPU via the data bus and with the outside world via pins 2, 3, and 4 of Port 2. The hardware, software, and registers are explained in the following paragraphs.

Wake-Up Feature

In a typical multi-processor application, the software protocol will usually contain a destination address in the initial byte(s) of the message. In order to permit non-selected MPU's to ignore the remainder of the message, a wake-up feature is included whereby all further interrupt processing may be optionally inhibited until the beginning of the next message. When the next message appears, the hardware re-enables (or "wakes-up") for the next message. The "wake-up" is automatically triggered by a string of ten consecutive 1's which indicates an idle transmit line. The software protocol must provide for the short idle period between any two consecutive messages.

Programmable Options

The following features of the HD6801V serial I/O section are programmable:

- · format standard mark/space (NRZ)
- Clock external or internal
- baud rate one of 4 per given MPU ϕ_2 clock frequency or external clock $\times 8$ input
- wake-up feature enabled or disabled
- Interrupt requests enabled or masked individually for transmitter and receiver data registers
- clock output internal clock enabled or disabled to Port 2 (Bit 2)
- Port 2 (bits 3 and 4) dedicated or not dedicated to serial I/O individually for transmitter and receiver.

Serial Communications Hardware

The serial communications hardware is controlled by 4 registers as shown in Figure 22. The registers include:

- an 8-bit control and status register
- a 4-bit rate and mode control register (write only)
- an 8-bit read only receive data register and
- an 8-bit write only transmit data register.

In addition to the four registers, the serial I/O section utilizes bit 3 (serial input) and bit 4 (serial output) of Port 2. Bit 2 of Port 2 is utilized if the internal-clock-out or external-clock-in options are selected.

Transmit/Receive Control and Status (TRCS) Register

The TRCS register consists of an 8-bit register of which all 8 bits may be read while only bits 0^{-4} may be written. The register is initialized to \$20 on RES. The bits in the TRCS register are defined as follows:

Transmit/Receive Control and Status Register

7	6	5	4	3	2	1	0	
RDRF	ORFE	TDRE	RIE	RE	TIE	TE	WU	ADDR : \$0011



Figure 22 Serial I/O Registers

- Bit 0 WU "Wake-up" on Next Message set by HD6801V software and cleared by hardware on receipt of ten consecutive 1's or reset of RE flag. It should be noted that RE flag should be set in advance of MPU set of WU flag.
- Bit 1 TE Transmit Enable set by HD6801V to produce preamble of nine consecutive 1's and to enable gating of transmitter output to Port 2, bit 4 regardless of the DDR value corresponding to this bit; when clear, serial I/O has no effect on Port 2 bit 4.

TE set should be after at least one bit time of data transmit rate from the set-up of transmit data rate and mode.

- Bit 2 TIE Transmit Interrupt Enable when set, will permit an $\overline{IRQ_2}$ interrupt to occur when bit 5 (TDRE) is set; when clear, the TDRE value is masked from the bus.
- Bit 3 RE Receiver Enable when set, gates Port 2 bit 3 to input of receiver regardless of DDR value for this bit; when clear, serial I/O has no effect on Port 2 bit 3.
- Bit 4 RIE Receiver Interrupt Enable when set, will permit an $\overline{IRQ_2}$ interrupt to occur when bit 7 (RDRF) or bit 6 (ORFE) is set; when clear, the interrupt is masked.
- Bit 5 TDRE Transmit Data Register Empty set by hardware when a transfer is made from the transmit data register to the output shift register. The TDRE bit is cleared by reading the status register, then writing a new byte into the transmit data register,

TDRE is initialized to 1 by RES.

- Bit 6 ORFE Over-Run-Framing Error set by hardware when an overrun or framing error occurs (receive only). An overrun is defined as a new byte received with last byte still in Data Register/Buffer. A framing error has occurred when the byte boundaries in bit stream are not synchronized to bit counter. If WU flag is set, the ORFE bit will not be set. The ORFE bit is cleared by reading the status register, then reading the Receive Data Register, or by RES.
- Bit 7 RDRF Receiver Data Register Full set by hardware when a transfer from the input shift register to the receiver data register is made. If WU flag is set, the RDRF bit will not be set. The RDRF bit is cleared by reading the status register, then reading the Receive Data Register, or by RES.

Rate and Mode Control Register

The Rate and Mode Control register controls the following serial I/O variables:

- Baud rate
- format
- clocking source, and
- Port 2 bit 2 configuration

The register consists of 4 bits all of which are write-only and cleared on \overline{RES} . The 4 bits in the register may be considered as a pair of 2-bit fields. The two low order bits control the bit rate for internal clocking and the remaining two bits control the format and clock select logic. The register definition is as follows:

Rate and Mode Control Register



Bit 0 SSO Speed Select - These bits select the Baud rate for Bit | SS1 the internal clock. The four rates which may be selected are a function of the MPU ϕ_2 clock frequency. Table 5 lists the available Baud rates.

Bit 2 CCO Clock Control and Format Select - this 2-bit field Bit 3 CC1 controls the format and clock select logic. Table 6 defines the bit field.

Table 5 SCI Bit Times and Rates

		XTAL	2.4576 MHz	4.0 MHz	4.9152 MHz*
SS1	: SSO	Ε	614.4 kHz	1.0 MHz	1.2288 MHz
0	0	E ÷ 16	26 µs/38,400 Baud	16 µs/62,500 Baud	13 µs/76,800 Baud
0	1	E ÷ 128	208 µs/4,800 Baud	128 µs/7812.5 Baud	104.2 µs/9,600 Baud
1	0	E ÷ 1024	1.67 ms/600 Baud	1.024 ms/976.6 Baud	33.3 µs/1,200 Baud
1	1	E ÷ 4096	6.67 ms/150 Baud	4.096 ms/244.1 Baud	3.33 ms/300 Baud

*HD6801V5 Only

Table 6 SCI Format and Clock Source Control

CC1, CC0	Format	Clock Source	Port 2 Bit 2	Port 2 Bit 3	Port 2 Bit 4
00	-	-	-	**	**
01	NRZ	Internal	Not Used	**	**
10	NRZ	Internal	Output*	**	••
11	NRZ	External	Input	**	••

Clock output is available regardless of values for bits RE and TE.
 Bit 3 is used for serial input if RE = "1" in TRCS; bit 4 is used for serial output if TE = "1" in TRCS.

Internally Generated Clock

If the user wishes for the serial I/O to furnish a clock, the following requirements are applicable:

- the values of RE and TE are immaterial.
- CC1, CC0 must be set to 10
- the maximum clock rate will be $E \div 16$.
- the clock will be at $1 \times$ the bit rate and will have a rising edge at mid-bit.

Externally Generated Clock

If the user wishes to provide an external clock for the serial I/O, the following requirements are applicable:

- the CC1, CC0, field in the Rate and Mode Control Register must be set to 11.
- the external clock must be set to 8 times (×8) the desired baud rate and
- the maximum external clock frequency is 1.0 MHz.

Serial Operations

The serial I/O hardware should be initialized by the HD6801V software prior to operation. This sequence will normally consist of;

- · writing the desired operation control bits to the Rate and Mode Control Register and
- writing the desired operational control bits in the Transmit/ Receive Control and Status Register.

The Transmitter Enable (TE) and Receiver Enable (RE) bits may be left set for dedicated operations.

Transmit Operations

The transmit operation is enabled by the TE bit in the Transmit/Receive Control and Status Register. This bit when set, gates the output of the serial transmit shift register to Port 2 Bit 4 and takes unconditional control over the Data Direction Register value for Port 2, Bit 4.

Following a RES the user should configure both the Rate and Mode Control Register and the Transmit/Receive Control and Status Register for desired operation. Setting the TE bit during this procedure initiates the serial output by first transmitting a ten-bit preamble of 1's. Following the preamble, internal synchronization is established and the transmitter section is ready for operation.

At this point one of two situation exist:

- 1) if the Transmit Data Register is empty (TDRE = 1), a continuous string of ones will be sent indicating an idle line. or.
- 2) if data has been loaded into the Transmit Data Register (TDRE = 0), the word is transferred to the output shift register and transmission of the data word will begin.

During the transfer itself, the 0 start bit is first transmitted. Then the 8 data bits (beginning with bit 0) followed by the stop bit, are transmitted. When the Transmitter Data Register has been emptied, the hardware sets the TDRE flag bit.

If the HD6801V fails to respond to the flag within the proper time, (TDRE is still set when the next normal transfer from the parallel data register to the serial output register should occur) then a 1 will be sent (instead of a 0) at "Start" bit time, followed by more 1's until more data is supplied to the data register. No 0's will be sent while TDRE remains a 1.

Receive Operation

The receive operation is enabled by the RE bit which gates in the serial input through Port 2 Bit 3. The receiver section operation is conditioned by the contents of the Transmit/ Receive Control and Status Register and the Rate and Mode Control Register.

The receiver bit interval is divided into 8 sub-intervals for internal synchronization. In the NRZ Mode, the received bit stream is synchronized by the first 0 (space) encountered.

The approximate center of each bit time is strobed during the next 10 bits. If the tenth bit is not a 1 (stop bit) a framing error is assumed, and bit ORFE is set. If the tenth bit as a 1, the data is transferred to the Receive Data Register, and interrupt flag RDRF is set. If RDRF is still set at the next tenth bit time, ORFE will be set, indicating an over-run has occurred. When the HD6801V responds to either flag (RDRF or ORFE) by reading the status register followed by reading the Data Register, RDRF (or ORFE) will be cleared.

RAM CONTROL REGISTER

This register, which is addressed at \$0014, gives status information about the standby RAM. A 0 in the RAM enable bit (RAM E) will disable the standby RAM, thereby protecting it at power down if V_{CC} Standby is held greater than V_{SBB} volts, as explained previously in the signal description for V_{CC} Standby.

RAM Control Register

\$0014	STBY PWR	RAME	×	x	×	×	x	×
							_	

Bit 0 Not used.

- Bit 1 Not used.
- Bit 2 Not used.
- Bit 3 Not used.
- Bit 4 Not used.
- Bit 5 Not used.
- Bit 6 RAME The RAM Enable control bit allows the user the ability to disable the standby RAM. This bit is set to a logic "1" by \overline{RES} which enables the standby RAM and can be written to one or zero under program control. When the RAM is disabled, data is read from external memory.
- Big 7 STBY The Standby Power bit is cleared when the stand-PWR by voltage is removed. This bit is a read/write status flag that the user can read which indicates that the standby RAM voltage has been applied, and the data in the standby RAM is valid.

GENERAL DESCRIPTION OF INSTRUCTION SET

The HD6801V is upward object code compatible with the HD6800 as it implements the full HMCS6800 instruction set. The execution times of key instructions have been reduced to increase throughout. In addition, new instructions have been added; these include 16-bit operations and a hardware multiply.

- Included in the instruction set section are the following:
- MPU Programming Model (Figure 23)
- Addressing modes
- Accumulator and memory instructions Table 7
- New instructions
- Index register and stack manipulations instructions Table 8

- $\bullet \mbox{ Condition code register manipulation instructions} \mbox{ Table 10}$
- Instructions Execution times in machine cycles Table 11
- Summary of cycle by cycle operation Table 12
- Summary of undefined instructions operation
- Op codes Map Table 13

MPU Programming Model

The programming model for the HD6801V is shown in Figure 23. The double (D) accumulator is physically the same as the Accumulator A concatenated with the Accumulator B so that any operation using accumulator D will destroy information in A and B.



Figure 23 MCU Programming Model

MPU Addressing Modes

The HD6801V eight-bit microcomputer unit has seven address modes that can be used by a programmer, with the addressing mode a function of both the type of instruction and the coding within the instruction. A summary of the addressing modes for a particular instruction can be found in Table 11 along with the associated instruction execution time that is given in machine cycles. With a clock frequency of 4 MHz, these times would be microseconds.

Accumulator (ACCX) Addressing

In accumulator only addressing, either accumulator A or accumulator B is specified. These are one-byte instructions. Immediate Addressing

In immediate addressing, the operand is contained in the second byte of the instruction except LDS and LDX which have the operand in the second and third bytes of the instruction. The MCU addresses this location when it fetches the immediate instruction for execution. These are two or three-byte instructions.

• Jump and branch instructions - Table 9

HD6801V0, HD6801V5-----

		Addressing Modes					C	one	liti	on (Cod	e											
Operations	Mnemonic			_				r —			-			, —			Boolean/			Reg	iste	r 	
		IM	ME	<u>P.</u>	DIF	REC	T		DE	<u>×</u>	EX.	TEN				ED	Arithmetic Operation	5	4	3	2	1	<u> </u>
I		OP	~	#	OP	~	#	OP	~	#	OP	~	#	OP	~	#		н	1	N	z	V.	с
Add	ADDA	8B	2	2	9B	3	2	AB	4	2	88	4	3				A + B → A	ŧ	٠	\$	ŧ	\$	\$
	ADDB	СВ	2	2	DB	3	2	EB	4	2	FB	4	3				$B + M \rightarrow B$	\$	•	\$	\$	\$	\$
Add Double	ADDD	C3	4	3	D3	5	2	E3	6	2	F3	6	3	{ -			$A: B+M: M+1 \rightarrow A: B$	•	•	1	\$	\$	+
Add Accumulators	ABA													1B	2	1	$A + B \rightarrow A$	1	•	\$	1	\$	\$
Add With Carry	ADCA	89	2	2	99	3	2	A9	4	2	В9	4	3				$A + M + C \rightarrow A$	\$	•	\$	\$	\$:
	ADCB	C9	2	2	D9	3	2	E9	4	2	F9	4	3				$B + M + C \rightarrow B$	\$	•	\$	\$	\$	1
AND	ANDA	84	2	2	94	3	2	A4	4	2	B4	4	3				A·M → A	•	•	1	1	R	•
	ANDB	C4	2	2	D4	3	2	E4	4	2	F4	4	.3				B·M→B	•	•	:	1	R	•
Bit Test	BITA	85	2	2	95	3	2	A5	4	2	B5	4	3				A·M	•	•	1	1	R	•
	BITB	C5	2	2	D5	3	2	E5	4	2	F5	4	3				B·M	•	•	\$	\$	R	•
Clear	CLR		1_					6F	6	2	7F	6	3				00 → M	•	•	R	S	R	R
	CLRA													4F	2	1	00 → A	•	•	R	s	R	R
	CLRB													5F	2	1	00 → B	•	•	R	S	R	R
Compare	CMPA	81	2	2	91	3	2	A1	4	2	B1	4	3				A - M	•	•	\$	\$	1	1
	СМРВ	C1	2	2	D1	3	2	E1	4	2	F 1	4	3	÷			B – M	•	•	\$	‡	\$	+
Compare Accumulators	СВА													11	2	1	А – В	•	٠	\$	t	\$	1
Complement, 1's	COM		Γ					63	6	2	73	6	3			-	M → M	•	•	1	\$	R	s
	COMA	1		1										43	2	1	Ā → A	•	•	1	1	R	s
	СОМВ								-	-		Γ		53	2	1	B → B	•	•	\$	\$	R	s
Complement, 2's	NEG			-				60	6	2	70	6	3				00 - M → M	•	•	\$	\$	0	2
(Negate)	NEGA													40	2	1	$00 - A \rightarrow A$	•	•	1	\$	٢	2
	NEGB											L		50	2	1	00 – B → B	•	•	ŧ	\$	$^{(1)}$	2
Decimal Adjust, A	DAA													19	2	1	Converts binary add of BCD characters into BCD format	•	•	ŧ	\$	1	3
Decrement	DEC		1					6A	6	2	7A	6	3				$M - 1 \rightarrow M$	•	•	ŧ	1	٩	
	DECA		T				\square	1				1	1	4A	2	1	$A - 1 \rightarrow A$	•	•	ŧ	1	4	
	DECB							1						5A	2	1	B - 1 → B	•	•	1	1	4	•
Exclusive OR	EORA	88	2	2	98	3	2	A8	4	2	B8	4	3	1			$A \oplus M \rightarrow A$	•	•	1	\$	R	•
	EORB	C8	2	2	D8	3	2	E8	4	2	F8	4	3	1		1	B ⊕ M→ B	•	•	1	1	R	•
Increment	INC						T	6C	6	2	7C	6	3	1		Γ	M + 1 → M	•	•	1	1	\$	•
	INCA			-								Γ	Ĺ	4C	2	1	A + 1 → A	•	•	1	1	5	•
	INCB		Γ											5C	2	1	B + 1 → B	•	•	\$	1	(5)	•
Load	LDAA	86	2	2	96	3	2	A6	4	2	B 6	4	3				M → A	•	•	1	1	R	•
Accumulator	LDAB	C6	2	2	D6	3	2	E6	4	2	F6	4	3	[]		{	M → B	•	•	ŧ	1	R	•
Load Double Accumulator	LDD	сс	3	3	DC	4	2	EC	5	2	FC	5	3				M + 1 → B, M → A	•	•	1	1	R	•
Multiply Unsigned	MUL					-	1			1		1-		3D	10	1	A x B → A : B	•	•	٠	•	•	1
OR, Inclusive	ORAA	8A	2	2	9A	3	2	AA	4	2	BA	4	3				$A + M \rightarrow A$	•	•	1	1	R	•
	ORAB	CA	2	2	DA	3	2	EA	4	2	FA	4	3			1	B + M→ B	•	•	1	ŧ	R	•
Push Data	PSHA	1	\square							1	1	t		36	3	1	$A \rightarrow Msp, SP - 1 \rightarrow SP$	•	•	•	•	•	•
	PSHB		1-	1			T				1-	T	1-	37	3	1	$B \rightarrow Msp, SP - 1 \rightarrow SP$	•	•	•	•	•	•
Pull Data	PULA		1	1		-	1				-			32	4	1	SP + 1 \rightarrow SP, Msp \rightarrow A	•	•	•	. •	•	•
	PULB						Γ					Γ.		33	4	1	$SP + 1 \rightarrow SP, Msp \rightarrow B$	•	•	•	٠	•	•
Rotate Left	ROL		Γ				Γ	69	6	2	79	6	3	1			M	•	•	1	\$	6	+
	ROLA	T	Γ				Γ			1	1	Γ		49	2	1		•	•	II	1	(6)	1
	ROLB		1	1		_	\top	1	-		1	†		59	2	1	в С 67 60	•	•	ŧ	1	6	1
Rotate Right	ROR			\Box				66	6	2	76	6	3				M, []	•	•	\$	1	6	\$
	RORA													46	2	1		•	٠	1	1	6	\$
	RORB													56	2	1	B	•	•	1	1	6	1

Table 7 Accumulator & Memory Instructions

The Condition Code Register notes are listed after Table 10.

(Continued)

-

		Γ	7				Ado	dressi	ng l	Moc	les					J.		Condition Code Register							
Operations	Mnemonic	IM	ME	D.	DIF	REC	т	IN	DE	x	EX	TEN	١D	IMF	LIE	D	Boolean/ Arithmetic Operation	5	4	3	2	1	0		
		OP	~	#	OP	~	#	OP	~	#	OP	~	#	OP	~	#		н	1	N	z	v	с		
Shift Left	ASL							68	6	2	78	6	3				M	•	•	\$	\$	6	\$		
Arithmetic	ASLA			1 -		-	1	1	1		1		Γ	48	2	1		•	•	‡	\$	6	\$		
	ASLB												Γ	58	2	1	в) С 67 60	•	•	\$	\$	6	\$		
Double Shift Left, Arithmetic	ASLD													05	3	1		•	•	\$	\$	6	ŧ		
Shift Right	ASR							67	6	2	77	6	3		T	1	M)	•	•	\$	\$	6	\$		
Arithmetic	ASRA	1		1		-	1					1	1	47	2	1		•	•	\$	\$	6	\$		
	ASRB					1			-	1			T	57	2	1	B/ 6/ 60 C	•	•	\$	ŧ	6	\$		
Shift Right	LSR							64	6	2	74	6	3		Γ	Γ	M)	•	•	\$	t	6	\$		
Logical	LSRA													44	2	1		•	•	\$	\$	6	\$		
	LSRB	1					1							54	2	1	8 67 69 C	•	•	\$	\$	6	\$		
Double Shift Right Logical	LSRD													04	3	1		•	•	R	ŧ	6	\$		
Store	STAA				97	3	2	A7	4	2	B7	4	3				$A \rightarrow M$	•	•	\$	\$	R	•		
Accumulator	STAB				D7	3	2	E7	4	2	F7	4	3				B → M	•	•	\$	\$	R	•		
Store Double Accumulator	STD				DD	4	2	ED	5	2	FD	5	3				$A \rightarrow M$ $B \rightarrow M + 1$	•	•	t	ŧ	R	•		
Subtract	SUBA	80	2	2	90	3	2	A0	4	2	B0	4	3				$A - M \rightarrow A$	•	•	\$	\$	\$	\$		
11 A.	SUBB	CO	2	2	DO	3	2	E0	4	2	FO	4	3				B - M → B	•	•	\$	\$	\$	\$		
Double Subtract	SUBD	83	4	3	93	5	2	A3	6	2	B 3	6	3	1			A : B – M : M + 1 → A : B	•	•	\$	\$	\$	\$		
Subtract Accumulators	SBA													10	2	1	$A - B \rightarrow A$	•	•	\$	\$	\$	\$		
Subtract	SBCA	82	2	2	92	3	2	A2	4	2	B2	4	3				$A - M - C \rightarrow A$	•	•	\$	\$	\$	\$		
With Carry	SBCB	C2	2	2	D2	3	2	E2	4	2	F2	4	3				$B - M - C \rightarrow B$	•	•	\$	\$	\$	\$		
Transfer	TAB													16	2	1	$A \rightarrow B$	•	•	\$	\$	R	•		
Accumulators	ТВА						1_			1				17	2	1	$B \rightarrow A$	•	•	\$	\$	R	•		
Test Zero or	TST							6D	6	2	7D	6	3				M - 00	•	•	ŧ	\$	R	R		
Minus	TSTA													4D	2	1	A - 00	•	•	\$	\$	R	R		
	TSTB													5D	2	1	B – 00	•	•	\$	\$	R	R		

Table / Accumulator & Memory Instructions (Continue	Table 1	7	Accumulator	&	Memory	Instructions	(Continue
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The Condition Code Register notes are listed after Table 10.

Direct Addressing

In direct addressing, the address of the operand is contained in the second byte of the instruction. Direct addressing allows the user to directly address the lowest 256 bytes in the machine i.e., locations zero through 255. Enhanced execution times are achieved by storing data in these locations. In most configurations, it should be a random access memory. These are two-byte instructions.

Extended Addressing

In extended addressing, the address contained in the second byte of the instruction is used as the higher eight-bits of the address of the operand. The third byte of the instruction is used as the lower eight-bits of the address for the operand. This is an absolute address in memory. These are three-byte instructions. Indexed Addressing

In indexed addressing, the address contained in the second byte of the instruction is added to the index register's lowest eight bits in the MCU. The carry is then added to the higher order eight bits of the index register. This result is then used to address memory. The modified address is held in a temporary address register so there is no change to the index register. These are two-byte instructions.

Implied Addressing

In the implied addressing mode the instruction gives the address (i.e., stack pointer, index register, etc.). These are one-byte instructions.

Relative Addressing

In relative addressing, the address contained in the second byte of the instruction is added to the program counter's lowest eight bits plus two. The carry or borrow is then added to the high eight bits. This allows the user to address data within a range of -126 to +129 bytes of the present instruction. These are two-byte instructions.

New Instructions

In addition to the existing 6800 Instruction Set, the following new instructions are incorporated in the HD6801V Microcomputer.

- ABX Adds the 8-bit unsigned accumulator B to the 16-bit X-Register taking into account the possible carry out of the low order byte of the X-Register.
- ADDD Adds the double precision ACCD* to the double precision value M:M+1 and places the results in ACCD.
- ASLD Shifts all bits of ACCD one place to the left. Bit 0 is loaded with zero. The C bit is loaded from the most significant bit of ACCD.
- LOD Loads the contents of double precision memory location into the double accumulator A:B. The condition codes are set according to the data.
- LSRD Shifts all bits of ACCD one place to the right. Bit 15 is loaded with zero. The C bit is loaded from the least significant bit to ACCD.
- MUL Multiplies the 8 bits in accumulator A with the 8 bits in accumulator B to obtain a 16-bit unsigned number in A:B, ACCA contains MSB of result.
- **PSHX** The contents of the index register is pushed onto the stack at the address contained in the stack pointer. The stack pointer is decremented by 2.
- **PULX** The index register is pulled from the stack beginning at the current address contained in the stack pointer +1. The stack pointer is incremented by 2 in total.
- **STD** Stores the contents of double accumulator A:B in memory. The contents of ACCD remain unchanged.
- **SUBD** Subtracts the contents of M:M + 1 from the contents of double accumulator AB and places the result in ACCD.
- **BRN** Never branches. If effect, this instruction can be considered a two byte NOP (No operation) requiring three cycles for execution.
- **CPX** Internal processing modified to permit its use with any conditional branch instruction.

*ACCD is the 16 bit register (A:B) formed by concatenating the A and B accumulators. The A-accumulator is the most significant byte.

		Γ					Ade	dress	ing	Mo	des						Boolean/	C	Cone	ditic Regi	ste	od	e
Pointer Operations	Mnemonic	IM	ME	D.	DI	REC	т	IN	DE	x	EX	TNE	5	IMP	LIE	D	Arithmetic Operation	5	4	3	2	1	0
		OP	~	#	OP	~	#	OP	~	#	OP	~	#	OP	~	#		н	1	Ν	Ζ	۷	С
Compare Index Reg	CPX	80	4	3	9C	5	2	AC	6	2	BC	6	3				X - M : M + 1	•	٠	ŧ	ŧ	\$	\$
Decrement Index Reg	DEX	1		1		1	1							09	3	1	$X - 1 \rightarrow X$	•	•	•	\$	•	•
Decrement Stack Pntr	DES					Γ			{					34	3	1	SP – 1 → SP	٠	٠	•	•	٠	•
Increment Index Reg	INX	T				1			Γ					08	3	1	$X + 1 \rightarrow X$	٠	•	•	\$	•	•
Increment Stack Pntr	INS					1	-							31	3	1	SP + 1 → SP	٠	٠	•	•	٠	•
Load Index Reg	LDX	CE	3	3	DE	4	2	EE	5	2	FE	5	3				$M \rightarrow X_H, (M+1) \rightarrow X_L$	•	•	D	‡	R	•
Load Stack Pntr	LDS	8E	3	3	9E	4	2	AE	5	2	BE	5	3				$M \rightarrow SP_{H}, (M+1) \rightarrow SP_{L}$	•	•	\bigcirc	\$	R	•
Store Index Reg	STX				DF	4	2	EF	5	2	FF	5	3		Γ		$X_H \rightarrow M, X_L \rightarrow (M + 1)$	•	•		\$	R	•
Store Stack Pntr	STS		Γ		9F	4	2	AF	5	2	BF	5	3			T	$SP_H \rightarrow M, SP_L \rightarrow (M+1)$	•	•		\$	R	٠
Index Reg -+ Stack Pntr	TXS						1		Γ	Γ		Γ		35	3	1	X – 1 → SP	•	•	•	•	٠	٠
Stack Pntr → Index Reg	TSX	1							1					30	3	1	SP + 1 → X	•	•	•	•	•	•
Add	ABX					Γ			Γ					3A	3	1	$B + X \rightarrow X$	•	•	٠	٠	٠	٠
Push Data	PSHX								Γ					3C	4	1	$X_L \rightarrow M_{sp}, SP - 1 \rightarrow SP$	•	•	•	٠	٠	•
		1]	1		1			ł		Į				$X_H \rightarrow M_{sp}, SP - 1 \rightarrow SP$			l		1	
Pull Data	PULX					Γ	Γ		Γ				I	38	5	1	$SP + 1 \rightarrow SP, M_{SP} \rightarrow X_H$	•	•	•	•	٠	•
																	$SP + 1 \rightarrow SP, M_{sp} \rightarrow X_L$						

Table 8 Index Register and Stack Manipulation Instructions

The Condition Code Register notes are listed after Table 10.

							A	ddres	sin	, M	odes								6	Con	diti Reg	on i	Cod	le
Operations	Mnemonic	REL	AT	IVE	DI	RE	СТ	11	IDE	x	EX	TN	D	1	імр	LIE	D	Branch Test	5	4	3	2	1	0
		OP	~	#	OP	~	#	OP	~	#	OP	1~		# (OP	~	#		н	1	N	z	V	С
Branch Always	BRA	20	3	2			T					T		Т				None	•	٠	•	٠	•	•
Branch Never	BRN	21	3	2		Γ		Γ				Τ	Τ	T				None	•	٠	•	•	•	•
Branch If Carry Clear	BCC	24	3	2														C = 0	•	•	•	٠	•	•
Branch If Carry Set	BCS	25	3	2			1-	-	1	T	\top	T			~			C = 1	•	•	•	•	•	٠
Branch If = Zero	BEQ	27	3	2			T		T	T			T					Z = 1	•	٠	•	•	•	•
Branch If ≥ Zero	BGE	2C	3	2				T		T		T						N ⊕ V = 0	•	•	٠	•	•	•
Branch If > Zero	BGT	2E	3	2		Γ			T	T	T	Τ						Z + (N (+) V) = 0	•	•	•	•	•	•
Branch If Higher	вні	22	3	2		-		1	T			T		1				C + Z = 0	•	•	•	•	•	•
Branch If < Zero	BLE	2F	3	2			T		T	T		T		T				Z + (N 🕀 V) = 1	•	•	•	•	•	•
Branch If Lower Or Same	BLS	23	3	2			T		T	1		T	T					C + Z = 1	•	•	•	•	•	•
Branch If < Zero	BLT	2D	3	2				1		T				T				N ⊕ V = 1	•	•	•	•	•	•
Branch If Minus	BMI	2B	3	2	1	T	1	1	T	1				1	~			N = 1	•	•	•	•	•	•
Branch If Not Equal Zero	BNE	26	3	2				Ī	T	T	Γ	T		T				Z = 0	•	•	•	•	•	•
Branch If Overflow Clear	BVC	28	3	2														V = 0	•	•	•	•	•	•
Branch If Overflow Set	BVS	29	3	2		Γ	Γ	Γ				Τ						V = 1	•	•	•	•	•	•
Branch If Plus	BPL	2A	3	2	Γ				Т	Ţ							_	N = 0	•	•	•	•	•	•
Branch To Subroutine	BSR	8D	6	2		1	T	T	T	Γ		T			_			1	•	•	•	•	•	•
Jump	JMP	-		<u> </u>		\top	Ť	6E	3	2	7È	3	3	3	-			See Special Operations	•	•	•	•	•	•
Jump To Subroutine	JSR			1	9D	5	2	AD	6	2	BD	6	3	1					•	•	•	•	•	•
No Operation	NOP			Γ			T		T	T	T	T	1	C	01	2	1	Advances Prog. Cntr. Only	•	•	•	•	•	•
Return From Interrupt	RTI			1	1	Γ	T	T	T			T	1	1	3B	10	1	1	- 1		- (8	-	_
Return From Subroutine	RTS						T	1						13	39	5	1	See Special Operations	•	•	•	•	•	•
Software Interrupt	SWI			T		1		1		1		T		13	3F	12	1	• • • •	٠	S	•	•	•	•
Wait for Interrupt	WAI			Γ		Γ	T	T	Τ	T	Τ	T	Τ	3	3E	9	1)	•	9	•	•	•	•

Table 9 Jump and Branch Instructions

Table10 Condition Code Register Manipulation Instructions

		Addre	ssing	Aodes		C	ondit	ion C	ode l	Regis	ter
Operations	Mnemonic	IM	PLIE	D	Boolean Operation	5	4	3	2	1	0
		OP	~	#		н	1	N	Z	V	С
Clear Carry	CLC	00	2	1	0 → C	•	•	•	•	•	R
Clear Interrupt Mask	CLI	0E	2	1	0 → I	•	R	•	•	•	•
Clear Overflow	CLV	0A	2	1	0 → V	•	•	•	•	R	•
Set Carry	SEC	0D	2	1	1 → C	•	•	•	•	•	S
Set Interrupt Mask	SEI	OF	2	1	1 -+ I	•	S	•	•	•	•
Set Overflow	SEV	OB	2	1	1 → V	•	•	•	•	S	•
Accumulator A → CCR	TAP	06	2	1	A→ CCR			- (Ô -	_	
CCR → Accumulator A	ТРА	07	2	1	CCR → A	•	•		•		

Condition Code Register Notes: (Bit set it test is true and cleared otherwise)

- (Bit V)
 (Bit C)
 (Bit C)
 (Bit V)
 (Bit V)
 (Bit V)
 (Bit V)
 (Bit N)
 (All)
 (Bit I) Test: Result = 10000000?
- Test: Result = 00000000?
- Test: Decimal value of most significant BCD Character greater than nine? (Not cleared if previously set) Test: Operand = 10000000 prior to execution? Test: Operand = 0111111 prior to execution? Test: Set equal to result to N @ C after shift has occurred. Test: Result less than zero? (Bit 15 = 1) Load Compliance Code Repitter from Stock (Soc Second Operations)

- Load Condition Code Register from Stack. (See Special Operations) Set when interrupt occurs. If previously set, a Non-Maskable Interrupt is required to exit the wait state. Set according to the contents of Accumulator A.
- () (All) () (Bit C)
- Set equal to result of Bit 7 (AccB)

HD6801V0, HD6801V5---

	ACCX	Imme- diate	Direct	Ex- tended	In- dexed	lm- plied	Re- lative		ACCX	Imme- diate	Direct	Ex- tended	In- dexed	lm- plied	Re- lative
ABA	•	•	•	•	•	2	•	(NX	•	•	•	•	•	3	•
ABX	•	•	•	•	•	3	•	JMP	٠	•	•	3	3	•	•
ADC	•	2	3	4	4	•	•	JSR	•	•	5	6	6	•	•
ADD	•	2	3	4	4	•	•	LDA	•	2	3	4	4	•	•
ADDD	•	4	5	6	6	•	•	LÙD	•	3	4	5	5	•	•
AND	•	2	3	4	4	•	•	LDS	•	3	4	5	5	٠	٠
ASL	2	٠	•	6	6	•	•	LDX	•	3	4	5	5	•	٠
ASLD	•	•	•	•	•	3	•	LSR	2	٠	٠	6	6	٠	٠
ASR	2	٠	•	6	6	٠	٠	LSRD	•	٠	٠	•	•	3	•
BCC	•	٠	•	•	•	•	3	MUL	•	٠	٠	•	•	10	•
BCS	•	•	٠	•	•	•	3	NEG	2	٠	٠	6	6	•	٠
BEQ	•	•	•	•	•	•	3	NOP	•	٠	٠	٠	•	2	٠
BGE	•	•	•	•	•	•	3	ORA	•	2	3	4	4	•	•
BGT	•	•	•	•	•	•	3	PSH	3	٠	٠	•	•	•	•
вні	•	•	•	•	•	•	3	PSHX	•	٠	٠	•	•	4	•
віт	•	2	3	4	4	•	•	PUL	4	٠	٠	•	•	٠	٠
BLE	•	•	•	•	•	•	3	PULX	٠	٠	٠	•	•	5	•
BLS	•	•	•	•	٠	٠	3	ROL	2	•	٠	6	6	•	٠
BLT	•	•	•	•	•	•	3	ROR	2	•	•	6	6	•	٠
BMI	•	•	•	•	•	•	3	RTI	٠	٠	•	•	٠	10	٠
BNE	•	•	•	•	•	•	3	RTS	•	•	•	٠	٠	5	٠
BPL	•	•	•	٠	•	•	3	SBA	•	•	٠	٠	•	2	٠
BRA	•	•	•	٠	•	•	3	SBC	٠	2	3	4	4	٠	٠
BRN	٠	•	•	٠	٠	•	3	SEC	•	•	•	•	•	2	•
BSR	•	•	•	•	٠	•	6	SEI	٠	٠	٠	•	•	2	٠
BVC	•	•	•	٠	•	•	3	SEV	٠	•	•	•	•	2	٠
BVS	•	•	•	٠	٠	•	3	STA	٠	•	3	4	4	•	•
CBA	٠	٠	•	•	٠	2	٠	STD	٠	•	4	5	5	٠	•
CLC	•	•	•	٠	٠	2	•	STS	٠	•	4	5	5	٠	•
CLI	•	•	•	•	٠	2	٠	STX	٠	•	4	5	5	•	•
CLR	2	٠	•	6	6	•	•	SUB	•	2	3	4	4	•	•
CLV	•	•	•	•	•	2	•	SUBD	٠	4	5	6	6	٠	•
CMP	•	2	3	4	4	•	٠	SWI	٠	٠	٠	٠	•	12	٠
COM	2	•	•	6	6	•	•	TAB	•	٠	٠	•	•	2	•
СРХ	•	4	5	6	6	•	•	TAP	٠	•	•	٠	•	2	•
DAA	•	•	•	٠	•	2	•	тва	•	٠	٠	•	•	2	٠
DEC	2	•	•	6	6	•	•	TPA	٠	•	•	•	•	2	•
DES	•	•	•	•	•	3	٠	тзт	2	•	•	6	6	•	٠
DEX	•	•	•	•	•	3	•	TSX	٠	•	٠	٠	•	3	•
EOR	•	2	3	4	4	•	•	TXS	•	٠	٠	•	٠	3	•
INC	2	•	•	6	6	•	٠	WAI	٠	٠	٠	•	٠	9	•
INS	•	•	•	•	•	3	•								

Table 11 Instruction Execution Times in Machine Cycle

• Summary of Cycle by Cycle Operation

Table 12 provides a detailed description of the information present on the Address Bus, Data Bus, and the Read/Write line (R/\overline{W}) during each cycle for each instruction.

This information is useful in comparing actual with expected results during debug of both software and hardware as the control program is executed. The information is categorized in groups according to addressing mode and number of cycles per instruction. (In general, instructions with the same addressing mode and number of cycles execute in the same manner; exceptions are indicated in the table).

Table 12 Cycle by Cycle Operation

Address Mode & Instructions	Cycles	Cycle #	Address Bus	R/W Line	Data Bus
IMMEDIATE					
ADC EOR ADD LDA AND ORA BIT SBC CMP SUB	2	1 2	Op Code Address Op Code Address + 1	1	Op Code Operand Data
LDS LDX	3	1 2 3	Op Code Address Op Code Address + 1 Op Code Address + 2	1 1 1	Op Code Operand Data (High Order Byte) Operand Data (Low Order Byte)
CPX SUBD ADDD	4	1 2 3 4	Op Code Address Op Code Address + 1 Op Code Address + 2 Address Bus FFFF	1 1 1 1	Op Code Operand Data (High Order Byte) Operand Data (Low Order Byte) Low Byte of Restart Vector
DIRECT	_,				
ADC EOR ADD LDA AND ORA BIT SBC CMP SUB	3	1 2 3	Op Code Address Op Code Address + 1 Address of Operand	1 1 1	Op Code Address of Operand Operand Data
STA	3	1 2 3	Op Code Address Op Code Address + 1 Destination Address	1 1 0	Op Code Destination Address Data from Accumulator
LDS LDX LDD	4	1 2 3 4	Op Code Address Op Code Address + 1 Address of Operand Operand Address + 1	1 1 1 1	Op Code Address of Operand Operand Data (High Order Byte) Operand Data (Low Order Byte)
STS STX STD	4	1 2 3 4	Op Code Address Op Code Address + 1 Address of Operand Address of Operand + 1	1 1 0 0	Op Code Address of Operand Register Data (High Order Byte) Register Data (Low Order Byte)
CPX SUBD ADDD	5	1 2 3 4 5	Op Code Address Op Code Address + 1 Operand Address Operand Address + 1 Address Bus FFFF	1 1 1 1	Op Code Address of Operand Operand Data (High Order Byte) Operand Data (Low Order Byte) Low Byte of Restart Vector
JSR	5	1 2 3 4 5	Op Code Address Op Code Address + 1 Subroutine Address Stack Pointer Stack Pointer + 1	1 1 1 0 0	Op Code Irrelevant Data First Subroutine Op Code Return Address (Low Order Byte) Return Address (High Order Byte)

(Continued)

Address Mode & Instructions	Cycles	Cycle #	Address Bus	R/W Line	Data Bus
NDEXED					
JMP	3	1	Op Code Address	1	Op Code
		2	Op Code Address + 1	1	Offset
		3	Address Bus FFFF	1	Low Byte of Restart Vector
ADC EOR	4	1	Op Code Address	1	Op Code
ADD LDA		2	Op Code Address + 1	1	Offset
AND ORA		3	Address Bus FFFF	1	Low Byte of Restart Vector
BIT SBC		4	Index Register Plus Offset	1	Operand Data
CMP SUB					
STA	4	1	Op Code Address	1	Op Code
		2	Op Code Address + 1	1	Offset
		3	Address Bus FFFF	1	Low Byte of Restart Vector
		4	Index Register Plus Offset	0	Operand Data
LDS	5	1	Op Code Address	1	Op Code
LDX	-	2	Op Code Address + 1	1	Offset
LDD		3	Address Bus FFFF	1	Low Byte of Restart Vector
		4	Index Register Plus Offset	1	Operand Data (High Order Byte)
		5	Index Register Plus Offset + 1	1	Operand Data (Low Order Byte)
STS	5	1	Op Code Address	1	Op Code
STX	-	2	Op Code Address + 1	1	Offset
STD	1	3	Address Bus FFFF	1	Low Byte of Restart Vector
		4	Index Register Plus Offset	0	Operand Data (High Order Byte)
		5	Index Register Plus Offset + 1	0	Operand Data (Low Order Byte)
ASL LSR	6	1	Op Code Address	1	Op Code
ASR NEG		2	Op Code Address + 1	1	Offset
CLR ROL		3	Address Bus FFFF	1	Low Byte of Restart Vector
COM ROR		4	Index Register Plus Offset	1	Current Operand Data
DEC TST*		5	Address Bus FFFF	1	Low Byte of Restart Vector
INC		6	Index Register Plus Offset	0	New Operand Data
CPX	6	1	Op Code Address	1	Op Code
SUBD		2	Op Code Address + 1	1	Offset
ADDD		3	Address Bus FFFF	1	Low Byte of Restart Vector
		4	Index Register + Offset	1	Operand Data (High Order Byte)
		5	Index Register + Offset + 1	1	Operand Data (Low Order Byte)
		6	Address Bus FFFF	1.	Low Byte of Restart Vector
JSR	6	1	Op Code Address	1	Op Code
		2	Op Code Address + 1	t	Offset
		3	Address Bus FFFF	1	Low Byte of Restart Vector
		4	Index Register + Offset	1	First Subroutine Op Code
		5	Stack Pointer	0	Return Address (Low Order Byte)
		6	Stack Pointer ~ 1	0	Return Address (High Order Byte)

Table 12 Cycle by Cycle Operation (Continued)

* In the TST instruction, R/W line of the sixth cycle is "1" level, and AB=FFFF, DB=Low Byte of Reset Vector.

(Continued)

1

Address Mode & Instructions	Cycles	Cycle #	Address Bus	R/W Line	Data Bus
EXTENDED					······································
JMP	3	1 2 3	Op Code Address Op Code Address + 1 Op Code Address + 2	1 1 1	Op Code Jump Address (High Order Byte) Jump Address (Low Order Byte)
ADC EOR ADD LDA AND ORA BIT SBC CMP SUB	4	1 2 3 4	Op Code Address Op Code Address + 1 Op Code Address + 2 Address of Operand	1 1 1 1	Op Code Address of Operand Address of Operand (Low Order Byte) Operand Data
STA A STA B	4	1 2 3 4	Op Code Address Op Code Address + 1 Op Code Address + 2 Operand Destination Address	1 1 1 0	Op Code Destination Address (High Order Byte) Destination Address (Low Order Byte) Data from Accumulator
LDS LDX LDD	5	1 2 3 4 5	Op Code Address Op Code Address + 1 Op Code Address + 2 Address of Operand Address of Operand + 1	1 1 1 1 1	Op Code Address of Operand (High Order Byte) Address of Operand (Low Order Byte) Operand Data (High Order Byte) Operand Data (Low Order Byte)
STS STX STD	5	1 2 3 4 5	Op Code Address Op Code Address + 1 Op Code Address + 2 Address of Operand Address of Operand + 1	1 1 1 0 0	Op Code Address of Operand (High Order Byte) Address of Operand (Low Order Byte) Operand Data (High Order Byte) Operand Data (Low Order Byte)
ASL LSR ASR NEG CLR ROL COM ROR DEC TST* INC	6	1 2 3 4 5 6	Op Code Address Op Code Address + 1 Op Code Address + 2 Address of Operand Address Bus FFFF Address of Operand	1 1 1 1 1 0	Op Code Address of Operand (High Order Byte) Address of Operand (Low Order Byte) Current Operand Data Low Byte of Restart Vector New Operand Data
CPX SUBD ADDD	6	1 2 3 4 5 6	Op Code Address Op Code Address + 1 Op Code Address + 2 Operand Address Operand Address + 1 Address Bus FFFF	1 1 1 1 1 1	Op Code Operand Address (High Order Byte) Operand Address (Low Order Byte) Operand Data (High Order Byte) Operand Data (Low Order Byte) Low Byte of Restart Vector
JSR	6	1 2 3 4 5 6	Op Code Address Op Code Address + 1 Op Code Address + 2 Subroutine Starting Address Stack Pointer Stack Pointer - 1	1 1 1 0 0	Op Code Address of Subroutine (High Order Byte) Address of Subroutine (Low Order Byte) Op Code of Next Instruction Return Address (Low Order Byte) Address of Operand (High Order Byte)

Table 12 Cycle by Cycle Operation (Continued)

* In the TST instruction, R/W line of the sixth cycle is "1" level, and AB = FFFF, DB = Low Byte of Reset Vector.

(Continued)

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Address Mode & Instructions	Cycles	Cycle #	Address Bus	R/W Line	Data Bus
IMPLIED					
ABA DAA SEC ASL DEC SEI ASR INC SEV CBA LSR TAB CLC NEG TAP CLI NOP TBA CLR ROL TPA CLV ROR TST COM SBA	2	1 2	Op Code Address Op Code Address + 1	1	Op Code Op Code of Next Instruction
ABX	3	1 2 3	Op Code Address Op Code Address + 1 Address Bus FFFF	1 1 1	Op Code Irrelevant Data Low Byte of Restart Vector
ASLD LSRD	3	1 2 3	Op Code Address Op Code Address + 1 Address Bus FFFF	1 1 1	Op Code Irrelevant Data Low Byte of Restart Vector
DES INS	3	1 2 3	Op Code Address Op Code Address + 1 Previous Register Contents	1 1 1	Op Code Op Code of Next Instruction Irrelevant Data
INX DEX	3	1 2 3	Op Code Address Op Code Address + 1 Address Bus FFFF	1 1 1	Op Code Op Code of Next Instruction Low Byte of Restart Vector
PSHA PSHB	3	1 2 3	Op Code Address Op Code Address + 1 Stack Pointer	1 1 0	Op Code Op Code of Next Instruction Accumulator Data
TSX	3	1 2 3	Op Code Address Op Code Address + 1 Stack Pointer	1 1 1	Op Code Op Code of Next Instruction Irrelevant Data
TXS	3	1 2 3	Op Code Address Op Code Address + 1 Address Bus FFFF	1 1 1	Op Code Op Code of Next Instruction Low Byte of Restart Vector
PULA PULB	4	1 2 3 4	Op Code Address Op Code Address + 1 Stack Pointer Stack Pointer + 1	1 1 1 1	Op Code Op Code of Next Instruction Irrelevant Data
PSHX	4	1 2 3 4	Op Code Address Op Code Address + 1 Stack Pointer Stack Pointer - 1	1 1 0 0	Op Code Irrelevant Data Index Register (Low Order Byte) Index Register (High Order Byte)
PULX	5	1 2 3 4 5	Op Code Address Op Code Address + 1 Stack Pointer Stack Pointer + 1 Stack Pointer +2	1 1 1 1 1	Op Code Irrelevant Data Irrelevant Data Index Register (High Order Byte) Index Register (Low Order Byte)
RTS	5	1 2 3 4 5	Op Code Address Op Code Address + 1 Stack Pointer Stack Pointer + 1 Stack Pointer + 2	1 1 1 1	Op Code Irrelevant Data Irrelevant Data Address of Next Instruction (High Order Byte) Address of Next Instruction (Low Order Byte)
WAI**	9	1 2 3 4	Op Code Address Cp Code Address + 1 Stack Pointer Stack Pointer - 1	1 1 0 0	Op Code Op Code of Next Instruction Return Address (Low Order Byte) Return Address (High Order Byte)

Table 12 Cycle by Cycle Operation (Continued)

(Continued)

Address Mode & Instructions	Cycles	Cycle #	Address Bus	R/W Line	Data Bus
WAI**		5	Stack Pointer – 2	0	Index Register (Low Order Byte)
		6	Stack Pointer – 3	0	Index Register (High Order Byte)
		7	Stack Pointer – 4	0	Contents of Accumulator A
		8	Stack Pointer – 5	0	Contents of Accumulator B
		9	Stack Pointer – 6	0	Contents of Cond. Code Register
MUL	10	1	Op Code Address	1	Op Code
		2	Op Code Address + 1	1	Irrelevant Data
		3	Address Bus FFFF	1	Low Byte of Restart Vector
		4	Address Bus FFFF	1	Low Byte of Restart Vector
		5	Address Bus FFFF	1	Low Byte of Restart Vector
	1	6	Address Bus FFFF	1	Low Byte of Restart Vector
		7	Address Bus FFFF	1	Low Byte of Restart Vector
		8	Address Bus FFFF	1	Low Byte of Restart Vector
		9	Address Bus FFFF	1	Low Byte of Restart Vector
		10	Address Bus FFFF	1	Low Byte of Restart Vector
RTI	10	1	Op Code Address	1	Op Code
		2	Op Code Address + 1	1	Irrelevant Data
		3	Stack Pointer	1	Irrelevant Data
		4	Stack Pointer + 1	1	Contents of Cond. Code Reg.
					from Stack
		5	Stack Pointer + 2	1	Contents of Accumulator B
					from Stack
		6	Stack Pointer + 3	1	Contents of Accumulator A
		7	Stack Pointer + 4	1	Index Begister from Stack
		'	Stack Fornier - 4	•	(High Order Byte)
		8	Stack Pointer + 5	1	Index Register from Stack
	1				(Low Order Byte)
		9	Stack Pointer + 6	1	Next Instruction Address from
		_			Stack (High Order Byte)
	1	10	Stack Pointer + 7	1	Next Instruction Address from
					Stack (Low Order Byte)
SWI	12	1	Op Code Address	1	Op Code
		2	Op Code Address + 1	1	Irrelevant Data
	1	3	Stack Pointer	0	Return Address (Low Order Byte)
		4	Stack Pointer – 1	0	Return Address
		1			(High Order Byte)
		5	Stack Pointer – 2	0	Index Register (Low Order Byte)
		6	Stack Pointer – 3	0	Index Register (High Order Byte)
	1	7	Stack Pointer – 4	0	Contents of Accumulator A
		8	Stack Pointer - 5	0	Contents of Accumulator B
		9	Stack Pointer – 6	0	Contents of Cond. Code Register
		10	Stack Pointer – 7	1	Irrelevant Data
		11	Vector Address FFFA (Hex)	1	Address of Subroutine
					(High Order Byte)
		12	Vector Address FFFB (Hex)	1	Address of Subroutine
					(Low Order Byte)

Table 12	Cycle by	Cycle	Operation	(Continued)

* While the MPU is in the "Wait" state, its bus state will appear as a series of MPU reads of an address which is seven locations less than the original contents of the Stack Pointer. Contrary to the HD6800, none of the ports are driven to the high impedance state by a WAI instruction.

(Continued)

Address Mode & Instruction	Cycles	Cycle #	Address Bus	R/W Line	Data Bus
RELATIVE					
BCC BHT BNE	3	1	Op Code Address	1	Op Code
BCS BLE BPL	1	2	Op Code Address + 1	1	Branch Offset
BEQ BLS BRA	1	3	Address Bus FFFF	1	Low Byte of Restart Vector
BGE BLT BVC		1			
BGT BMT BVS					
BRN					
BSR	6	1	Op Code Address	1	Op Code
		2	Op Code Address + 1	1	Branch Offset
		3	Address Bus FFFF	1	Low Byte of Restart Vector
	1	4	Subroutine Starting Address	1	Op Code of Next Instruction
	ľ	5	Stack Pointer	0	Return Address (Low Order Byte
	1	6	Stack Pointer – 1	0	Return Address (High Order Byte

Table 12 Cycle by Cycle Operation (Continued)

• Summary of Undefined Instruction Operations

The HD6801V has 36 undefined instructions. When these are carried out, the contents of Register and Memory in MPU change at random.

When the op codes (4E, 5E) are used to execute, the MPU continues to increase the program counter and it will not stop until the Reset signal enters. These op codes are used to test the LSI.

Table 13 Op codes Map

	HD6801V MICROCOMPUTER INSTRUCTIONS																	
				100	400			ACCA or SP				ACCB or X				1		
CODE			ALL ALL	IND	EXT	IMM	DIR	IND	EXT	ІММ	DIR	IND	EXT	1				
	н	0000	0001	0010	0011	0100	0101	0110	0111	1000	1001	1010	1011	1100	1101	1110	1111]
	-	0	1	2	3	4	5	6	7	8	9	A	B	С	D	E	F	
0000	0		SBA	BRA	TSX	NEG				SUB								
0001	1	NOP	CBA	BRN	INS					СМР								
0010	2		/	BHI	PULA (+1)					SBC								2
0011	3		/	BLS	PULB (+1)	COM				•	SUB	D (+2)		•	1	3		
0100	4	LSRD (+1)	/	BCC	DES	LSR				AND								4
0101	5	ASLD (+1)	/	BCS	TXS					BIT								5
0110	6	TAP	TAB	BNE	PSHA	ROR				LDA								6
0111	7	TPA	TBA	BEQ	PSHB	ASR			/	STA STA							7	
1000	8	INX (+1)	/	BVC	PULX (+2)	ASL				EOR								8
1001	9	DEX (+1)	DAA	BVS	RTS (+2)	ROL				ADC								9
1010	A	CLV	/	BPL	ABX	DEC				ORA								A
1011	В	SEV	ABA	BMI	RTI (+7)					ADD								
1100	С	CLC	/	BGE	PSHX (+1)	INC			•	CP	X (+2)		•	LD	D (+1)		C	
1101	D	SEC	/	BLT	MUL (+7)		т	БТ		BSR JSR (+2)			• (+1)) STD (+1)		1)	D	
1110	E	CLI	/	BGT	WAI (+6)	- •	•	JMP	(-3)	• LDS (+1)		•	LDX (+1)			E		
1111	F	SEI	/	BLE	SWI (+9)	CLP		R		· (+1)	STS (+1)		* (+í)	STX (+1)		1)	F	
BYTE/CYCLE		1/2	1/2	2/3	1/3	1/2	1/2	2/6	3/6	2/2	2/3	2/4	3/4	2/2	2/3	2/4	3/4	

[NOTES] 1) Undefined Op codes are marked with _____.

2) () indicate that the number in parenthesis must be added to the cycle count for that instruction,

3) The instructions shown below are all 3 bytes and are marked with "*".

Immediate addressing mode of SUBD, CPX, LDS, ADDD, LDD and LDX instructions, and undefined op codes (8F, CD, CF).

4) The Op codes (4E, 5E) are 1 byte/∞ cycles instructions, and are marked with "**".



Figure 24 Interrupt Flowchart



Figure 25 HD6801V MCU Single-Chip Dual Processor Configuration



Figure 26 HD6801V MCU Expanded Non-Multiplexed Mode



Figure 27 HD6801V MCU Expanded Multiplexed Mode