DS8925

DS8925 LocalTalk Dual Driver/Triple Receiver



Literature Number: SNOS696

December 1998

National Semiconductor

DS8925 LocalTalk[™] Dual Driver/Triple Receiver

General Description

The DS8925 is a dual driver/triple receiver device optimized to provide a single chip solution for a LocalTalk Interface. The device provides one differential TIA/EIA-422 driver, one TIA/EIA-423 single ended driver, one TIA/EIA-422 receiver and two TIA/EIA-423 receivers, all in a surface mount 16 pin package. This device is electrically similar to the 26LS30 and 26LS32 devices.

The drivers feature $\pm 10V$ common mode range, and the differential driver provides TRI-STATEable outputs. The receivers offer ± 200 mV thresholds over the $\pm 10V$ common mode range.

Connection Diagram



See NS Package Number M16A

■ Single chip solution for LocalTalk port

■ Wide common mode range: ±10V

■ ±200 mV receiver sensitivity

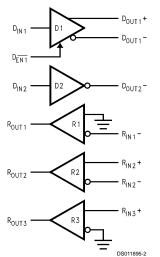
Available in SOIC packaging

Two driver/three receivers per package

70 mV typical receiver input hysteresis

Features

Functional Diagram



DS8925 LocalTalk Dual Driver/Triple Receive



TRI-STATE[®] is a registered trademark of National Semiconductor Corporation. LocalTalk[™] is a trademark of Apple Computer Incorporated.

Absolute Maximum Ratings (Note 1)

•

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

| Supply Voltage (V _{CC}) | +7V |
|---|-------|
| Supply Voltage (V _{EE}) | -7V |
| Enable Input Voltage (D _{EN1}) | +7V |
| Driver Input Voltage (D _{IN}) | +7V |
| Driver Output Voltage (Power Off: D _{OUT}) | ±15V |
| Receiver Input Voltage (V _{ID} : R _{IN} + - R _{IN} -) | ±25V |
| Receiver Input Voltage (V _{CM} : (R _{IN} + + R _{IN} -)/2) | ±25V |
| Receiver Input Voltage (Input to GND: R _{IN}) | ±25V |
| Receiver Output Voltage (R _{OUT}) | +5.5V |
| Maximum Package Power Dissipation @+25°C M Package | 1.33W |

| Derate M Package 10.6 mW/°C above +25°C | |
|---|-----------------|
| Storage Temperature Range | –65°C to +150°C |
| Lead Temperature Range (Soldering, 4 Sec.) | +260°C |
| This Device Does Not Meet 2000V ESD Rating | (Note 7) |

Recommended Operating Conditions

| | Min | Тур | Max | Units |
|-----------------------------------|-------|------|-------|-------|
| Supply Voltage (V _{CC}) | +4.75 | +5.0 | +5.25 | V |
| Supply Voltage (V _{EE}) | -4.75 | -5.0 | -5.25 | V |
| Operating Free Air | | | | |
| Temperature (T _A) | 0 | 25 | 70 | °C |
| | | | | |

Electrical Characteristics (Notes 2, 3) Over Supply Voltage and Operating Temperature ranges, unless otherwise specified

| V _{OD} (V _O (V _{OD1} (V _{SS} | TIAL DRIVER CHARACTERISTIC Output Differential Voltage Output Voltage Output Differential Voltage | $R_{L} = \infty \text{ or } R_{L} = 3$ $R_{L} = \infty \text{ or } R_{L} = 3$ | | | ±7 | ±9.0 | ±10 | V |
|--|--|---|---|---------------------|-----|------|-------|----|
| V _O (V _{OD1} (V _{SS} | Output Voltage | $R_L = \infty$ or $R_L = 3$ | | _ | ±7 | ±9.0 | ±10 | V |
| V _{OD1} | 1 0 | | 9 40 | | | | | |
| V _{SS} | Output Differential Voltage | | $R_L = \infty$ or $R_L = 3.9 \text{ k}\Omega$ | | | ±4.5 | ±5.25 | V |
| | | $R_L = 100\Omega$, Figure 1 | | | 4.0 | 6.4 | | V |
| ΔV_{OD1} | V _{OD1} - V _{OD1*} | | | | 8.0 | 12.8 | | V |
| | Output Unbalance | | | | | 0.02 | 0.4 | V |
| Vos | Offset Voltage | | | D _{OUT} +, | | 0 | 3 | V |
| ΔV _{OS} | Offset Unbalance |] | | D _{OUT} - | | 0.05 | 0.4 | V |
| V _{OD2} | Output Differential Voltage | RL = 140Ω, <i>Figure 1</i> | | | 6.0 | 7.0 | | V |
| I _{OZD} . | TRI-STATE [®] Leakage Current | $V_{\rm CC} = 5.25 V$ | V _O = +10V | | | 2 | 150 | μA |
| | | V _{EE} = -5.25V | V _O = +6V | | | 1 | 100 | μA |
| | | | $V_{O} = -6V$ | | | -1 | -100 | μA |
| | | | $V_{O} = -10V$ | | | -2 | -150 | μA |
| SINGLE EN | NDED DRIVER CHARACTERISTI | cs | | | | | | |
| Vo | Output Voltage (No Load) | $R_L = \infty$ or $R_L = 3$ | .9 kΩ, <i>Figure 2</i> | | 4 | 4.4 | 6 | V |
| V _T | Output Voltage | $R_L = 3 k\Omega$, Figure | 2 | | 3.7 | 4.3 | | V |
| | | $R_{L} = 450\Omega$, Figure | e 2 | D _{OUT} - | 3.6 | 4.1 | | V |
| ΔV_T | Output Unbalance | | | | | 0.02 | 0.4 | V |
| DRIVER CH | HARACTERISTICS | r. | | | | | | |
| V _{CM} | Common Mode Range | Power Off, or D1 | Disabled | | ±10 | | | V |
| I _{OSD} : | Short Circuit Current | V _O = 0V, Sourcing Current | | | | -80 | -150 | mA |
| | | V _O = 0V, Sinking Current | | 1_ | | 80 | 150 | mA |
| I _{OXD} | Power-Off Leakage Current | $V_0 = +10V$ | | D _{OUT} +, | | 2 | 150 | μA |
| | $(V_{CC} = V_{EE} = 0V)$ | V _O = +6V | | D _{OUT} - | | 1 | 100 | μA |
| | | $V_{\rm O} = -6V$ | | | | -1 | -100 | μA |
| | | $V_{0} = -10V$ | | | | -2 | -150 | μA |

| $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | ECEIVE | Parameter | Conditions | Pin | Min | Тур | Max | Units |
|---|---|--|--|----------|---------------------------------------|---|--------------------|------|-----|-------|-------|
| | | $ \begin{array}{ c c c c c c } \hline Hysteresis & V_{CM} = 0V & & & & & & & & & & & & & & & & & & $ | $ \begin{array}{ c c c c c c } \hline V_{CM} & Hysteresis & V_{CM} = 0V & & & & & & & & & & & & & & & & & & $ | | | 1 | | | | | |
| | | $ \begin{array}{ c c c c c c } \hline Hysteresis & V_{CM} = 0V & & & & & & & & & & & & & & & & & & $ | | тн | Input Threshold | $-7V \le V_{CM} \le +7V$ | | -200 | ±35 | +200 | mV |
| $ \begin{array}{ c c c c c c c c c } \hline R_{IN} & Input Resistance & -10V \leq V_{CM} \leq \pm 10V & & & & & & & & & & & & & & & & & & &$ | $\begin{array}{ c c c c c c c c c c c c c c c c c c c$ | $ \frac{1}{NN} \frac{1}{N} \ln \mu t \operatorname{Resistance} -10V \le V_{CM} \le \pm 10V \\ N \frac{1}{N} \frac{1}{N} \ln \mu t \operatorname{Current} (Other Input = 0V, \\ Power On, or V_{CC} = V_{EE} = 0V) \\ \hline V_{IN} = \pm 3V \\ \hline V_{IN} = \pm 2VO mV \\ \hline I_{OH} = \pm 400 \ \mu A, \\ V_{IN} = \pm 200 \ mV \\ \hline I_{OH} = \pm 400 \ \mu A, \\ V_{IN} = \pm 200 \ mV \\ \hline I_{OH} = \pm 400 \ \mu A, \\ V_{IN} = \pm 200 \ mV \\ \hline I_{OH} = \pm 400 \ \mu A, \\ V_{IN} = \pm 200 \ mV \\ \hline I_{OH} = \pm 400 \ \mu A, \\ V_{IN} = \pm 200 \ mV \\ \hline I_{OH} = \pm 400 \ \mu A, \\ V_{O} = 0V \\ \hline I_{OH} = \pm 400 \ \mu A, \\ V_{O} = 0V \\ \hline I_{OH} = \pm 400 \ \mu A, \\ V_{O} = 0V \\ \hline I_{OH} = \pm 400 \ \mu A, \\ V_{O} = 0V \\ \hline I_{OH} = \pm 400 \ \mu A, \\ V_{O} = 0V \\ \hline I_{OH} = \pm 400 \ \mu A, \\ V_{O} = 0V \\ \hline I_{OH} = \pm 400 \ \mu A, \\ I_{OH$ | $\begin{array}{c c c c c c c c c c c c c c c c c c c $ | НҮ | Hysteresis | V _{CM} = 0V | | | 70 | | mV |
| $ \begin{array}{ c c c c c c c c c c } & & & & & & & & & & & & & & & & & & &$ | $ \begin{array}{ c c c c c c c c } & & & & & & & & & & & & & & & & & & &$ | | $ \begin{array}{ c c c c c c } & \mbox{Input Current (Other Input = 0V, \\ Power On, or V_{CC} = V_{EE} = 0V) & \hline V_{IN} = +10V & V_{IN} = +3V & & & & \\ \hline V_{IN} = +3V & & & & & \\ \hline V_{IN} = -3V & & & & & \\ \hline V_{IN} = -10V & & & & & & \\ \hline V_{IN} = -10V & & & & & & \\ \hline V_{IN} = -10V & & & & & & \\ \hline V_{IN} = -10V & & & & & & \\ \hline V_{IN} = -10V & & & & & & \\ \hline V_{IN} = -10V & & & & & & \\ \hline V_{IN} = -10V & & & & & & \\ \hline V_{IN} = -10V & & & & & & \\ \hline V_{IN} = -1200 \ MV & & & & & & \\ \hline V_{IN} = +200 \ MV & & & & & & \\ \hline V_{IN} = +200 \ MV & & & & & \\ \hline V_{IN} = -400 \ \mu A, \ V_{IN} = -200 \ MV & & & & & \\ \hline V_{OL} & Low \ Level \ Output \ Voltage & & & & \\ \hline V_{OL} & Low \ Level \ Output \ Voltage & & & & \\ \hline V_{OL} & Low \ Level \ Input \ Voltage & & & & \\ \hline V_{IN} = -400 \ \mu A, \ V_{IN} = -200 \ MV & & & & \\ \hline \hline MH & High \ Level \ Input \ Voltage & & & & \\ \hline HH & High \ Level \ Input \ Voltage & & & & \\ \hline HH & High \ Level \ Input \ Voltage & & & & \\ \hline HH & High \ Level \ Input \ Current & & \\ \hline V_{IN} = 2.4V & & & & \\ \hline MIL & Low \ Level \ Input \ Current & & \\ \hline V_{IN} = 0.4V & & & & \\ \hline MIL & Low \ Level \ Input \ Current & & \\ \hline V_{IN} = 0.4V & & & \\ \hline MIL & Low \ Level \ Input \ Current & & \\ \hline V_{IN} = 0.4V & & & \\ \hline \hline MIL & High \ Level \ Input \ Current & & \\ \hline V_{IN} = -12 \ mA & & & \\ \hline \hline MIL & & \\ \hline \ CC & Power \ Supply \ Current & & \\ \hline No \ Load & & \hline \hline V_{CC} & & & \\ \hline \end{array}$ | | Input Resistance | $-10V \le V_{CM} \le +10V$ | | 6.0 | 8.5 | | kΩ |
| $\begin{array}{ c c c c c c }\hline & & & & & & & & & & & & & & & & & & &$ | $\begin{tabular}{ c c c c c c } \hline V_{IN} &= -3V$ & V_{IN} &= -10V$ & V_{IN} &= -10V$ & V_{IN} &= -10V$ & V_{IN} &= -10V & V_{IN} &= -10V & V_{IN} &= -3.25 & n & $-3.25 & n & V_{OH} & V_{OH} & V_{IN} &= -400 μA, V_{IN} &= 0PEN & V_{IN} &= 2.7 & $4.2 & V_{IN} &= -400 μA, V_{IN} &= 0PEN & V_{O} &= 0V &$ | $\begin{array}{ c c c c c c c }\hline & & & & & & & & & & & & & & & & & & &$ | $\begin{tabular}{ c c c c c c c } \hline & & & & & & & & & & & & & & & & & & $ | | | V _{IN} = +10V | R _{IN} +, | | | 3.25 | mA |
| $\begin{tabular}{ c c c c c c c c c c } \hline V_{IN} &= -10V & & & & & & & & & & & & & & & & & & &$ | $\begin{tabular}{ c c c c c c c } \hline V_{1N} = -10V & V_{1N} = -10V & I &$ | $ \begin{array}{ c c c c c c } \hline V_{IN} = -10V & & & & & & & & & & & & & & & & & & &$ | $\begin{tabular}{ c c c c c c c c c c } \hline & V_{1N} = -10V & & & & & & & & & & & & & & & & & & &$ | | Power On, or $V_{CC} = V_{EE} = 0V$) | $V_{IN} = +3V$ | R _{IN} - | 0 | | 1.50 | mA |
| $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | $ \begin{array}{c c c c c c c c c } \hline Input Balance Test & R_{S} = 500\Omega \ (R2 \ only) & & & & & & & & & & & & & & & & & & &$ | | | $V_{IN} = -3V$ | | 0 | | -1.50 | mA |
| | $ \begin{array}{c c} \mbox{I_{OH}} & \mbox{High Level Output Voltage} & \mbox{I_{OH}} = -400 \ \mu A, \\ \ V_{IN} = +200 \ mV \\ \hline \ I_{OH} = -400 \ \mu A, \\ \ V_{IN} = +200 \ mV \\ \hline \ I_{OH} = -400 \ \mu A, \\ \ V_{IN} = -400 \ \mu A, \\ \ V_{IN} = 0 \ mV \\ \hline \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$ | $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | | | | $V_{IN} = -10V$ | | | | -3.25 | mA |
| $ \begin{array}{ c c c c c c c c c c c c c c c c c c c$ | $ \begin{array}{ c c c c c c c c c } \hline V_{IN} = +200 \text{ mV} \\ \hline I_{OH} = -400 \ \mu\text{A}, \ V_{IN} = OPEN \\ \hline I_{OL} = 8.0 \ \text{mA}, \ V_{IN} = -200 \ \text{mV} \\ \hline \\ \hline \\ D_{SR} & Short Circuit Current & V_O = 0V \\ \hline \\ \hline \\ PEVICE CHARACTERISTICS \\ \hline \\ \hline \\ H & High Level Input Voltage & \\ \hline \\ H & High Level Input Voltage & \\ \hline \\ H & High Level Input Voltage & \\ \hline \\ H & High Level Input Current & V_{IN} = 2.4V \\ \hline \\ L & Low Level Input Current & V_{IN} = 0.4V \\ \hline \\ \hline \\ C_L & Input Clamp Voltage & \\ \hline \\ \hline \\ C_L & Power Supply Current & No Load & V_{CC} & 400 \ 65 \ \text{m} \\ \hline \\ $ | $ \begin{array}{ c c c c c c c c c } \hline V_{IN} = +200 \text{ mV} & & & & & & & & & & & & & & & & & & &$ | $\begin{tabular}{ c c c c c c c c c c } \hline V_{\rm IN} &= +200 \mbox{ mV} & & & & & & & & & & & & & & & & & & &$ | IB | Input Balance Test | $R_{S} = 500\Omega$ (R2 only) | | | | ±400 | mV |
| $\begin{tabular}{ c c c c c c c c c c c c c c c c c c c$ | $\begin{array}{ c c c c c c c c c c c c c c c c c c c$ | $\begin{array}{ c c c c c c c c c c c c c c c c c c c$ | $\begin{tabular}{ c c c c c c c c c c c } \hline I_{OH} &= -400 \ \mu\text{A}, \ V_{IN} &= OPEN \\ \hline I_{OL} &= Low \ Level \ Output \ Voltage & I_{OL} &= 8.0 \ \text{mA}, \ V_{IN} &= -200 \ \text{mV} & \hline & & 1.5 & -34 \\ \hline D_{DSR} & Short \ Circuit \ Current & V_O &= 0V & \hline & & -15 & -34 \\ \hline D_{EVICE \ CHARACTERISTICS & & & & \\ \hline V_{IL} & Low \ Level \ Input \ Voltage & & & & \\ H & High \ Level \ Input \ Voltage & & & & \\ \hline L & Low \ Level \ Input \ Current & V_{IN} &= 2.4V & & & \\ \hline L & Low \ Level \ Input \ Current & V_{IN} &= 0.4V & & & \\ \hline & & 1 & & \\ \hline D_{IN}, & & & \\ \hline D_{IN}, & & & $ | он | High Level Output Voltage | I _{OH} = -400 μA, | | 2.7 | 4.2 | | V |
| $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | $ \begin{array}{ c c c c c c } \hline C_{OL} & Low Level Output Voltage & I_{OL} = 8.0 \text{ mA}, V_{IN} = -200 \text{ mV} \\ \hline \hline D_{SR} & Short Circuit Current & V_O = 0V \\ \hline \hline -15 & -34 & -85 & n \\ \hline \hline PEVICE CHARACTERISTICS \\ \hline \hline T_{IH} & High Level Input Voltage & \\ \hline T_{IL} & Low Level Input Voltage & \\ \hline T_{IL} & Low Level Input Current & V_{IN} = 2.4V \\ \hline L & Low Level Input Current & V_{IN} = 0.4V \\ \hline \hline C_{L} & Input Clamp Voltage & I_{IN} = -12 \text{ mA} \\ \hline C_{CC} & Power Supply Current & No Load & V_{CC} & 40 & 65 & n \\ \hline \end{array} $ | $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | $ \begin{array}{ c c c c c c } \hline C_{OL} & Low Level Output Voltage & I_{OL} = 8.0 \text{ mA}, V_{IN} = -200 \text{ mV} & \hline & 0.3 & \hline \\ \hline & 0.3 & -15 & -34 & \hline \\ \hline & -15 & -34 & \hline \\ \hline \\ \hline & -15 & -34 & \hline \\ \hline$ | | | V _{IN} = +200 mV | | | | | |
| $\begin{array}{c c c c c c c c c c c c c c c c c c c $ | $\begin{array}{c c c c c c c c c c c c c c c c c c c $ | $\begin{array}{c c c c c c c c c c c c c c c c c c c $ | $\begin{array}{c c c c c c c c c c c c c c c c c c c $ | | | I _{OH} = -400 μA, V _{IN} = OPEN | R _{OUT} | 2.7 | 4.2 | | V |
| EVICE CHARACTERISTICS IH High Level Input Voltage U_{IN} | EVICE CHARACTERISTICS II- High Level Input Voltage I_{II-} Low Level Input Voltage I_{II-} IL Low Level Input Voltage $V_{IN} = 2.4V$ D_{IN} , I_{II-} | EVICE CHARACTERISTICS IH High Level Input Voltage U_{IN} | EVICE CHARACTERISTICS IH High Level Input Voltage Image: Colspan="2">Image: Colspan="2" Colspa="2" Colspa="2" Colspa="2" Colspan="2" Colspan="2" Colspan="2" C | OL | Low Level Output Voltage | I _{OL} = 8.0 mA, V _{IN} = -200 mV | | | 0.3 | 0.5 | V |
| IHHigh Level Input Voltage2.0VILLow Level Input Voltage $V_{IN} = 2.4V$ D_{IN} D_{IN} High Level Input Current $V_{IN} = 2.4V$ D_{IN} D_{IN} Low Level Input Current $V_{IN} = 0.4V$ -10 -200 CLInput Clamp Voltage $I_{IN} = -12$ mA -1.5 V CCPower Supply CurrentNo Load V_{CC} 4065 | IHHigh Level Input Voltage2.0ILLow Level Input Voltage0.8High Level Input Current $V_{IN} = 2.4V$ D_{IN} , D_{EN1} Low Level Input Current $V_{IN} = 0.4V$ -10Low Level Input Clamp Voltage $I_{IN} = -12$ mA-10CLPower Supply CurrentNo Load V_{CC} 40 | IH High Level Input Voltage 2.0 V IL Low Level Input Voltage 0.8 V High Level Input Current $V_{IN} = 2.4V$ D_{IN} , D_{IN} , Low Level Input Current $V_{IN} = 0.4V$ 1 40 $\mu \mu$ Low Level Input Current $V_{IN} = 0.4V$ -10 -200 $\mu \mu$ CL Input Clamp Voltage $I_{IN} = -12$ mA V_{CC} 40 65 m_{IN} | $\begin{array}{c c c c c c c c c c c c c c c c c c c $ | SR | Short Circuit Current | $V_{O} = 0V$ | | -15 | -34 | -85 | mA |
| ILLow Level Input Voltage0.8High Level Input Current $V_{IN} = 2.4V$ Low Level Input Current $V_{IN} = 0.4V$ Low Level Input Clamp Voltage $I_{IN} = -12 \text{ mA}$ CLInput Clamp Voltage $I_{IN} = -12 \text{ mA}$ CCPower Supply CurrentNo Load | $ \begin{array}{ c c c c c c c c c c c c c c c c c c c$ | Image: | $\begin{array}{c c c c c c c c c c c c c c c c c c c $ | EVICE | CHARACTERISTICS | | | | | | |
| Image: Decision of the sector of the sect | Image: Description of the text in the text in | Image: Decision of the sector of the sect | Image: Description of the sector of the s | н | High Level Input Voltage | | | 2.0 | | | V |
| High Level Input Current $V_{IN} = 2.4V$ D_{IN} | High Level Input Current $V_{IN} = 2.4V$ D_{IN} D_{EN1} 14040Low Level Input Current $V_{IN} = 0.4V$ -10 -200 40CLInput Clamp Voltage $I_{IN} = -12$ mA V_{CC} 4065m | High Level Input Current $V_{IN} = 2.4V$ D_{IN} D_{EN1} 140 $\mu\mu$ Low Level Input Current $V_{IN} = 0.4V$ -10 -200 $\mu\mu$ CLInput Clamp Voltage $I_{IN} = -12$ mA -1.5 V Power Supply CurrentNo Load V_{CC} 4065mm | High Level Input Current $V_{IN} = 2.4V$ D_{IN} D_{EN1} 1Low Level Input Current $V_{IN} = 0.4V$ -10 -10 CLInput Clamp Voltage $I_{IN} = -12 \text{ mA}$ V_{CC} 40 | | Low Level Input Voltage | | 1_ | | | 0.8 | V |
| Low Level Input Current $V_{IN} = 0.4V$ -10 -200 μh CLInput Clamp Voltage $I_{IN} = -12$ mA -1.5 V Power Supply CurrentNo Load V_{CC} 4065m. | Low Level Input Current $V_{IN} = 0.4V$ D_{EN1} -10 -200 μ CLInput Clamp Voltage $I_{IN} = -12$ mA -1.5 -1.5 -1.5 Power Supply CurrentNo Load V_{CC} 4065m | Low Level Input Current $V_{IN} = 0.4V$ -10 -200 μA CLInput Clamp Voltage $I_{IN} = -12$ mA -1.5 V Power Supply CurrentNo Load V_{CC} 4065max | $\begin{tabular}{ c c c c c c c c c c c c c c c c c c c$ | | High Level Input Current | V _{IN} = 2.4V | | | 1 | 40 | μA |
| CL Input Clamp Voltage I _{IN} = -12 mA -1.5 V C Power Supply Current No Load V _{CC} 40 65 m. | CLInput Clamp Voltage $I_{IN} = -12 \text{ mA}$ -1.5CPower Supply CurrentNo Load V_{CC} 4065n | CL Input Clamp Voltage I _{IN} = -12 mA -1.5 V C Power Supply Current No Load V _{CC} 40 65 m/r | CL Input Clamp Voltage I _{IN} = -12 mA V C Power Supply Current No Load V _{CC} 40 | | Low Level Input Current | | D _{EN1} | | -10 | -200 | μA |
| C Power Supply Current No Load V _{CC} 40 65 m. | C Power Supply Current No Load V _{CC} 40 65 n | C Power Supply Current No Load V _{CC} 40 65 m/ | c Power Supply Current No Load V _{CC} 40 | | Input Clamp Voltage | $I_{IN} = -12 \text{ mA}$ | | | | -1.5 | V |
| | | | | | Power Supply Current | | V _{cc} | | 40 | 65 | mA |
| | | | | | 1 | D1 Enabled or Disabled | | | -5 | -15 | mA |
| | | | | <u>E</u> | | | *EE | | 0 | 10 | |
| | | | | | | | | | | | |
| | | | | | | | | | | | |
| | | | | | | | | | | | |
| | | | | | | | | | | | |
| | | | | | | | | | | | |
| | | | | | | | | | | | |
| | | | | | | | | | | | |
| | | | | | | | | | | | |
| | | | | | | | | | | | |
| | | | | | | | | | | | |
| | | | | | | | | | | | |
| | | | | | | | | | | | |
| | | | | | | | | | | | |

· •

| Symbol | Parameter | Conditions | Min | Тур | Max | Units |
|-------------------|--|--|-----|-----|-----|-------|
| DIFFERE | NTIAL DRIVER CHARACTERISTICS | · | | | | |
| t _{PHLD} | Differential Propagation Delay High to Low | $R_{L} = 100\Omega, C_{L} = 500 \text{ pF},$ | 70 | 134 | 350 | ns |
| t _{PLHD} | Differential Propagation Delay Low to High | (Figures 3, 4) | 70 | 141 | 350 | ns |
| t _{SKD} | Differential Skew t _{PHLD} - t _{PLHD} | $C_1 = C_2 = 50 \text{ pF}$ | | 7 | 50 | ns |
| t _r | Rise Time | | 50 | 140 | 300 | ns |
| t _f | Fall Time | | 50 | 140 | 300 | ns |
| t _{PHZ} | Disable Time High to Z | $R_{L} = 100\Omega, C_{L} = 500 \text{ pF}$ | | 300 | 600 | ns |
| t _{PLZ} | Disable Time Low to Z | (Figures 7, 8) | | 300 | 600 | ns |
| t _{PZH} | Enable Time Z to High | | | 160 | 350 | ns |
| t _{PZL} | Enable Time Z to Low | | | 160 | 350 | ns |
| SINGLE E | NDED DRIVER CHARACTERISTICS | | | | | |
| t _{PHL} | Propagation Delay High to Low | $R_{L} = 450\Omega, C_{L} = 500 \text{ pF}$ | 70 | 120 | 350 | ns |
| t _{PLH} | Propagation Delay Low to High | (Figures 5, 6) | 70 | 150 | 350 | ns |
| t _{sk} | Skew, t _{PHL} – t _{PLH} | | | 30 | 70 | ns |
| t _r | Rise Time | | 50 | 100 | 300 | ns |
| t _f | Fall Time | | 20 | 50 | 300 | ns |
| RECEIVE | R CHARACTERISTICS | | | | | |
| t _{PHL} | Propagation Delay High to Low | C _L = 15 pF | 10 | 33 | 75 | ns |
| t _{PLH} | Propagation Delay Low to High | (Figures 9, 10) | 10 | 30 | 75 | ns |
| t _{sk} | Skew, t _{PHL} – t _{PLH} | | | 3 | 20 | ns |

Note 1: Absolute Maximum Ratings are those values beyond which the safety of the device cannot be guaranteed. They are not meant to imply that the devices should be operated at these limits. The table of Electrical Characteristics specifies conditions of device operation.

Note 2: Current into device pins is defined as positive. Current out of device pins is defined as negative. All voltages are referenced to ground except V_{OD}, V_{OD1}, V_{OD2}, and V_{SS}.

Note 3: All typicals are given for: V_{CC} = +5.0V, V_{EE} = -5.0V, T_A = +25°C unless otherwise specified.

Truth Tables

Driver (D1)

.

| Inp | Inputs | | puts |
|------------------|------------------|---------------------|---------------------|
| D _{EN1} | D _{IN1} | D _{OUT1} + | D _{OUT1} - |
| н | Х | Z | Z |
| L | L | L | н |
| L | н | Н | L |

Driver (D2)

| Input | Output |
|------------------|---------------------|
| D _{IN2} | D _{OUT2} - |
| L | Н |
| Н | L |

L = Logic High Level (Steady State) L = Logic Low Level (Steady State) X = Irrelevant (Any Input) Z = Off State (TRI-STATE, High Impedance) [†]OPEN = Non-Terminated

Receiver (1)

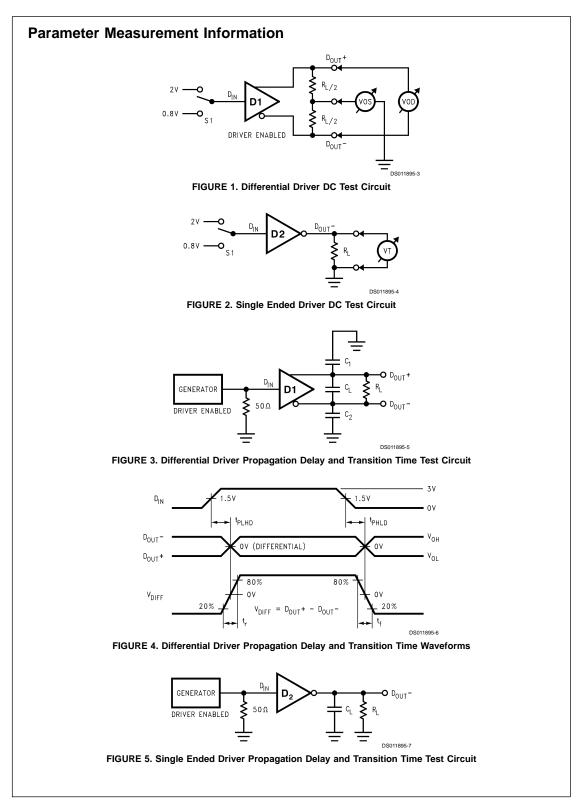
| Input | Output |
|--------------------|-------------------|
| R _{IN1} - | R _{out1} |
| ≤–200 mV | Н |
| ≥+200 mV | L |
| OPEN [†] | Н |

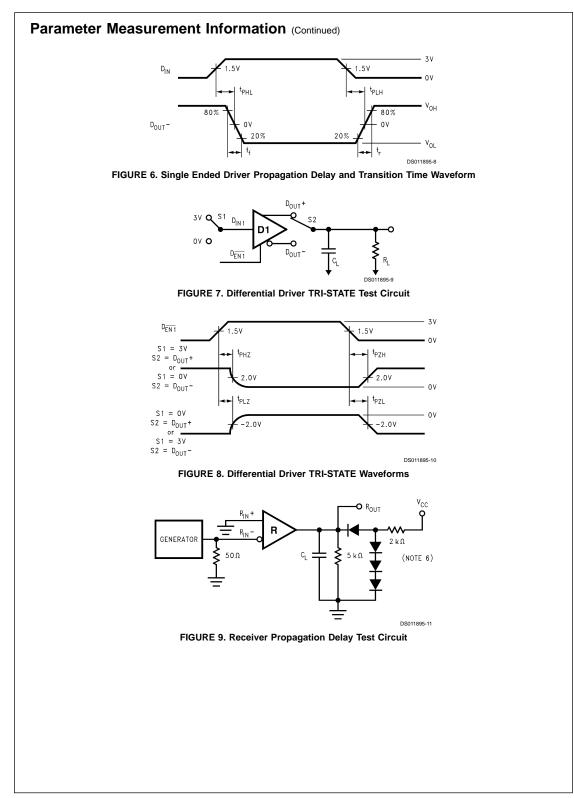
Receiver (2)

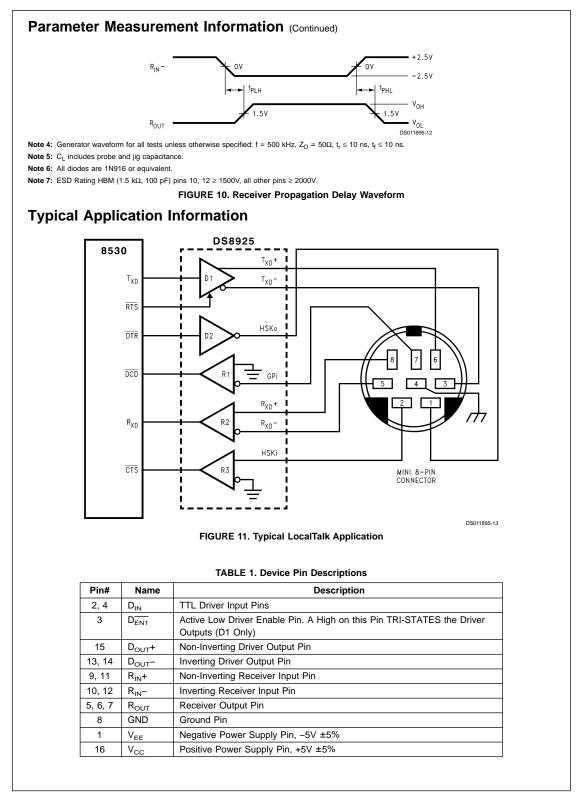
| Inputs | Output |
|---|-------------------|
| R _{IN2} + – R _{IN2} – | R _{OUT2} |
| ≤–200 mV | L |
| ≥+200 mV | Н |
| OPEN [†] | Н |

Receiver (3)

| Input | Output |
|--------------------|-------------------|
| R _{IN3} + | R _{OUT3} |
| ≤–200 mV | L |
| ≥+200 mV | Н |
| OPEN [†] | Н |







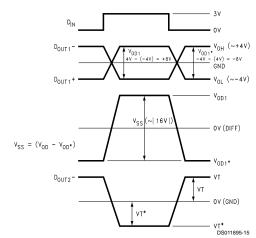
Typical Application Information (Continued)

DRIVER OUTPUT WAVEFORMS

The driver configuration on the DS8925 is unique among TIA/EIA-422 devices in that it utilizes $-5V V_{EE}$ supply. A typical TIA/EIA-422 driver uses +5V only and generates signal swings of approximately 0V–5V.

By utilizing V_{EE}, the differential driver is able to generate a much larger differential signal. The typical output voltage is about |4| V, which gives |8| V differentially, thus providing a much greater noise margin than +5V drivers. See *Figure 12*. The receiver therefore has a range of +8V to -8V or V_{SS} of 16V (V_{SS} = V_{OD}-V_{OD}-).

Each side of the differential driver operates similar to a TIA/ EIA-423 driver. The output voltages are slightly different due to the loading: the differential driver has differential termination, the single-ended driver is terminated with a resistor to ground.



Note 8: Star (*) represents the opposite input condition for a parameter. FIGURE 12. Typical Driver Output Waveforms

UNUSED PINS

Unused driver outputs should be left open. If tied to either ground or supply, the driver may enter an I_{OS} state and consume excessive power. Unused driver inputs should not be

left floating as this may lead to unwanted switching which may affect $I_{\rm CC},$ particularly the frequency component. Unused driver inputs should be tied to ground.

Receiver outputs will be in a HIGH state when inputs are open; therefore, outputs should not be tied to ground. It is best to leave unused receiver outputs floating.

RECEIVER FAILSAFE

All three receivers on this device incorporate open input failsafe protection. The differential receiver output will be in a HIGH state when inputs are open, but will be indetermined if inputs are shorted together. Unused differential inputs should be left floating.

Both single-ended receivers (inverting and non-inverting) are biased internally so that an open input will result in a HIGH output. Therefore, these inputs should not be shorted to ground when unused.

BYPASS CAPACITORS

Bypass capacitors are recommended for both V_{CC} and V_{EE}. Noise induced on the supply lines can affect the signal quality of the output; V_{CC} affects the V_{OH} and V_{EE} affects the V_{OL}. Capacitors help reduce the effect on signal quality. A value of 0.1 μ F is typically used.

Since this is a power device, it is recommended to use a bypass capacitor for each supply and for each device. Sharing a bypass capacitor between other devices may not be sufficient.

TERMINATION

On a multi-point transmission line which is electrically long, it is advisable to terminate the line at both ends with its characteristic impedance to prevent signal reflection and its associated noise/crosstalk.

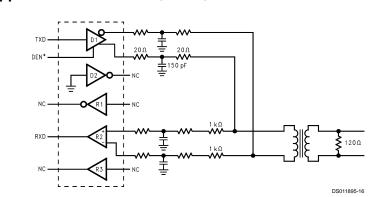
A 100 Ω termination resistor is commonly specified by TIA/ EIA-422 for differential signals. The DS8925 is also specified using 140 Ω termination which will result in less power associated with the driver output. The additional resistance is typical of applications requiring EMI filtering on the driver outputs.

TWO-WIRE LocalTalk

The DS8925 is a single chip solution for a LocalTalk interface. A typical application is shown in *Figure 11*.

An alternative implementation of LocalTalk is to only use two wires to communicate. The differential data lines can be transformer-coupled on to a twisted pair medium. See *Figure 13*. The handshake function must then be accomplished in software.

Typical Application Information (Continued)



Note 9: Star (*) represents the opposite input condition for a parameter.



SINGLE +5V SUPPLY

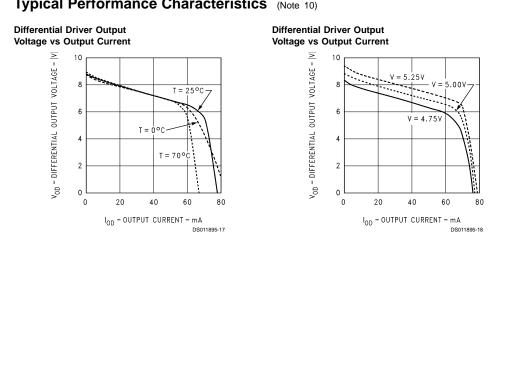
The DS8925 is derived from the DS3691/92 which could be configured using a single +5V supply (V_{EE} = 0V). This device is not specified for this type of operation. However, the device will not be damaged if operated using a single +5V supplv.

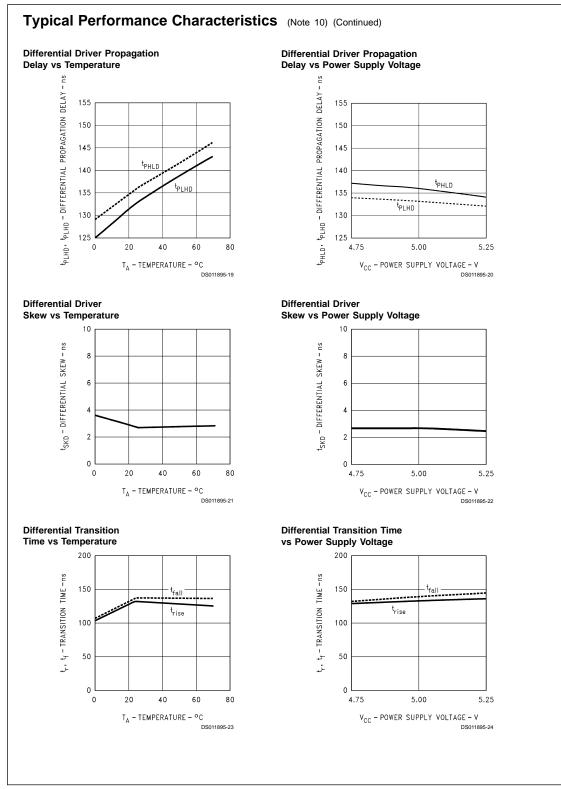
Both drivers require the -5V supply in order to meet the output voltage levels specified. When the device switches from a positive voltage to the complimentary state, it is pulled toward the V_{EE} level. If that level is 0V, then the complimentary

state will be near 0V instead of $\mathrm{V}_{\mathrm{EE}}.$ Thus, the output would switch from about 4V to 0V, instead of 4V to -4V. The differential driver will meet TIA/EIA-422, but with a reduced noise margin. The single-ended driver will not meet TIA/EIA-423 without the -5V supply.

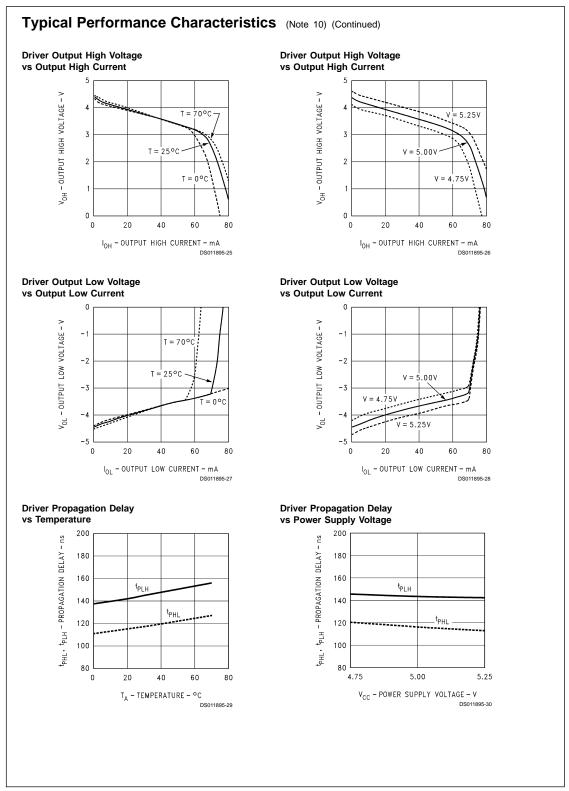
The receivers will be functional but may suffer parametrically. The inverting receiver is referenced to V_{EE} therefore, the threshold may shift slightly. The inputs can still vary over the ±10V common mode range.

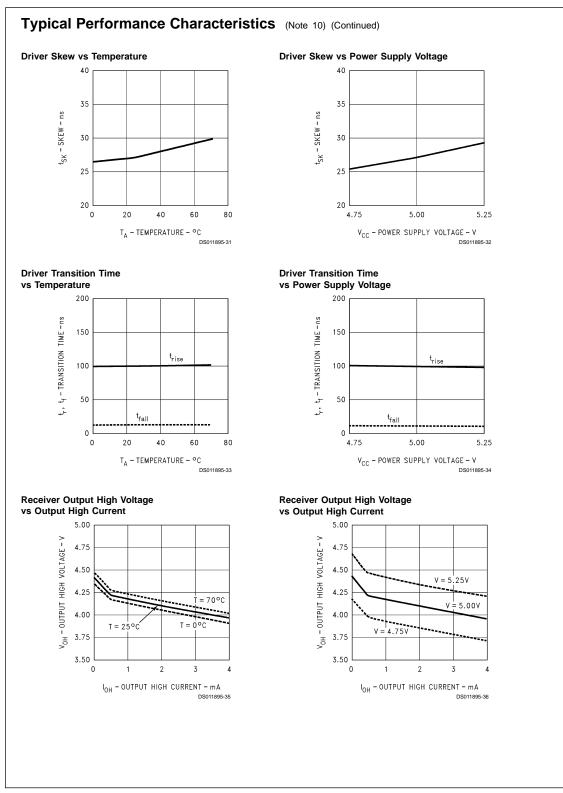
Typical Performance Characteristics (Note 10)



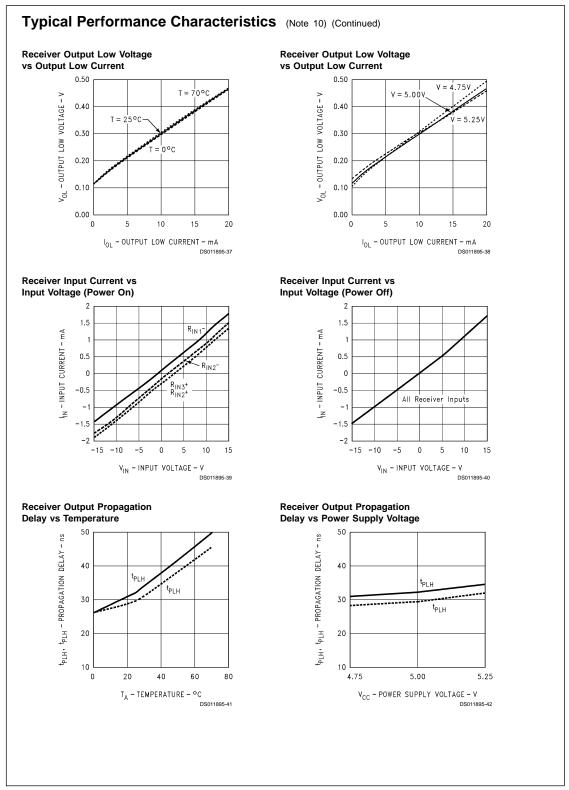


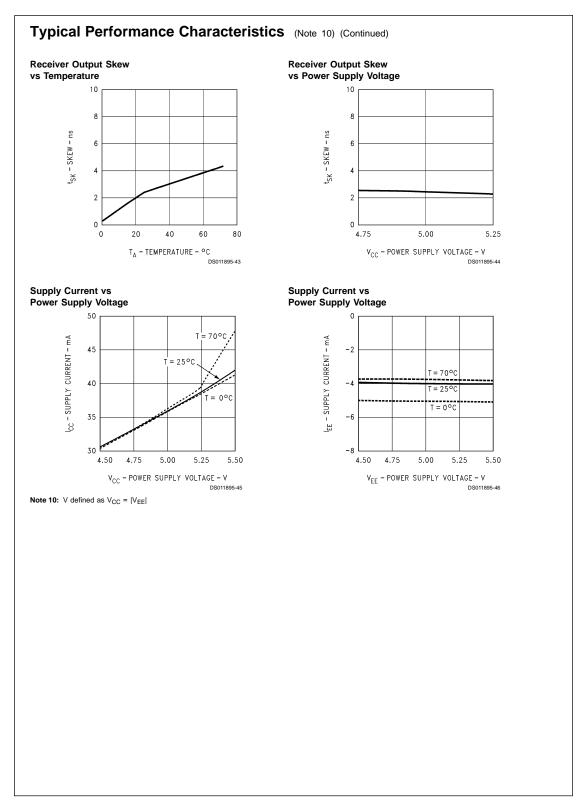
10



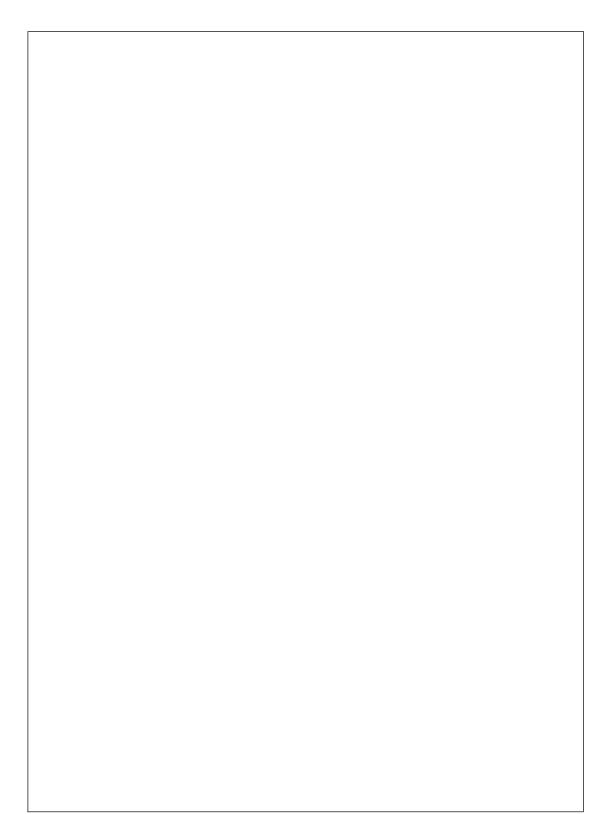


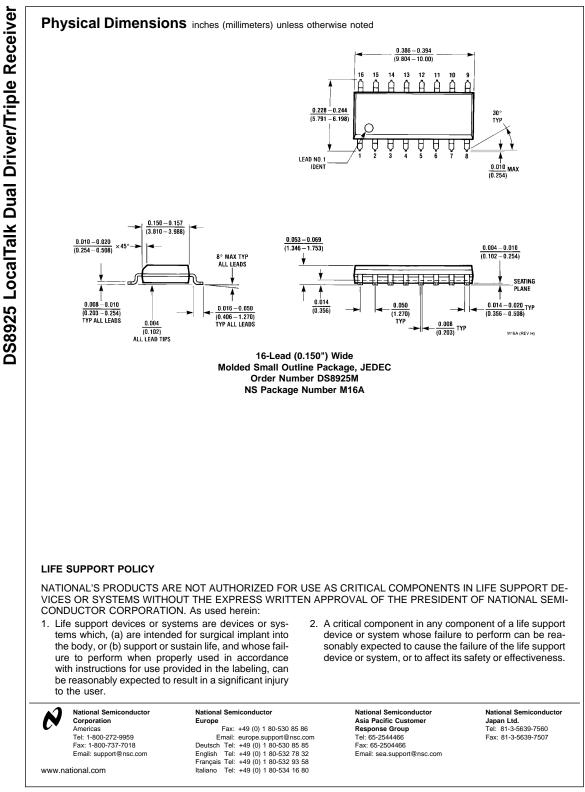
12





www.national.com





National does not assume any responsibility for use of any circuitry described, no circuit patent licenses are implied and National reserves the right at any time without notice to change said circuitry and specifications.

IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All products are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its hardware products to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by government requirements, testing of all parameters of each product is not necessarily performed.

TI assumes no liability for applications assistance or customer product design. Customers are responsible for their products and applications using TI components. To minimize the risks associated with customer products and applications, customers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any TI patent right, copyright, mask work right, or other TI intellectual property right relating to any combination, machine, or process in which TI products or services are used. Information published by TI regarding third-party products or services does not constitute a license from TI to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. Reproduction of this information with alteration is an unfair and deceptive business practice. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

TI products are not authorized for use in safety-critical applications (such as life support) where a failure of the TI product would reasonably be expected to cause severe personal injury or death, unless officers of the parties have executed an agreement specifically governing such use. Buyers represent that they have all necessary expertise in the safety and regulatory ramifications of their applications, and acknowledge and agree that they are solely responsible for all legal, regulatory and safety-related requirements concerning their products and any use of TI products in such safety-critical applications, notwithstanding any applications-related information or support that may be provided by TI. Further, Buyers must fully indemnify TI and its representatives against any damages arising out of the use of TI products in such safety-critical applications.

TI products are neither designed nor intended for use in military/aerospace applications or environments unless the TI products are specifically designated by TI as military-grade or "enhanced plastic." Only products designated by TI as military-grade meet military specifications. Buyers acknowledge and agree that any such use of TI products which TI has not designated as military-grade is solely at the Buyer's risk, and that they are solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI products are neither designed nor intended for use in automotive applications or environments unless the specific TI products are designated by TI as compliant with ISO/TS 16949 requirements. Buyers acknowledge and agree that, if they use any non-designated products in automotive applications, TI will not be responsible for any failure to meet such requirements.

Following are URLs where you can obtain information on other Texas Instruments products and application solutions:

| Products | | Applications | |
|------------------------|---------------------------------|-------------------------------|-----------------------------------|
| Audio | www.ti.com/audio | Communications and Telecom | www.ti.com/communications |
| Amplifiers | amplifier.ti.com | Computers and Peripherals | www.ti.com/computers |
| Data Converters | dataconverter.ti.com | Consumer Electronics | www.ti.com/consumer-apps |
| DLP® Products | www.dlp.com | Energy and Lighting | www.ti.com/energy |
| DSP | dsp.ti.com | Industrial | www.ti.com/industrial |
| Clocks and Timers | www.ti.com/clocks | Medical | www.ti.com/medical |
| Interface | interface.ti.com | Security | www.ti.com/security |
| Logic | logic.ti.com | Space, Avionics and Defense | www.ti.com/space-avionics-defense |
| Power Mgmt | power.ti.com | Transportation and Automotive | www.ti.com/automotive |
| Microcontrollers | microcontroller.ti.com | Video and Imaging | www.ti.com/video |
| RFID | www.ti-rfid.com | | |
| OMAP Mobile Processors | www.ti.com/omap | | |
| Wireless Connectivity | www.ti.com/wirelessconnectivity | | |
| | | u Hama Dawa | a O a Al a a m |

TI E2E Community Home Page

e2e.ti.com

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2011, Texas Instruments Incorporated